

Protocols for EH-WSNs

Internet of Things, a.a. 2019/2020

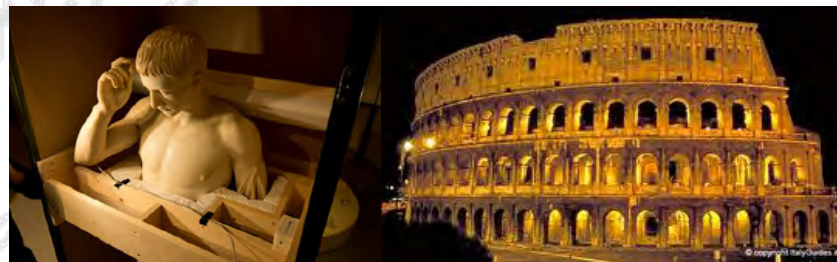
Un. of Rome "La Sapienza"

Chiara Petrioli[†]

[†] *Department of Computer Science – University of Rome "Sapienza" – Italy*



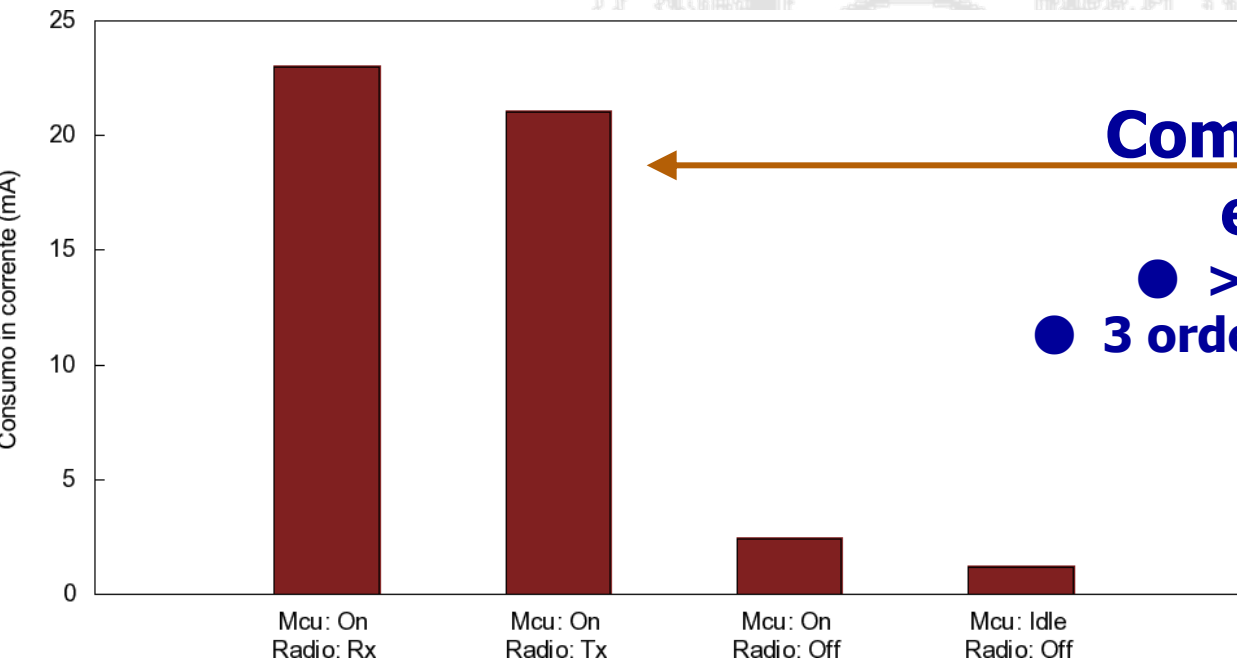
Structural health monitoring



Cultural Heritage



- In many applications (e.g., SHM) the network is required to run for **decades**
- Nodes are powered by batteries
 - **Limited lifetime** (a few days on 2xAA batteries if always on)

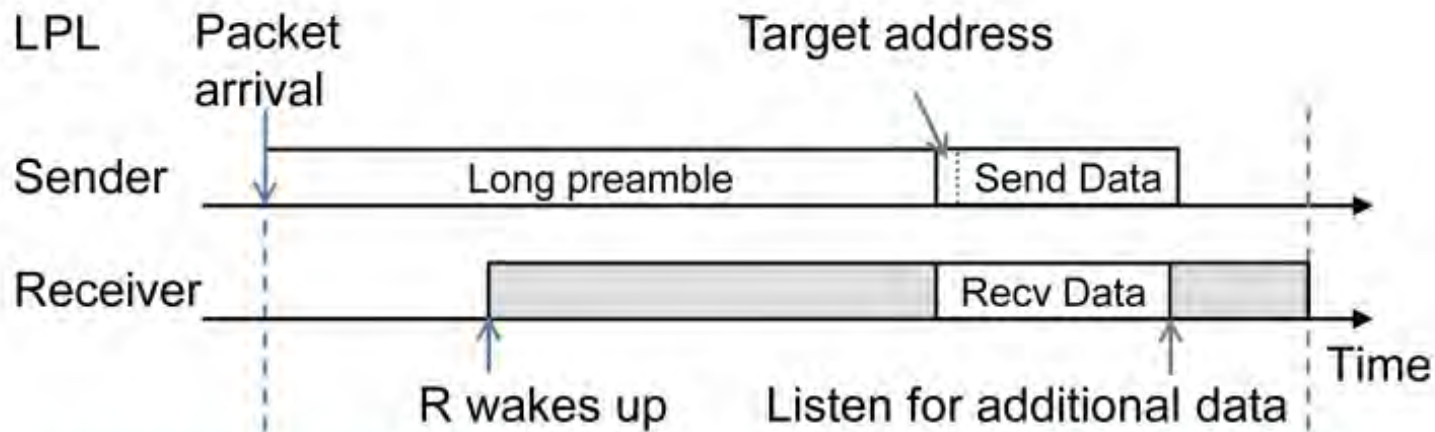
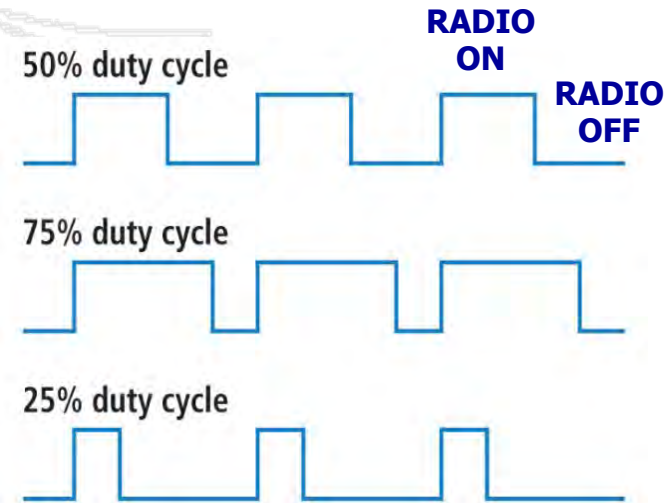


**Communication is
expensive!**

- **>10x w.r.t. MCU on**
- **3 orders of magnitude w.r.t. sleep**

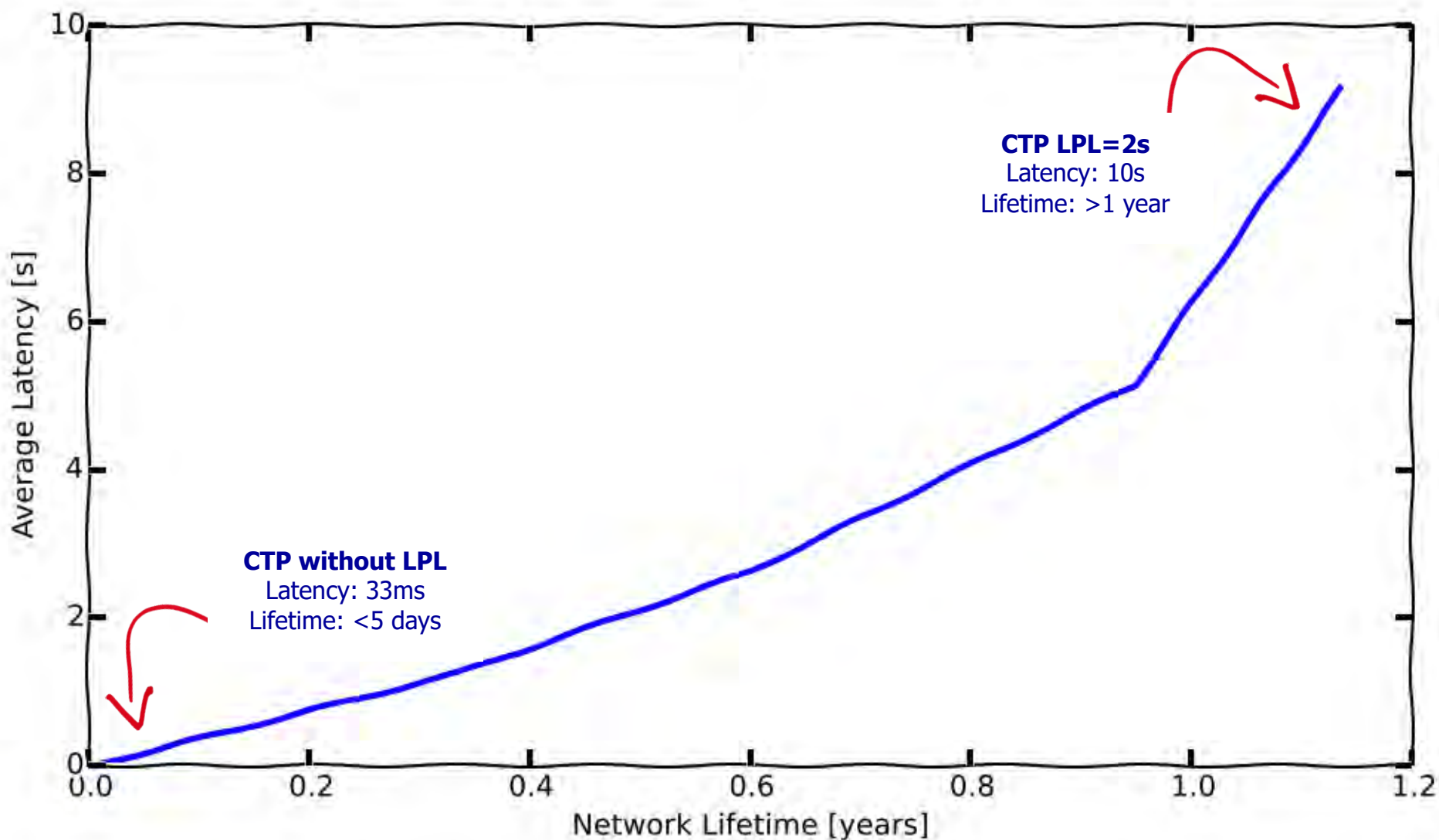


- Periodically cycle the radio between ON/OFF states
 - OFF = save energy, but no communication
 - ON = high energy, but data can be transmitted and received



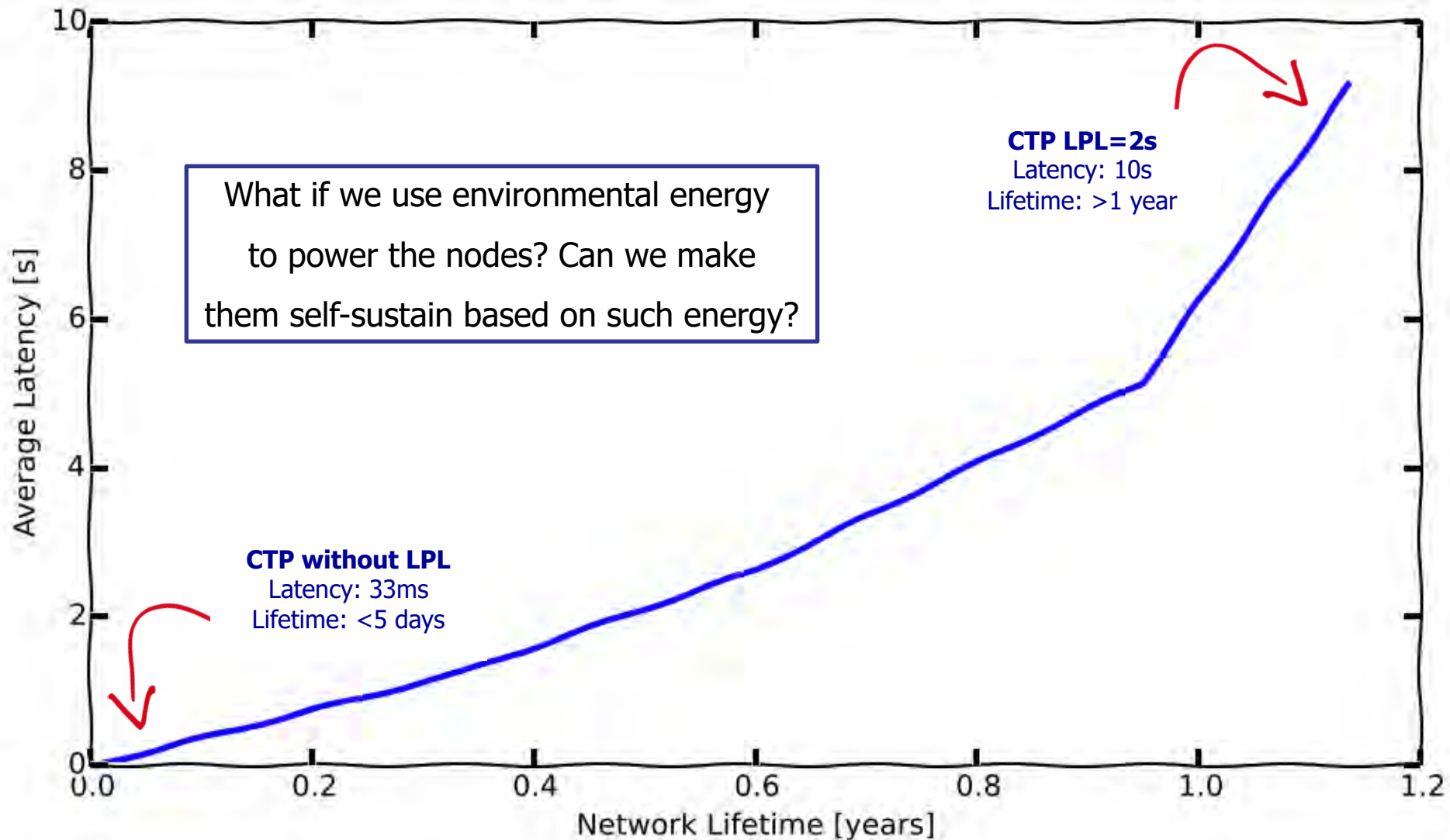


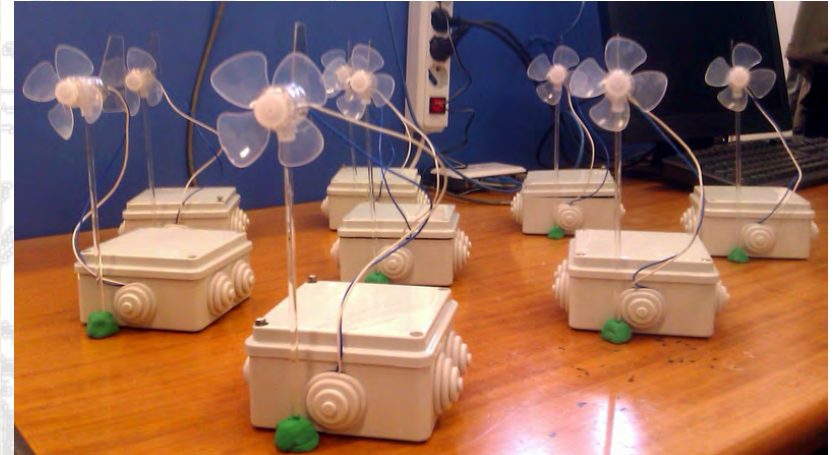
Latency vs. Energy Trade-off



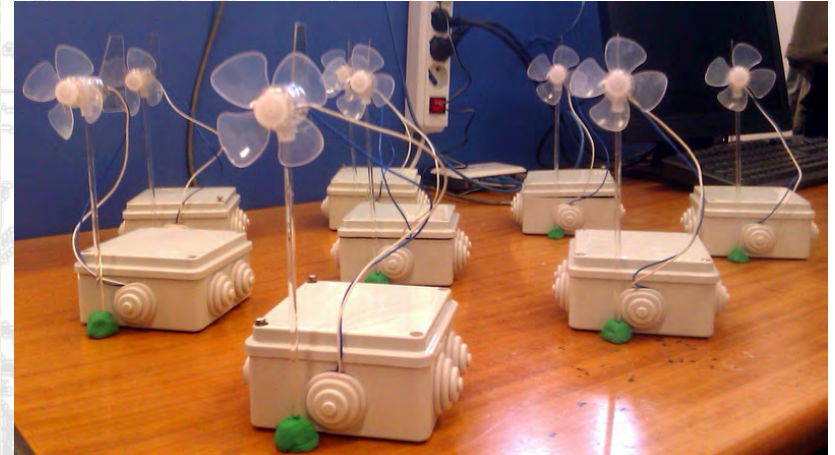


Latency vs. Energy Trade-off





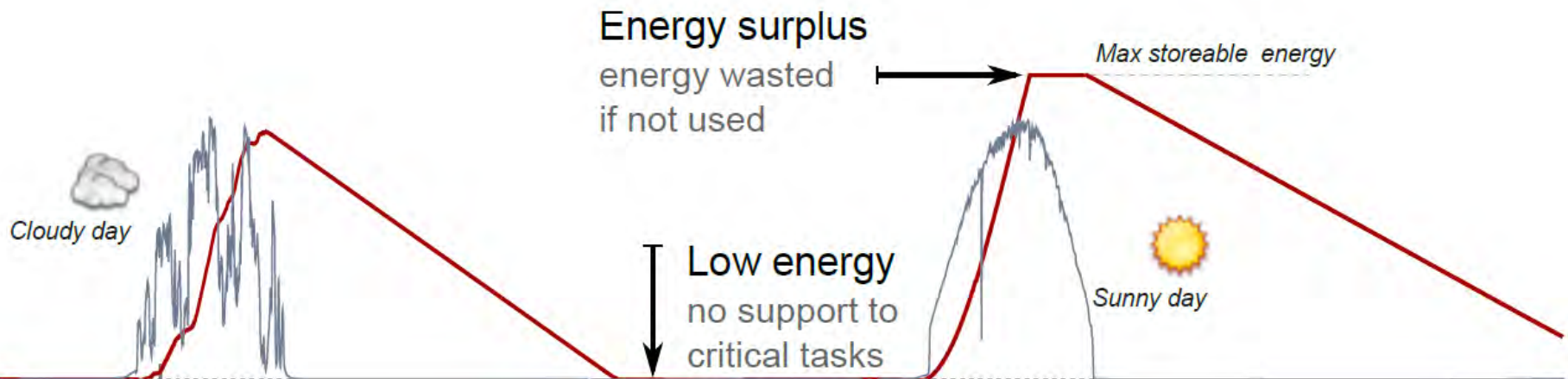
- Pose the basis for very long lasting operation
- Energy Neutral protocols have been proposed for several applications
- Changes also what a WSN can do



- Pose the basis for very long lasting operation
- Energy Neutral protocols have been proposed for several applications
- Changes also what a WSN can do

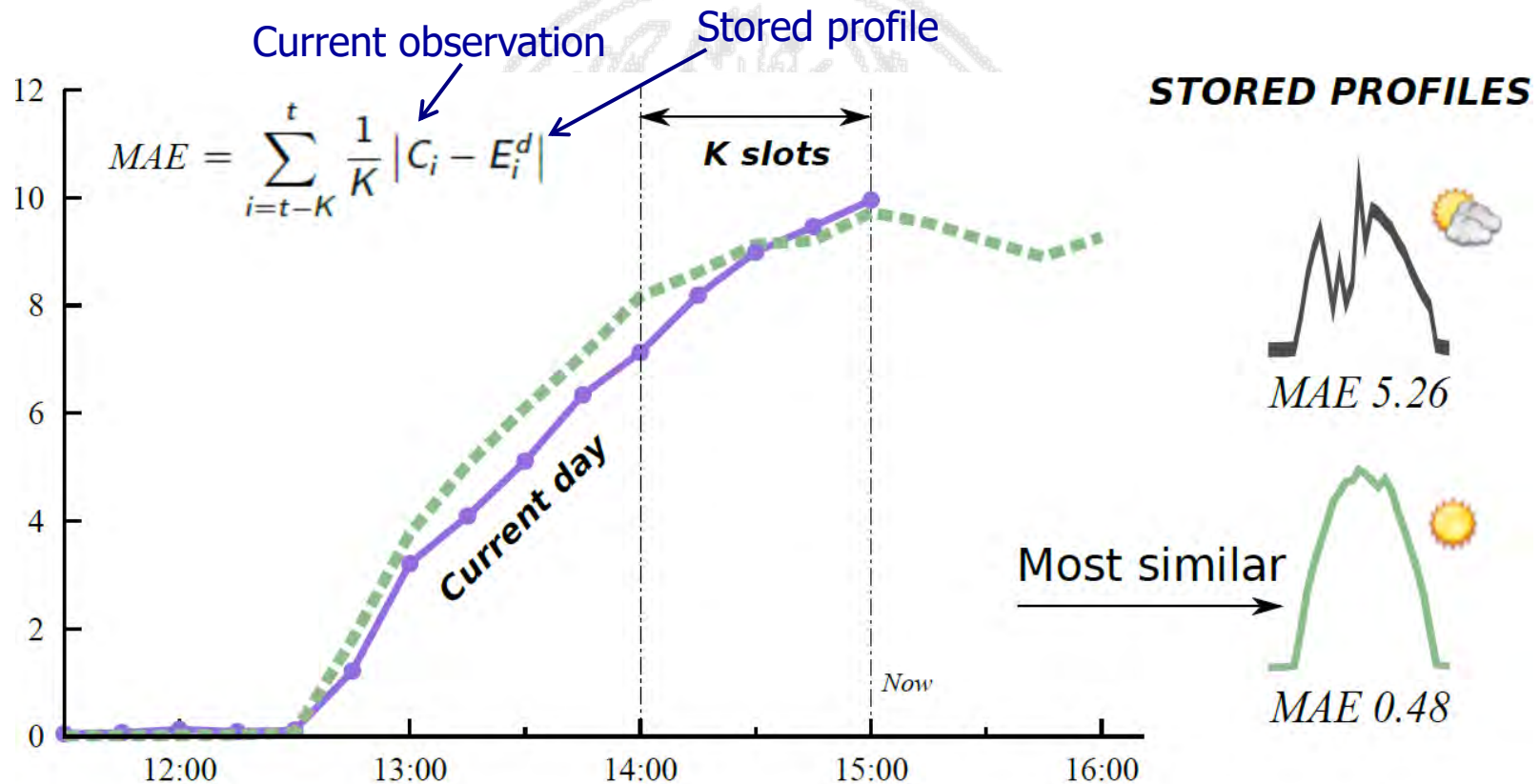


- Energy predictions to mitigate uncertain energy availability
- Plan energy usage in advance: **proactive** vs reactive energy allocation
- Exploit available energy at best:
 - I. Minimizing the likelihood of running out of energy and missing high priority tasks
 - II. Minimizing the waste of energy (energy buffers are limited in size and time)
 - III. Enable operations which were not considered feasible





- Keep track of energy profiles observed during D typical days
- Store traces representative of different weather conditions (sunny, windy, ...)
- Predict future energy intake by looking at the most similar stored profile



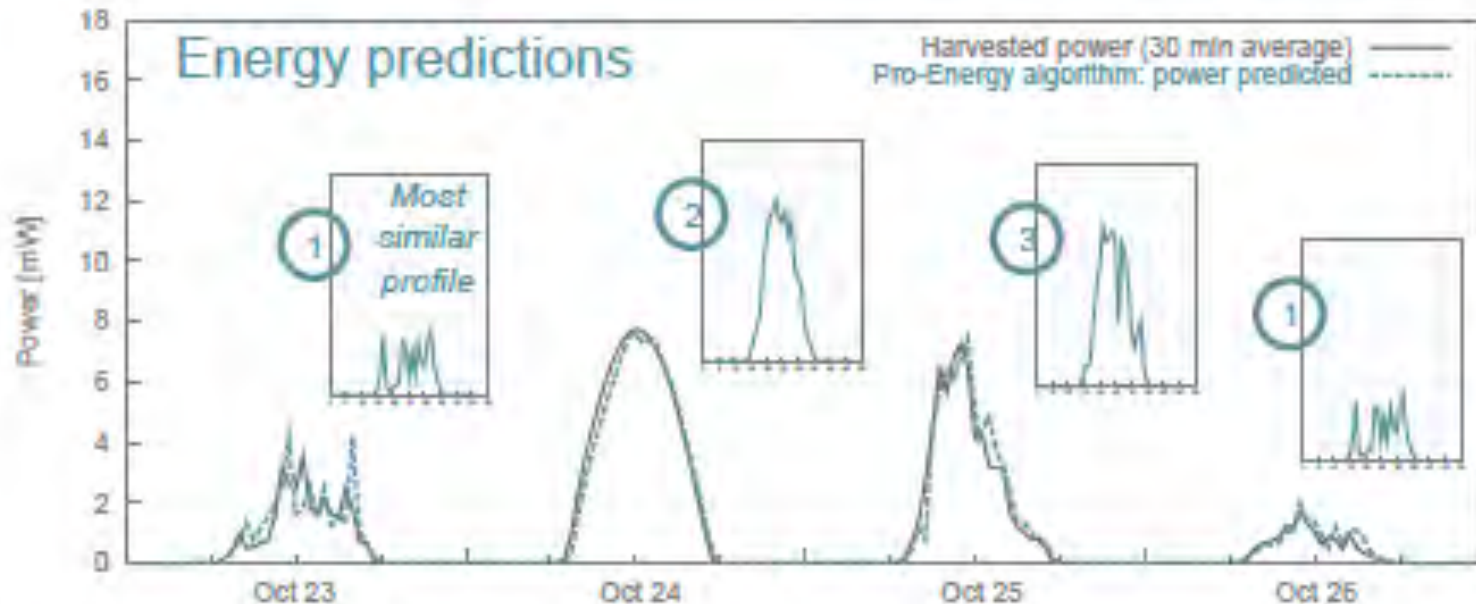


Figure 1. Pro-Energy: harvesting profiles representing energy observations from past days are used to predict the future energy availability.

How to select the current D profiles?

How to predict based on most similar profile?



$$\hat{E}_{t+1} = \alpha \cdot C_t + (1 - \alpha) \cdot E_{t+1}^d \quad (2)$$

where:

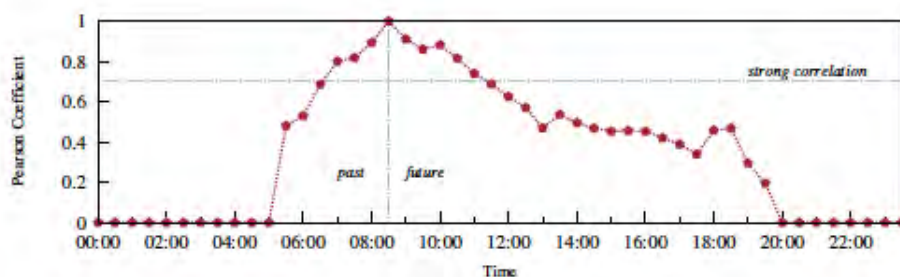
\hat{E}_{t+1} is the predicted energy intake in timeslot $t + 1$ of the current day;

E_{t+1}^d is the energy harvested during timeslot $t + 1$ on the stored day d ;

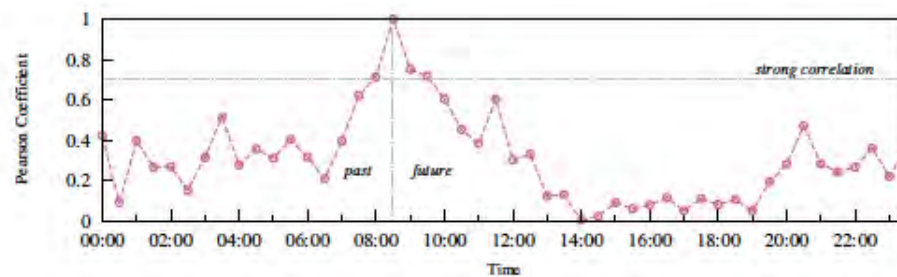
C_t is the energy harvested during timeslot t on the current day C ;

α is a weighting factor, $0 \leq \alpha \leq 1$.

The weighting parameter, α , allows to combine the value reported in the stored profile with the current energy observation, i.e., the energy observed in the last slot, C_t .



(a)



(b)

Figure 2. Pearson autocorrelation coefficient for (a) solar ORNL Dataset and (b) wind Bologna Dataset.

$$\gamma_i = \begin{cases} \alpha \cdot \left(1 - \frac{i-1}{G}\right), & \text{if } i \leq G \\ 0 & \text{if } i > G \end{cases} \quad \forall i, 1 \leq i \leq F$$

where:

- α is the weighting factor defined in Equation (2);
- i is the i^{th} timeslot in the future, with respect to the current slot, t ;
- G is the number of timeslots in the future which show a correlation above a given threshold with timeslot t ;
- F is the number of future timeslots for which Pro-Energy is delivering energy predictions.

Medium term energy
prediction
estimation

$$\hat{E}_{t+i} = \gamma_i \cdot C_t + (1 - \gamma_i) \cdot E_{t+i}^d$$



At the end of the day the profile P of the current day enters the pool if

- We have less than D profiles OR**
- There are old profiles in the pool (stored longer than D_{th} days ago)**
OR
- There is a pair of profiles in the pool which are too similar (MAE below a threshold) → the new profile moves in, the most similar to it among the pairs too close to each other moves out from the pool**



Let $E^{d_1}, E^{d_2}, \dots, E^{d_P}$ be the ordered list of profiles that are most similar to the current day C , i.e., profiles with the smaller Mean Absolute Errors. The weighted profile WP , for the future slot $t+i$, $i \in \{1, 2, \dots, F\}$, is computed as:

$$WP_{t+i} = \frac{1}{P-1} \sum_{j=0}^P w_j \cdot E_{t+i}^{d_j} \quad (4)$$

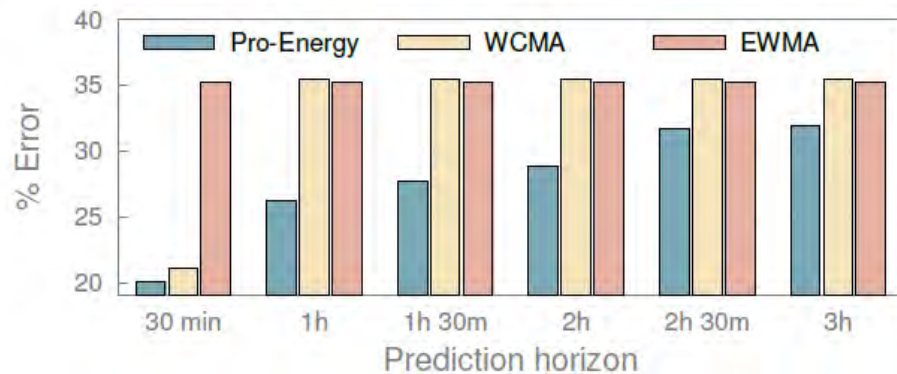
where

$$w_j = 1 - \frac{MAE_k(E^{d_j}, C)}{\sum_{j=1}^P MAE_k(E^{d_j}, C)} \quad (5)$$

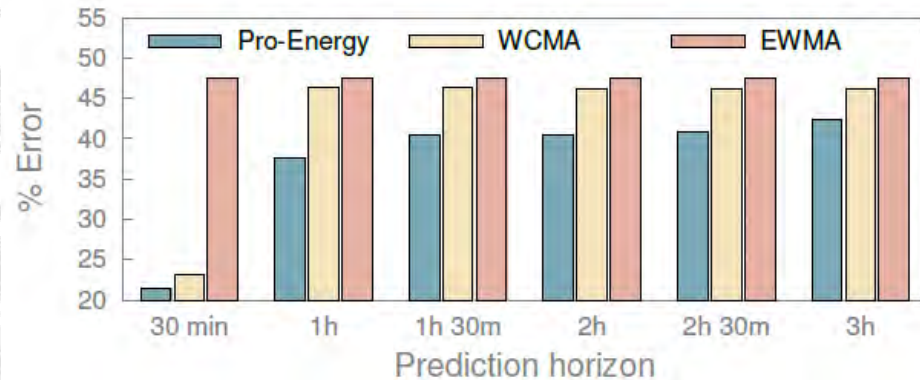
$$\hat{E}_{t+i} = \gamma_i \cdot C_t + (1 - \gamma_i) \cdot WP_{t+i}$$



Solar

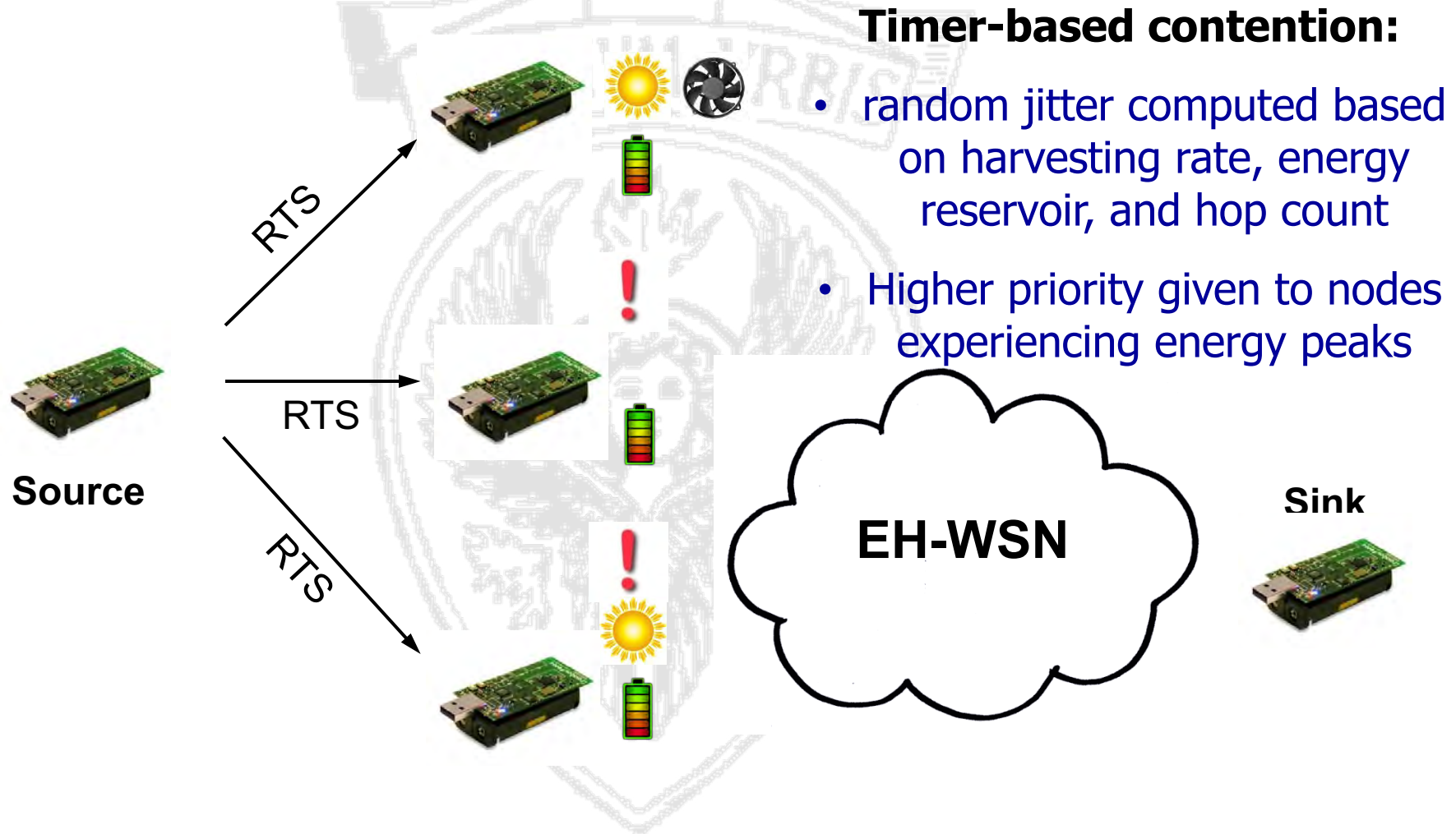


Wind



Solar: Pro-Energy performs up to **75%** better than EWMA and **60%** better than WCMA

Wind: Pro-Energy performs up to **55%** better than EWMA and **10%** better than WCMA





Source



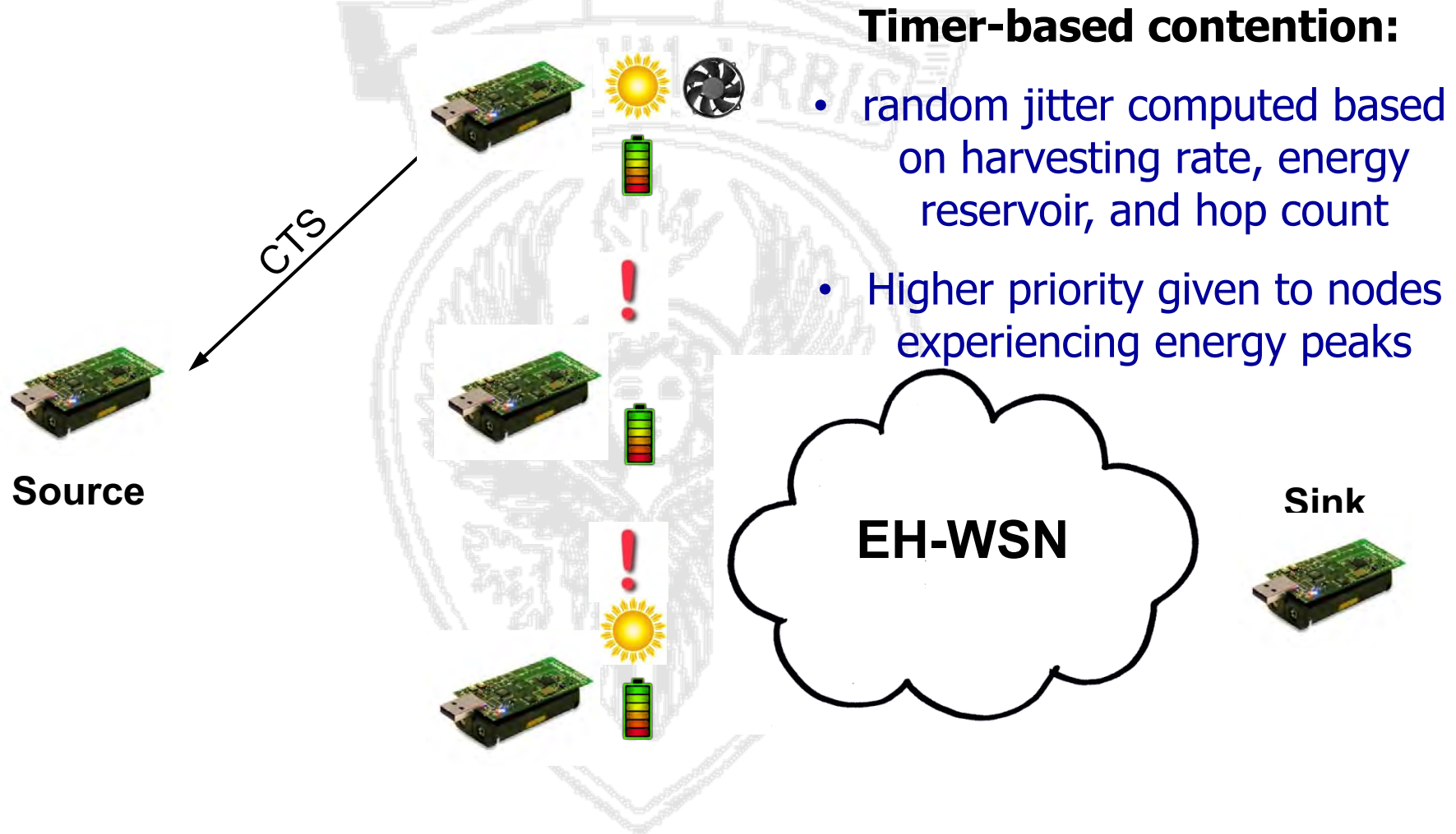
Timer-based contention:

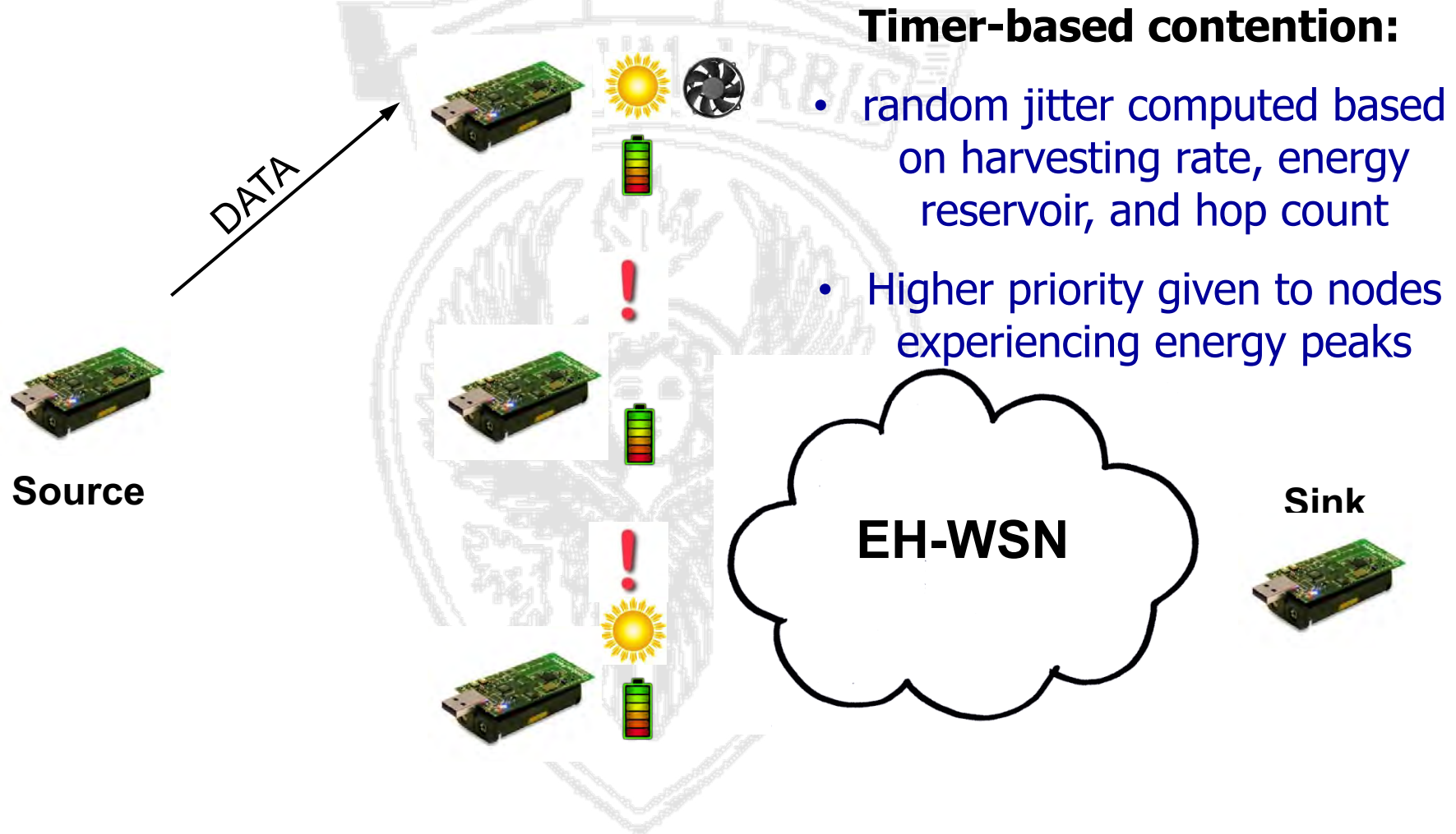
- random jitter computed based on harvesting rate, energy reservoir, and hop count
- Higher priority given to nodes experiencing energy peaks

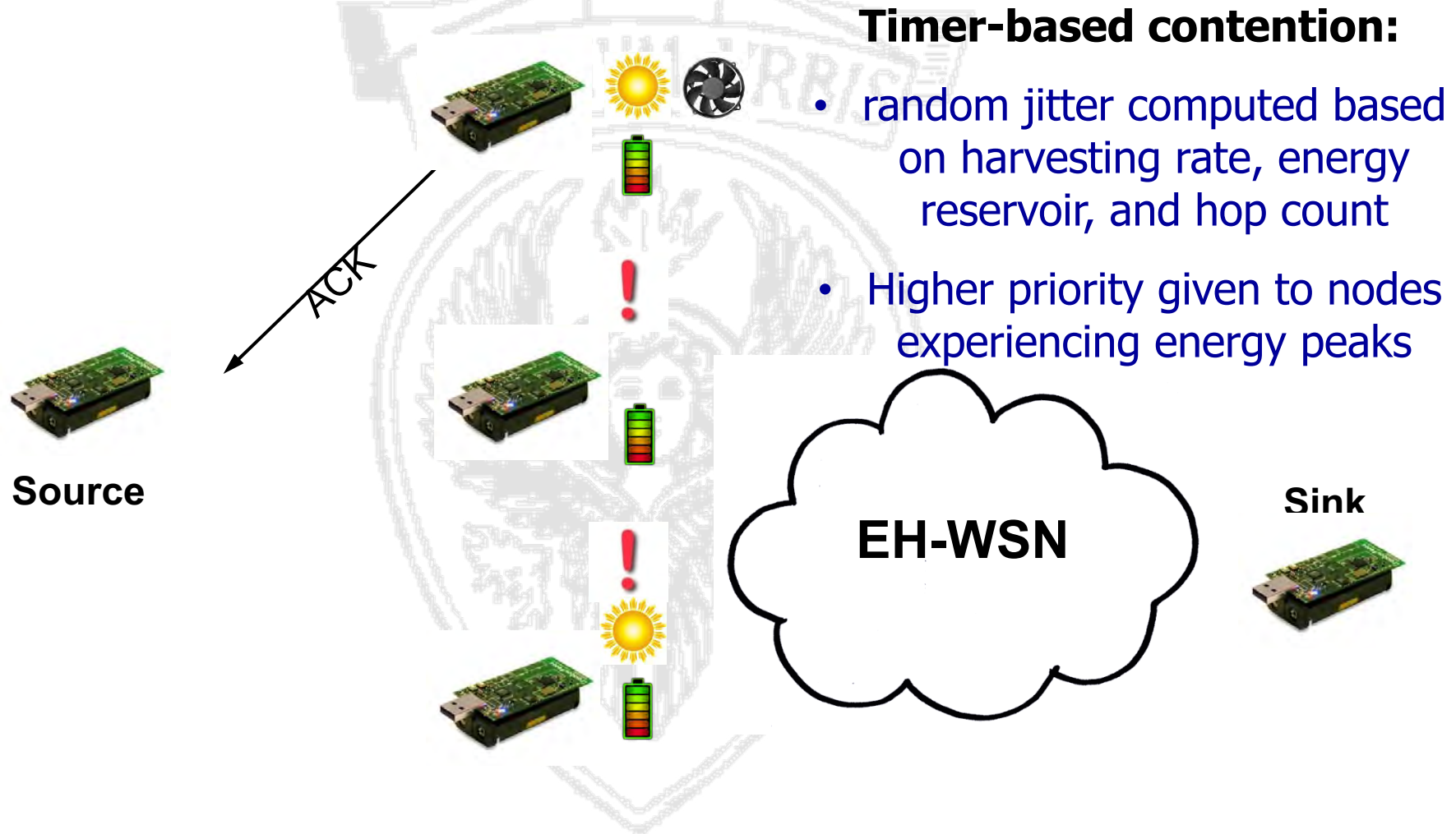


Sink







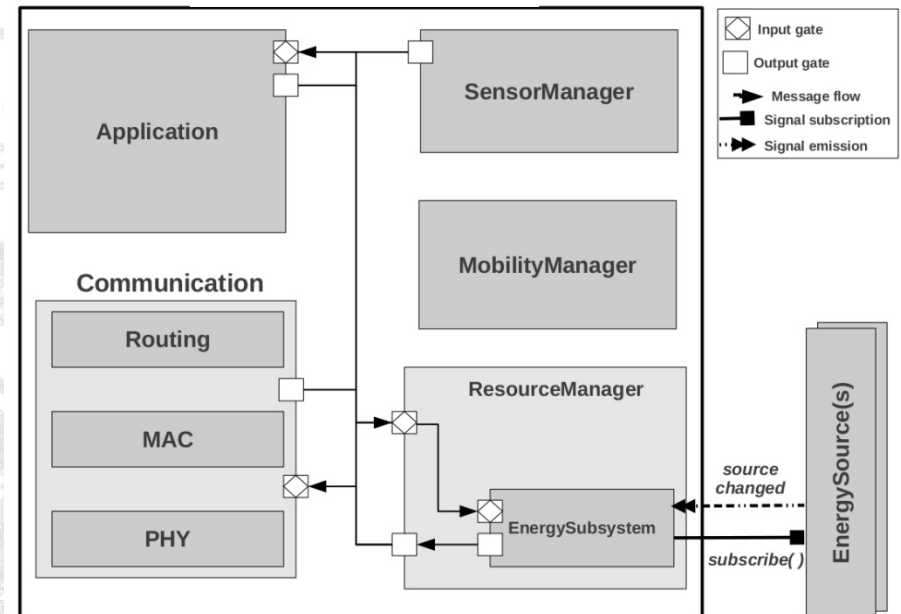




GreenCastalia features

- Support for multi-source harvesting
- Support for multi-storage devices
- Support for energy predictions
- Easily customizable
- Based on Castalia / OMNET++

Sensor node



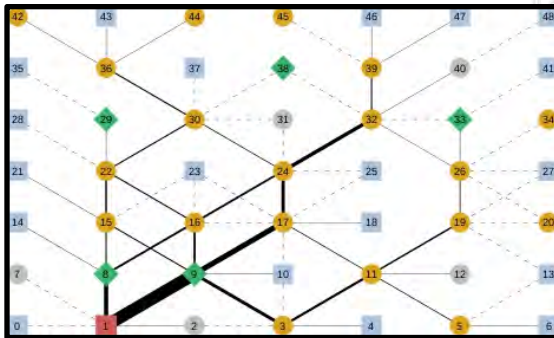
TraceEnergySource module: allows to feed the simulator with timestamped power traces collected through real-life deployments, or with energy availability traces obtained by data repositories or meteorological stations



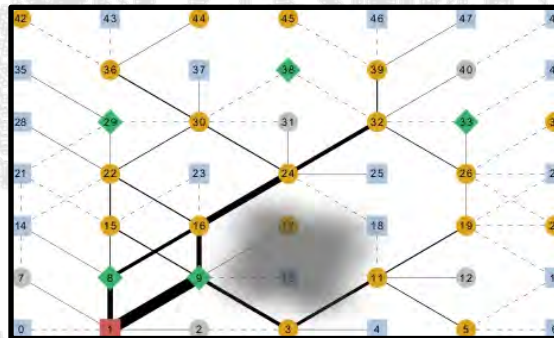
Simulation settings

- 120x120 meters field (7x7 grid deployment)
- Nodes with heterogeneous energy harvesting capabilities:
 - solar, wind both, none

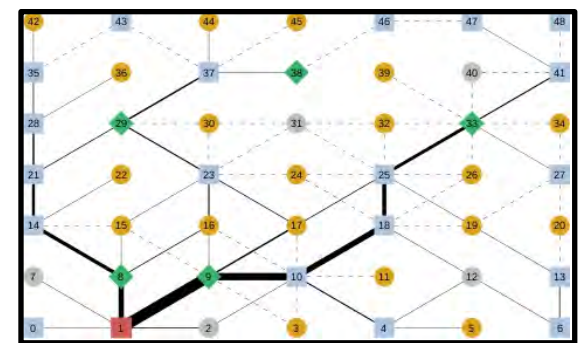
11am



5pm with shadow zone



8pm

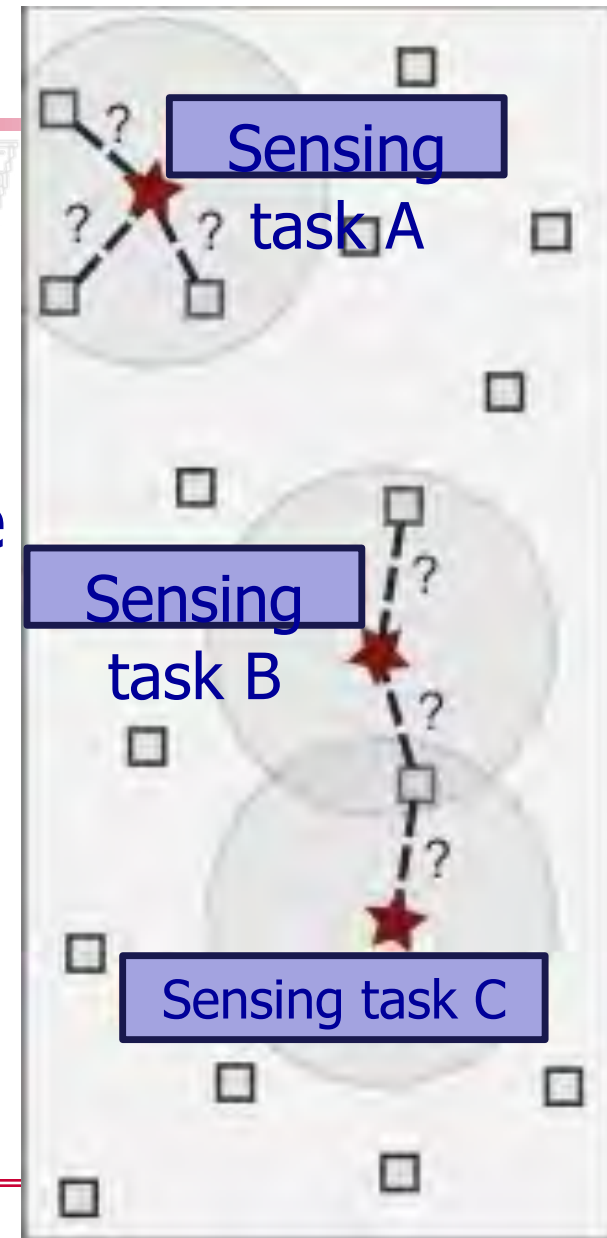


Self-adaptive behaviour: nodes experiencing energy peaks are selected with higher priority as next hop relays

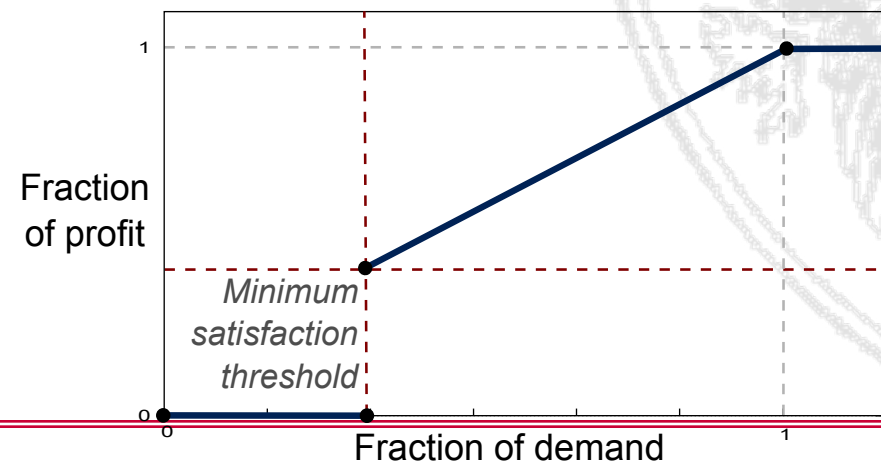
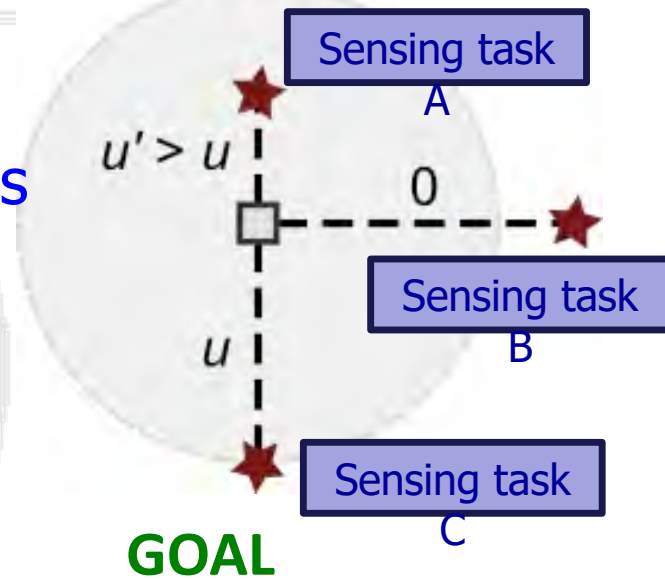


- Sensing tasks (missions) arrive in the network dynamically over time at different locations
- Multiple missions active at the same time, competing for the sensing resources of the network

Decide which sensor(s) should be assigned to each mission



- Missions have different priority (profit) and require different amount of resources (demand)
- **Assignments are not all equal..**
 - Nodes contribute to different missions with different **utility (quality of information)**
 - Achieved profit depends on allocated demand



Maximize the profit obtained by the network for missions execution within a given **target lifetime**



- Distributed heuristic for task allocation in WSN with **energy harvesting**
- Nodes make independent decisions about task execution
- Decision based on:

Partial profit

- 1. Profit of the mission
- 2. Potential contribution to the mission

Tune eagerness

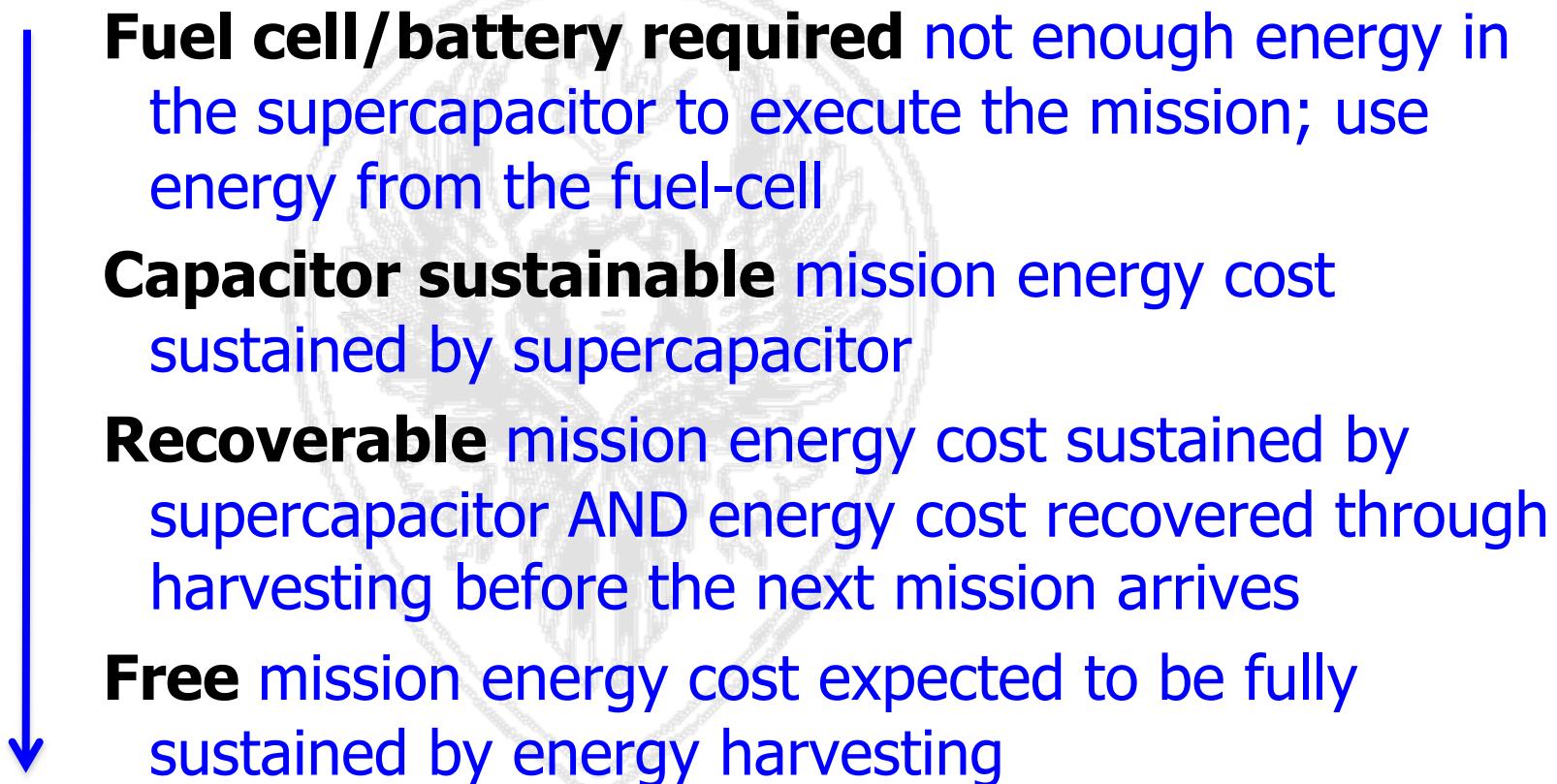
- 1. Target network lifetime

Classify missions

- 1. Current energy level of the node (fuel cell + supercap)
- 2. Energetic cost of the mission
- 3. Future energy availability



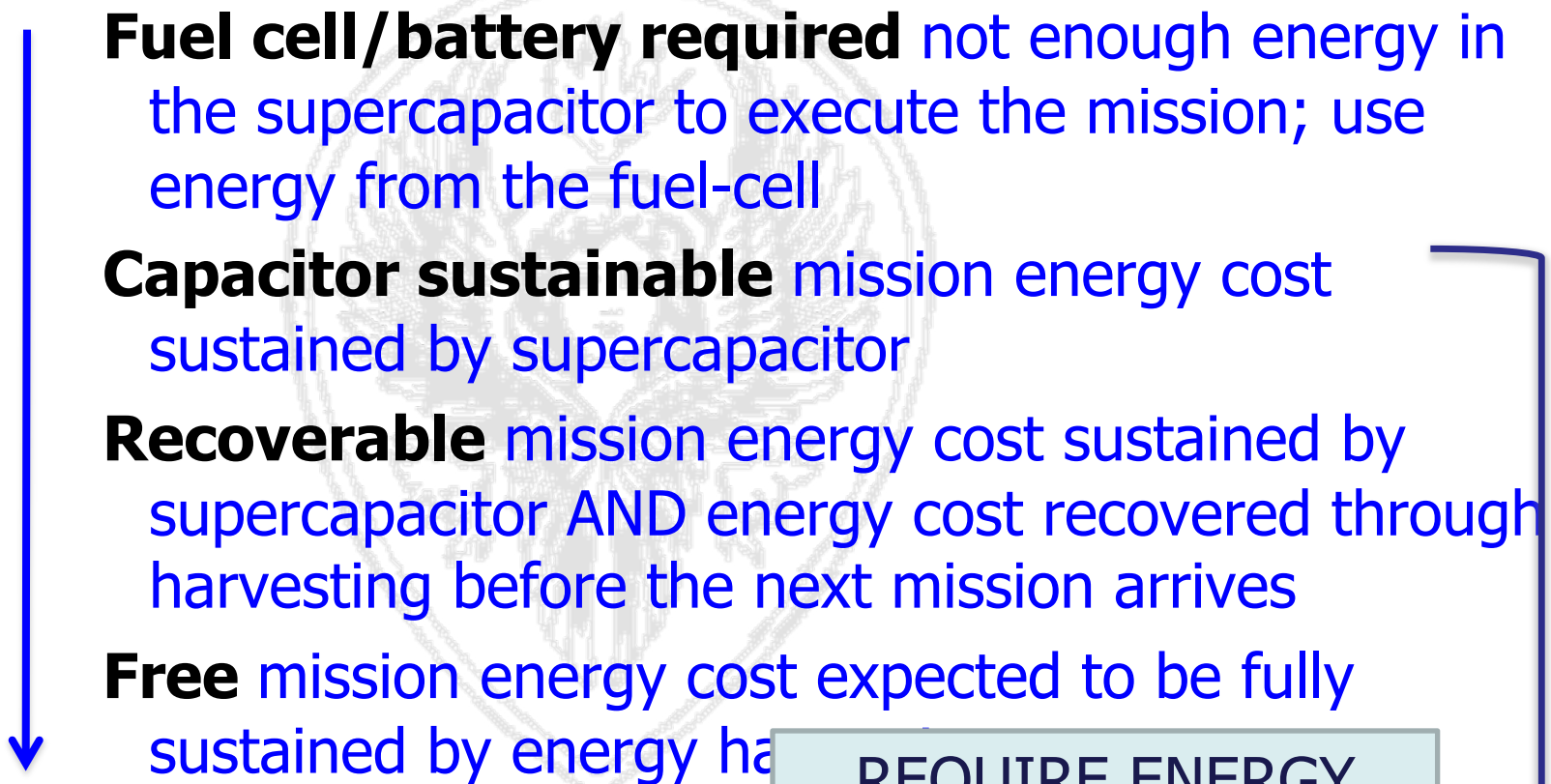
A new mission arrives  check energy requirements and energy availability



More
willing to
accept



A new mission arrives  check energy requirements and energy availability



REQUIRE ENERGY
PREDICTIONS

Task-Allocation

EN-MASSE-In summary



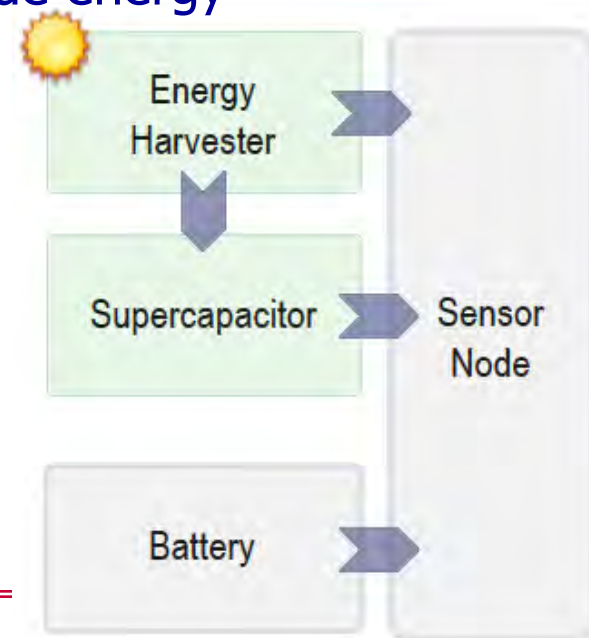
A **decentralized** harvesting-aware heuristic

Key features:

- Uses short and long term energy predictions for pro-active energy allocation
- Takes into account missions arrival statistics to make sustainable allocation decisions
- Considers the impact of executing a mission on node energy

Higher priority to less-impacting missions

1. **Free:** fully sustained by harvesting
2. **Recoverable:** sustained by supercapacitor and recovered before next mission
3. **Capacitor-sustainable:** sustained by supercapacitor
4. **Battery-required:** sustained by battery





- Expected partial profit of a mission

$$\bar{p} = \frac{E[u]}{E[d]} \times \frac{E[p]}{P},$$

Always for free missions

P maximum achievable profit: E[u], E[d], E[p] expected utility, demand and profit of a given mission

- Partial profit achievable by a node participating to a mission

$$p^* = \frac{e_{ij}}{d_j} \times \frac{p_j}{P} \times w$$

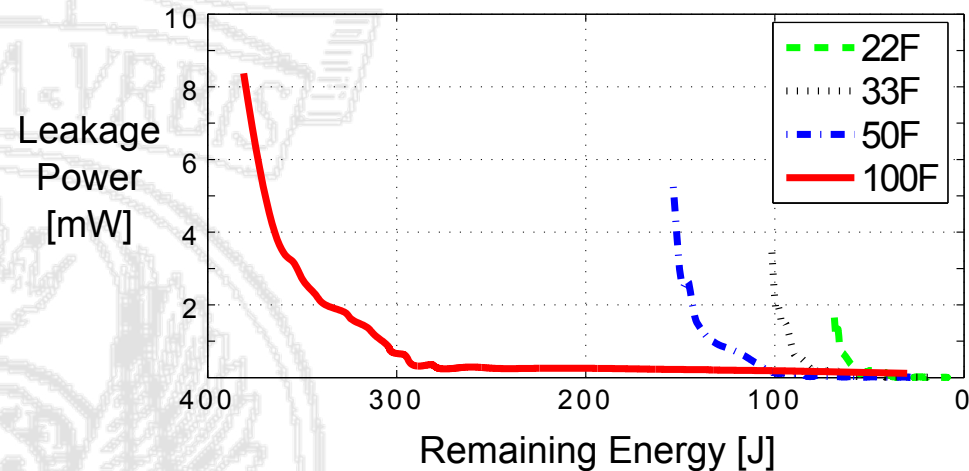
w weight which depends on mission classification. Bid if $p^* \geq$ expected partial profit

Modeling real harvesting systems



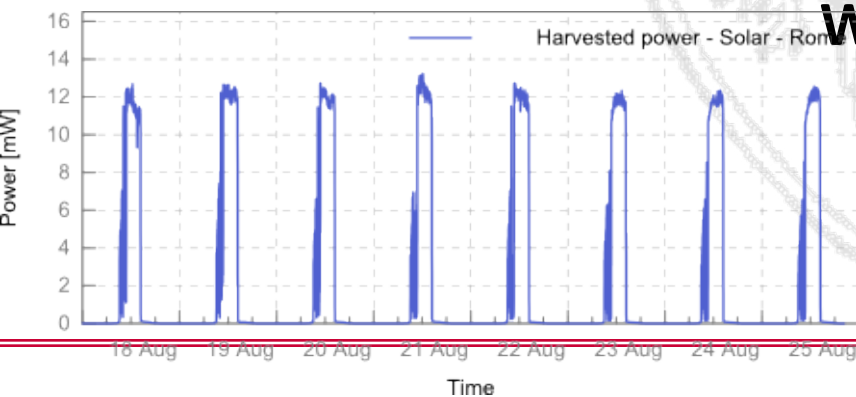
Non-ideal supercapacitors

1. Finite size
2. Charging\discharging efficiency < 1
3. Leakage\self-discharge

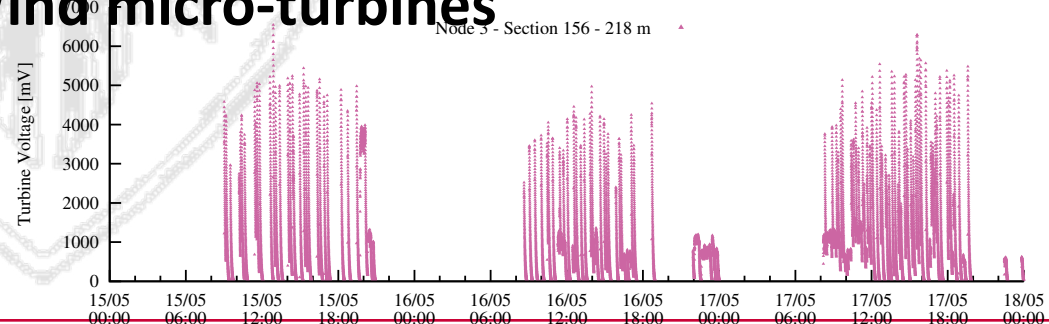


Real-life energy traces

Photovoltaic cells



Wind micro-turbines



Perf. evaluation



Table II. Simulation scenarios: default settings.

Parameter	Value
Nodes in the network	500
Simulation field	400 × 400 m
Communication range	40 m
Sensing range	30 m
Average mission profit	10
Average mission demand	2
Average mission duration	1 hour
Satisfaction threshold	50% of the mission demand

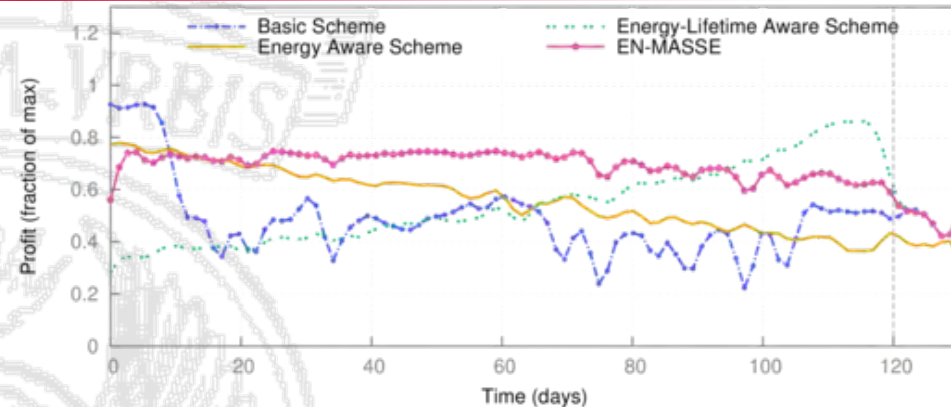
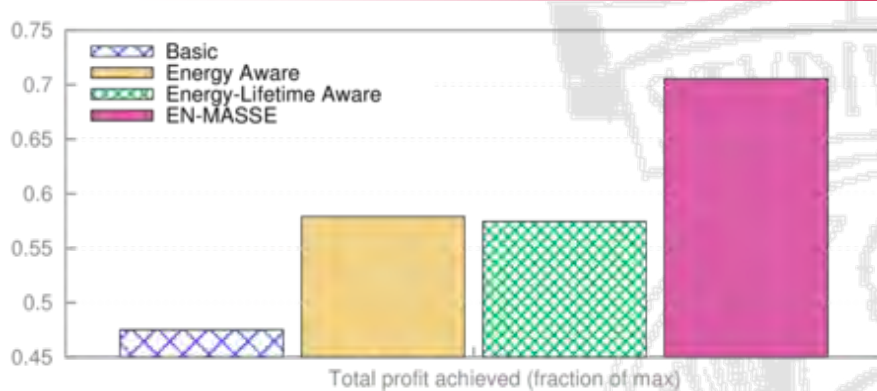
Perf. evaluation



Basic scheme: Nodes always bid for missions within their range

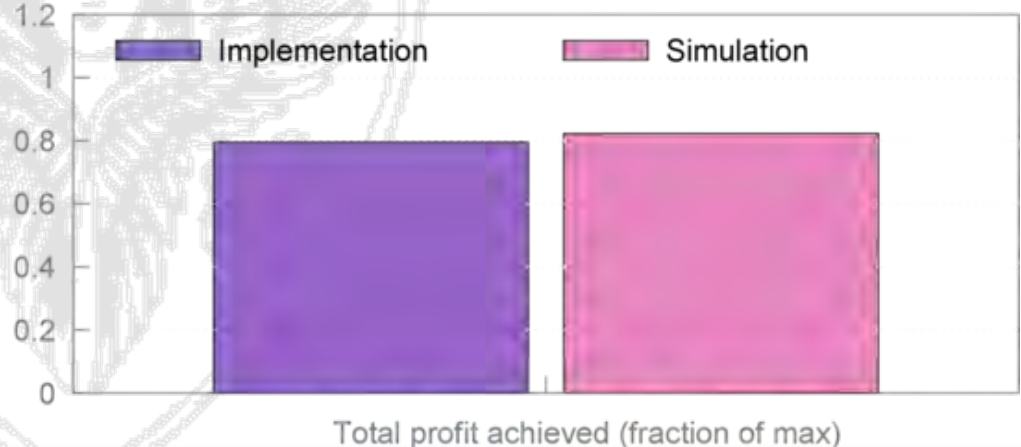
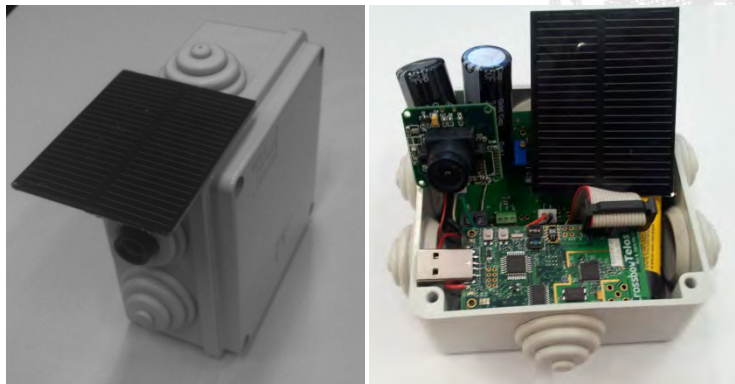
Energy aware scheme: Bids based on profit provided vs. expected profit, weight only considers battery level

Energy lifetime aware scheme: as above but weight set based on active sensing time a node could support given its available battery energy/expected occupancy time till network lifetime



Profit: up to 60% higher than SoA

Stable profit: 70-80% of maximum



In-field testbed validation

Gap between simulations and testbed:
less than 3% of maximum profit

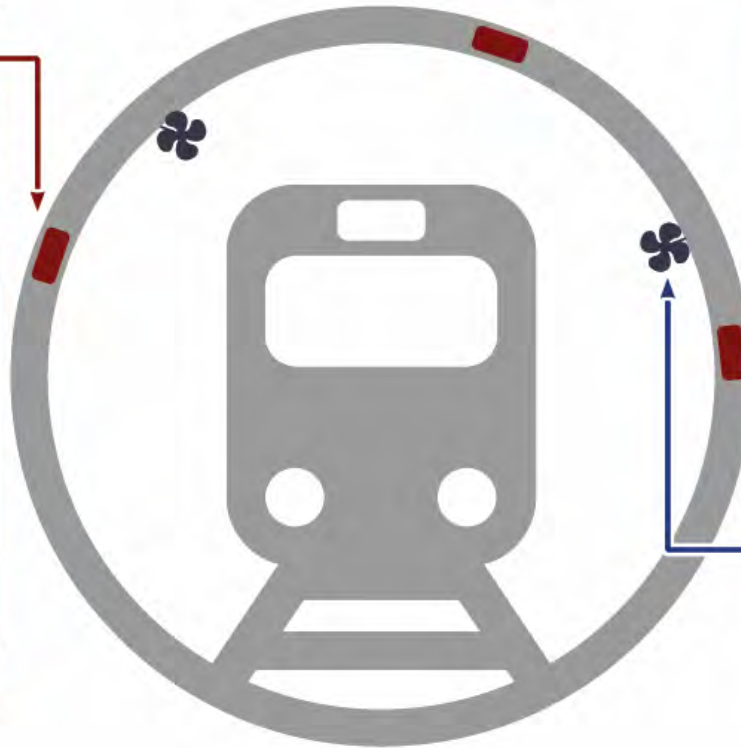


Vibrating Wire Strain Gauges

Monitor concrete and steel deformations to evaluate stability of the underground tunnel



SISGEO OVK4200VC00
Dedicated interface board for TelosB mote
Energy consumption: 720 mJ

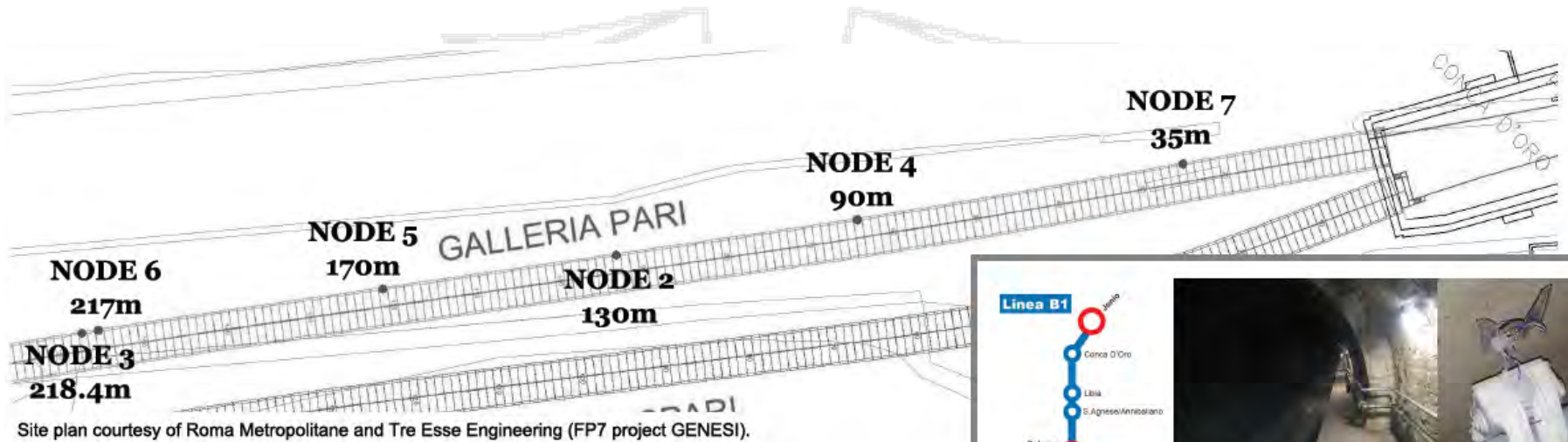


Micro wind turbines

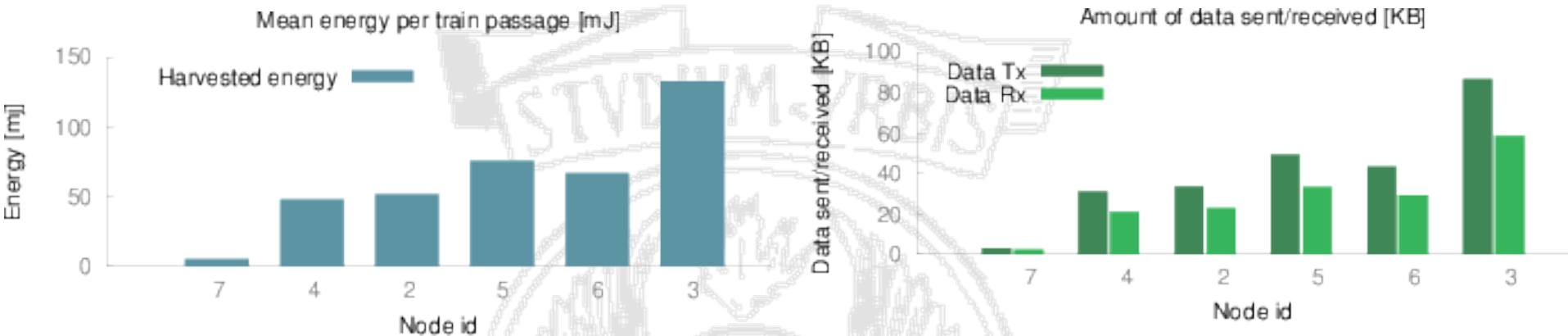
Energy harvesting from wind generated by trains

Why air-flow energy harvesting?

- SHM sensors are power-hungry
- required lifetime of decades or more
- battery-powered WSNs last only a few years

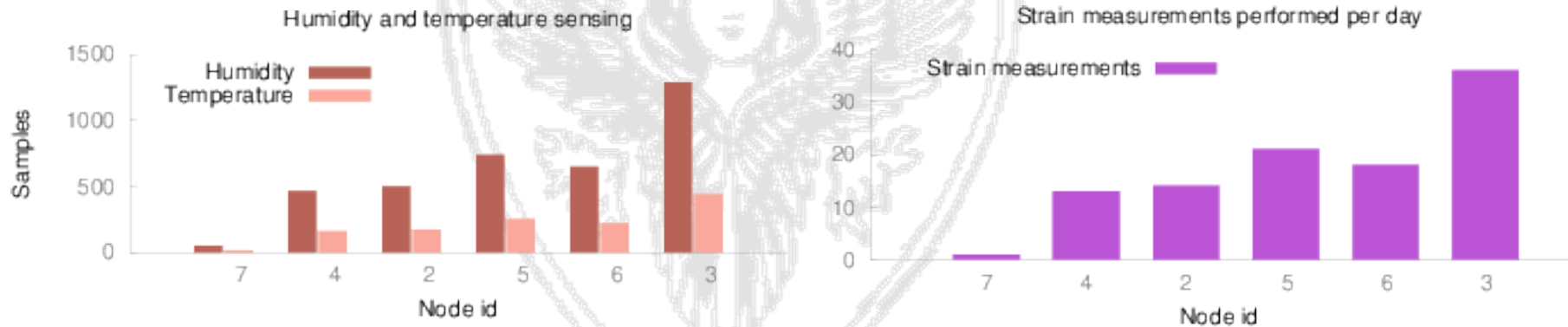


220 meter of instrumented tunnel
6 energy-harvesting nodes
33 days of data collection



Up to 133 mJ harvested per train passage

Transmit/receive tens of KB



Collect hundreds of humidity and temperature samples

Up to 36 strain measurements per day

Protocols for wake-up radio enabled Internet of Things, a.a. 2015/2016

Un. of Rome "La Sapienza"

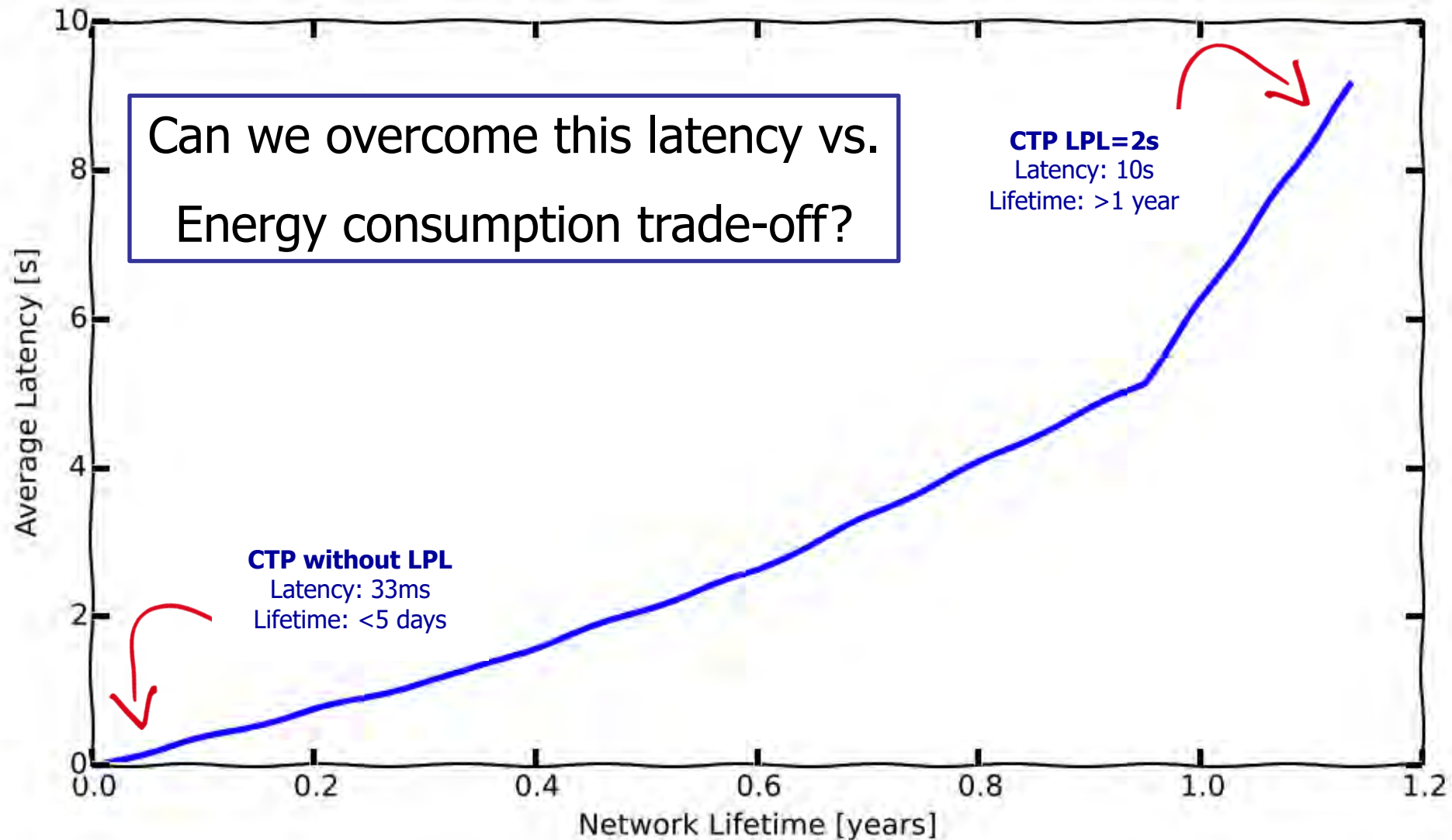
Chiara Petrioli[†]

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Latency vs. Energy Trade-off

Can we overcome this latency vs. Energy consumption trade-off?





- Enable **on-demand** communication

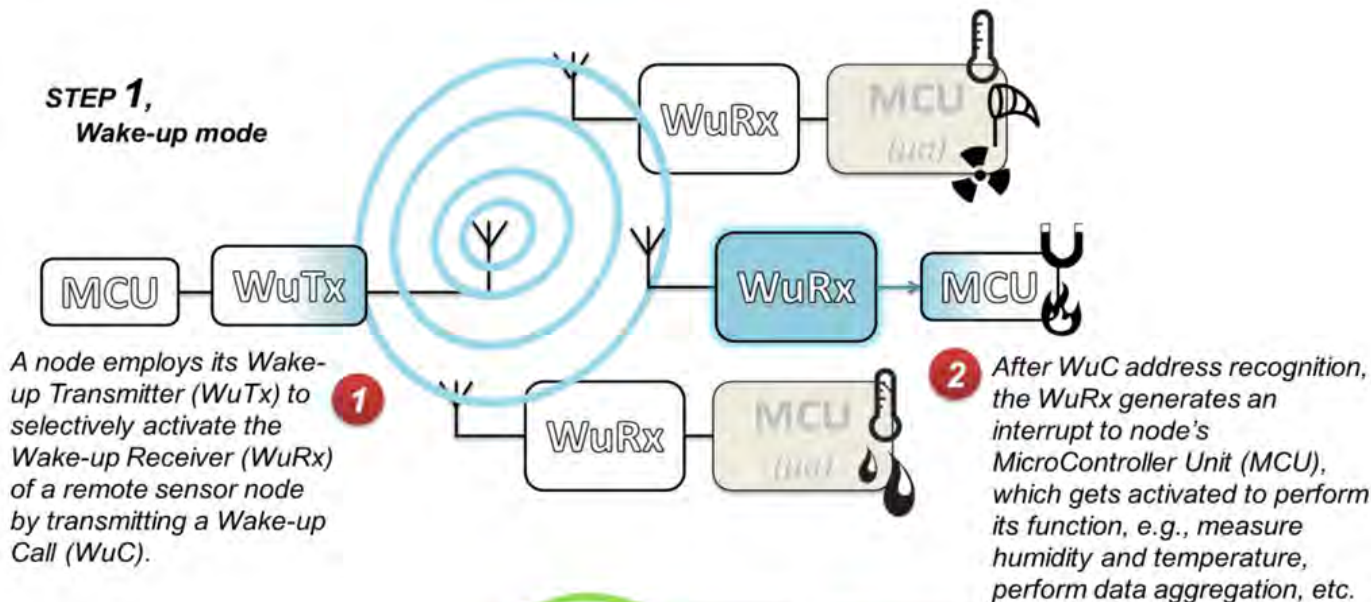
- Low-power dedicated hardware, continuously monitoring the channel
- Nodes keep their main radio OFF unless data communication is needed
- Virtually eliminates idle listening on the main radio
- Based on the architecture, possibility to selectively wake-up only specific nodes

- Terrific energy saving especially in event-based applications

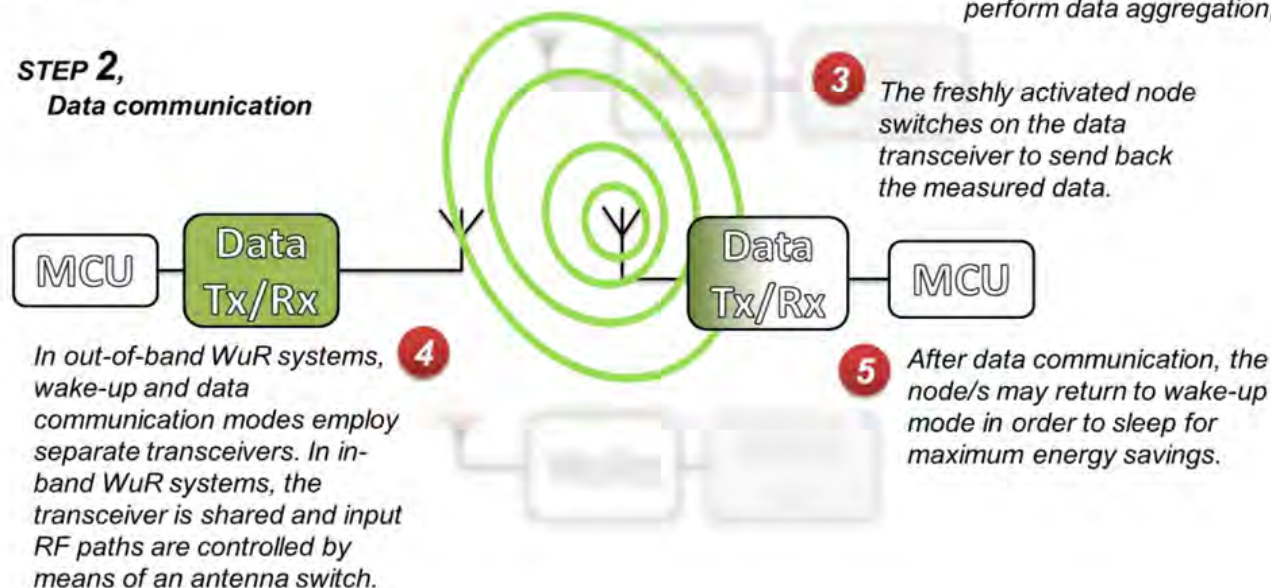
- No latency vs. energy trade off



STEP 1, Wake-up mode



STEP 2, Data communication





Passive WURs

- Harvest power from the radio signal
- No external power supply
- Low sensitivity = short wake-up range (3 m)
- Prone to interferences

RFID-based

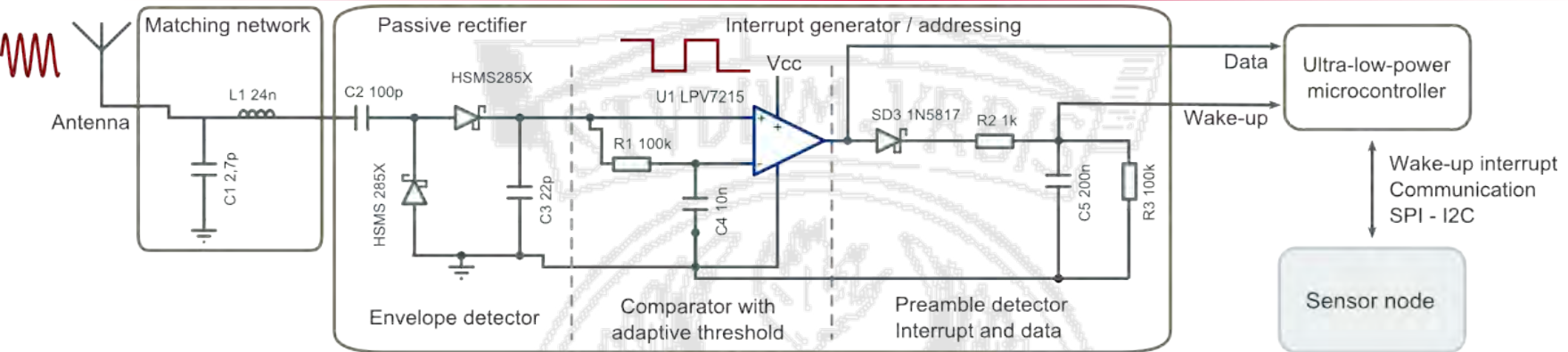
- Shifts energy toll to the transmitter
- Unsuitable for P2P networking

Semi-active WURs

- External power is needed
- Higher sensitivity = longer wake-up range
- Sensitivity: -35 to -47 dBm
- Power consumption: 2.3 to 10 μ W

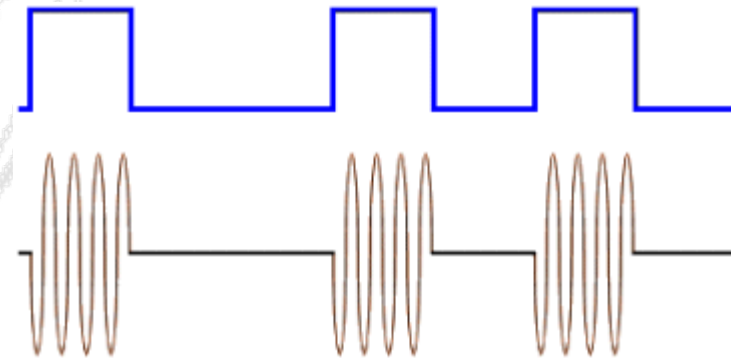
Nano-power WURs

- Power consumption: 98-270 nW
- Wake-up range \leq 10m



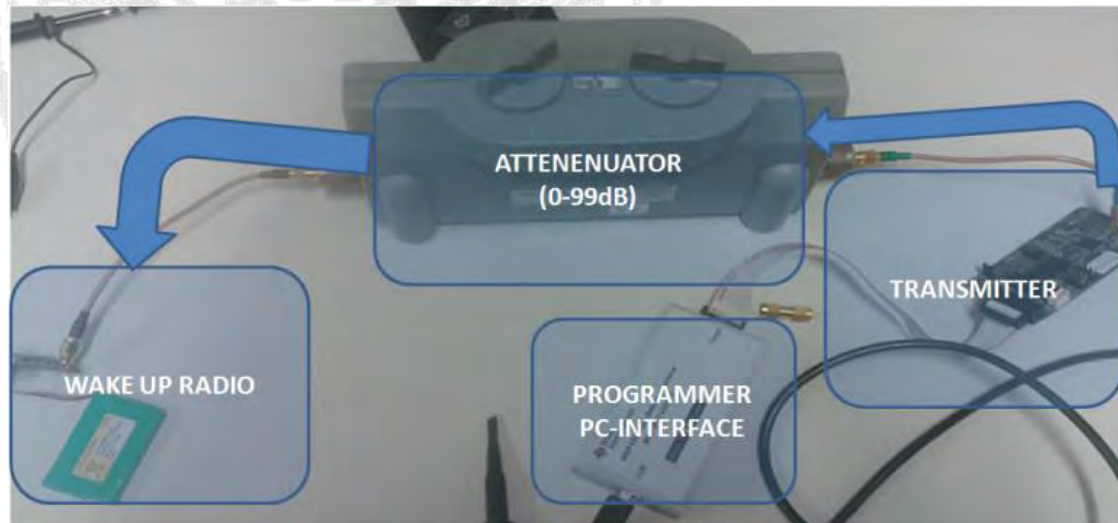
Collaboration with L. Benini and M. Magno, ETHZ

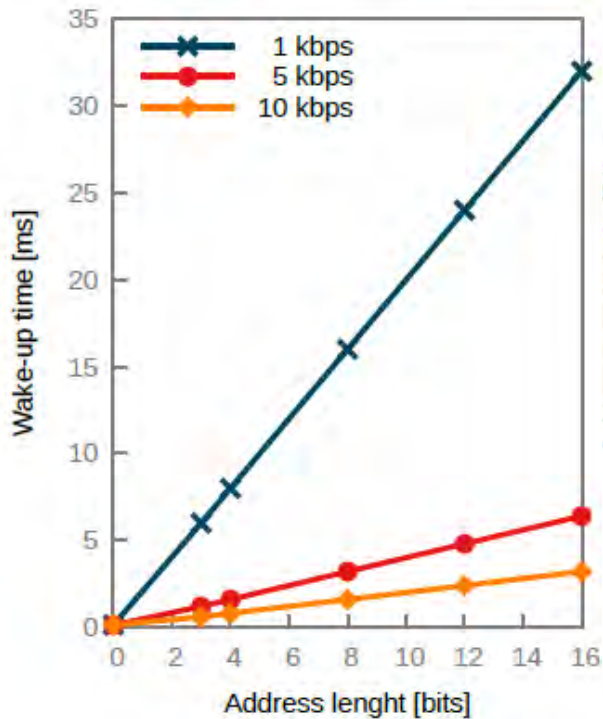
- OOK modulation
- Very low power consumption ($< 1.3\mu\text{W}$)
- High sensitivity (up to -49dBm)
- Fast reactivity (wake-up time of $130\mu\text{s}$)
- **Selective addressing**



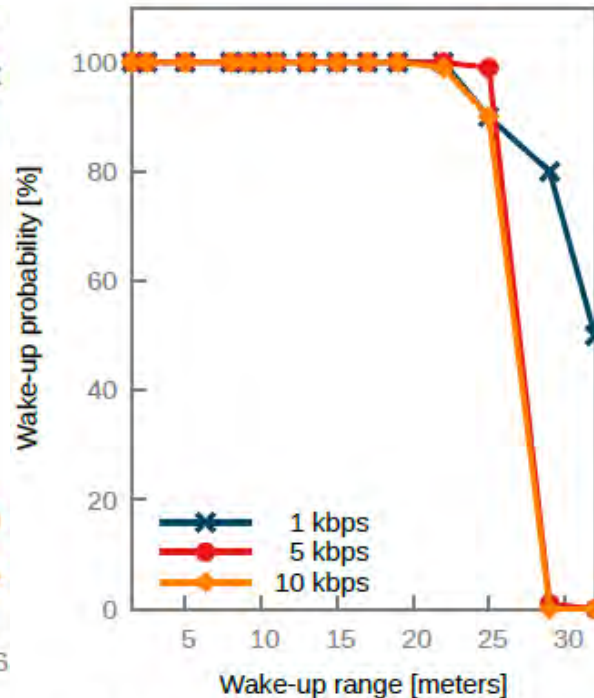


- TI CC1101 used to transmit WRx requests
- on-board PIC microcontroller to perform addressing while keeping the MagoNode in deep-sleep

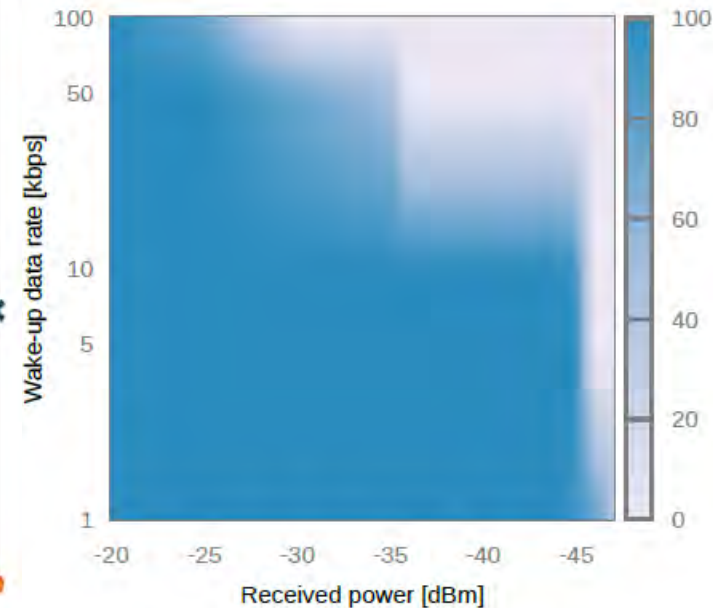




(a) Wake-up latency



(b) Wake-up probability vs. distance



(c) Wake-up probability vs. received power

- Sensitivity: -49 dBm
- Maximum wake-up range: 42 m (no addressing)
- Wake-up probability depends on WTx data rate and distance



- **Key idea: Semantic wake up addressing**
- use WRx addresses to wake up a node or a group of nodes based on their **state**
 - selectively wake up only **good** potential relays
 - e.g., relays ranked based on advance toward the sink, traffic and channel conditions
 - WRx addresses have a **semantic meaning**
 - each node dynamically changes its own WRx address to reflect its state



Wake-up-enabled communication stack

- ▶ Exploits proposed WuR to addresses latency vs. energy consumption tradeoff
- ▶ Both interest dissemination and convergecasting primitives
- ▶ **Key idea:** use wake-up addresses to wake up a node or a group of nodes based on certain properties

Interest dissemination

- ▶ Transmission of commands from sink to nodes
- ▶ **Goal:** avoid reception of duplicated packets
- ▶ Use current wake-up address to indicate whether a packet was already received



FLOOD-WUP

- ▶ Nodes are assigned shared wake-up broadcast addresses: w_a and w_b
- ▶ Initially in sleep, wake-up radio active with address = w_a

- ✱ Sink broadcasts first interest packet preceeding it with wake-up sequence w_a
- ✱ Nodes with address w_a wakes up, sets main radio to RX, receive packet

Sink



wa

wa

wa

wa

wa

wa

wa



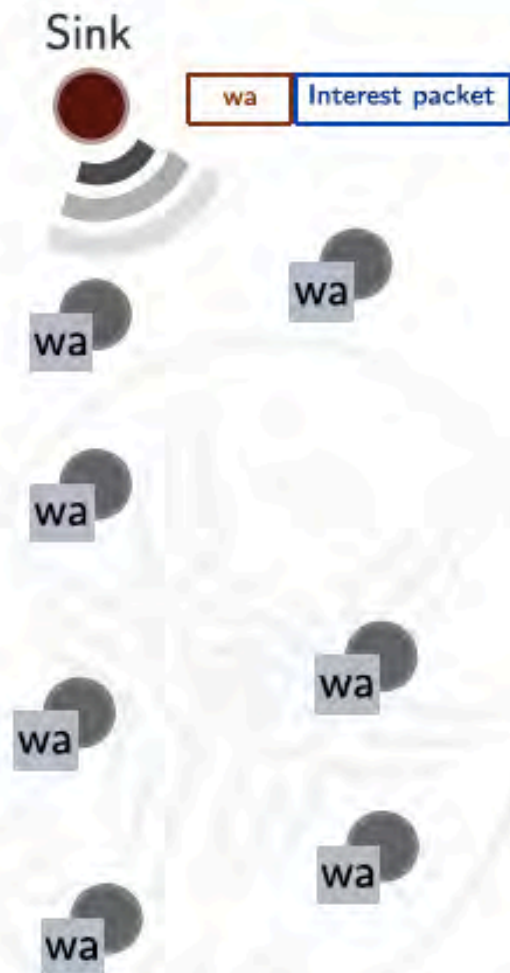


FLOOD-WUP

- ▶ Nodes are assigned shared wake-up broadcast addresses: w_a and w_b
- ▶ Initially in sleep, wake-up radio active with address = w_a
- ▶ Sink broadcasts first interest packet preceding it with wake-up sequence w_a

★ Nodes with address w_a wakes up, receive packet and forward it to R/L primary packet

★ Then change broadcast wake-up address to w_b





FLOOD-WUP

- ▶ Nodes are assigned shared wake-up broadcast addresses: w_a and w_b
- ▶ Initially in sleep, wake-up radio active with address = w_a
- ▶ Sink broadcasts first interest packet preceding it with wake-up sequence w_a
- ▶ Nodes with address w_a wakes up, sets main radio to RX, receive packet

- Nodes change broadcast address to w_b
- Sink & Floodgates nodes rebroadcast packet broadcast address





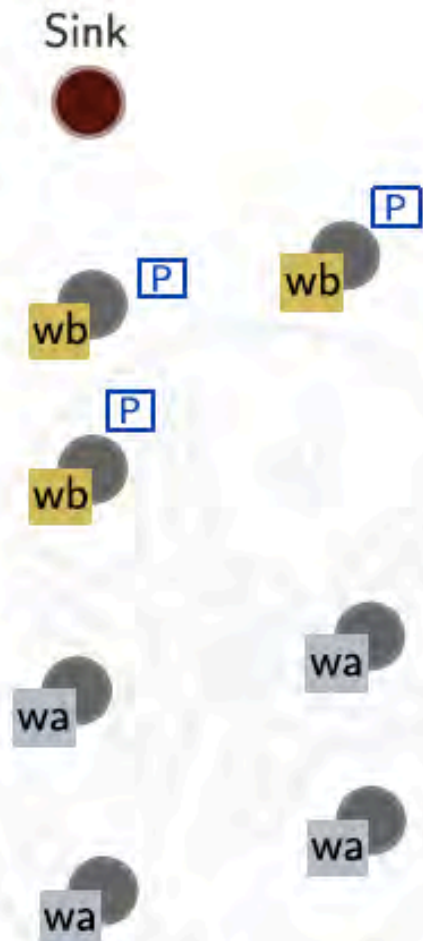
FLOOD-WUP

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- ▶ Nodes with address w_a wakes up, sets main radio to RX, receive packet
- ▶ Then change broadcast wake-up address to w_b

After a random time, nodes re-broadcast packet preceding it with w_b .

After a random time, nodes re-broadcast packet preceding it with w_a .

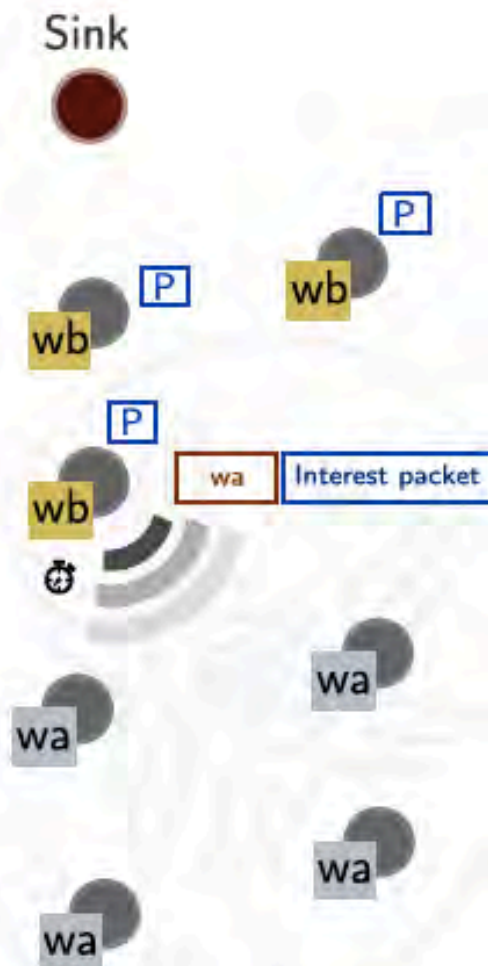
After a random time, nodes re-broadcast packet preceding it with w_b .





FLOOD-WUP

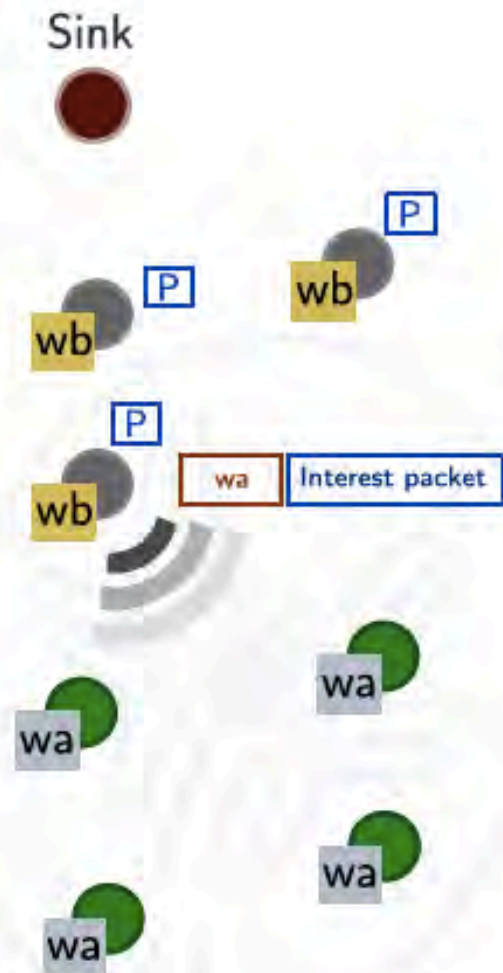
- ▶ Nodes are assigned shared wake-up broadcast addresses: w_a and w_b
- ▶ Initially in sleep, wake-up radio active with address = w_a
- ▶ Sink broadcasts first interest packet preceding it with wake-up sequence w_a
- ▶ Nodes with address w_a wakes up, sets main radio to RX, receive packet
- ▶ Then change broadcast wake-up address to w_b
- ▶ After a random time, nodes re-broadcast packet preceding it with w_a





FLOOD-WUP

- ▶ Nodes are assigned shared wake-up broadcast addresses: w_a and w_b
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- ▶ Then change broadcast wake-up address to w_b
- ▶ After a random time, nodes re-broadcast packet preceding it with w_a
- ▶ **No duplicates, only nodes with address w_a wake up**





Converge Casting: GREEN-WUP

- ▶ Multi-hop data transfer to sink
- ▶ Energy harvesting scenario: nodes scavenge power from environment
- ▶ **Key idea:** Selectively wake-up only **good** potential relays
- ▶ Ranked based on hop count, residual energy, energy intake (harvesting-aware)
- ▶ Wake-up addresses have a **semantic meaning**
- ▶ Nodes dynamically change their wake-up addresses over time to reflect their state
 - ▶ Format **Hop count** **Energy class**
 - ▶ Energy class depends on harvesting and residual energy



GREEN-WUP

► Example: energy classes

max battery level $>$ threshold T_{high} and excess energy from harvesting

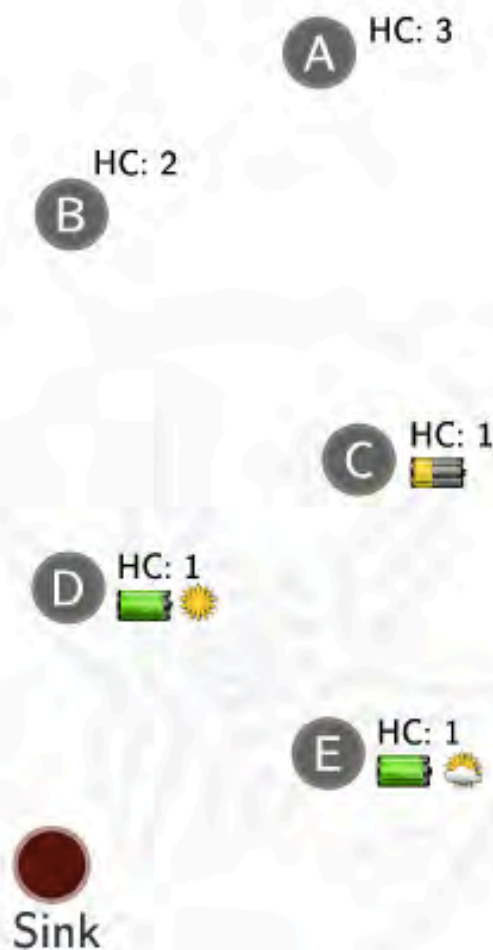
2 battery level $> T_{high}$

1 $T_{low} < \text{battery level} \leq T_{high}$

0 battery level $\leq T_{low}$

* Node E has a packet to transmit

* Sends RTS only to nodes with $\text{harvest} = 1$ and $\text{energy} = \text{max}$. Then it goes to sleep





GREEN-WUP

► Example: energy classes

max battery level $>$ threshold T_{high} **and** excess energy from harvesting

2 battery level $> T_{high}$

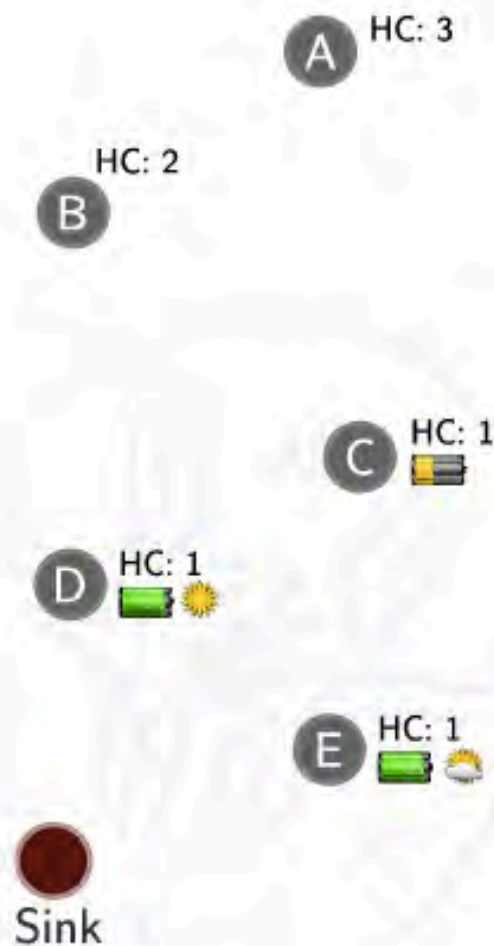
1 $T_{low} < \text{battery level} \leq T_{high}$

0 battery level $\leq T_{low}$

► Node B has a packet to transmit

► Sends RTS only to nodes with **high** energy and **not** energy $< T_{low}$. Then it goes to sleep

► Node **not** selected wakes up. Other nodes continue to sleep





GREEN-WUP

► Example: energy classes

max battery level > threshold T_{high} and excess energy from harvesting

2 battery level > T_{high}

1 $T_{low} < \text{battery level} \leq T_{high}$

0 battery level $\leq T_{low}$

► Node B has a packet to transmit

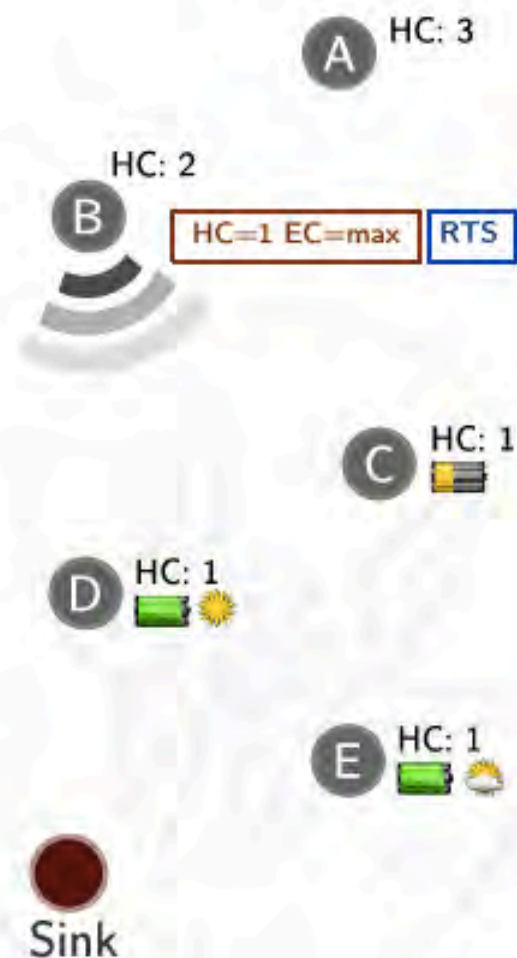
► Sends RTS only to nodes with hopcount = 1 and energy = max. Then it goes to sleep

► Only node A wakes up. Other nodes

continue to sleep

► Node B sends RTS to node A and goes to sleep

► Node A receives RTS and wakes up





GREEN-WUP

► Example: energy classes

max battery level > threshold T_{high} and excess energy from harvesting

2 battery level > T_{high}

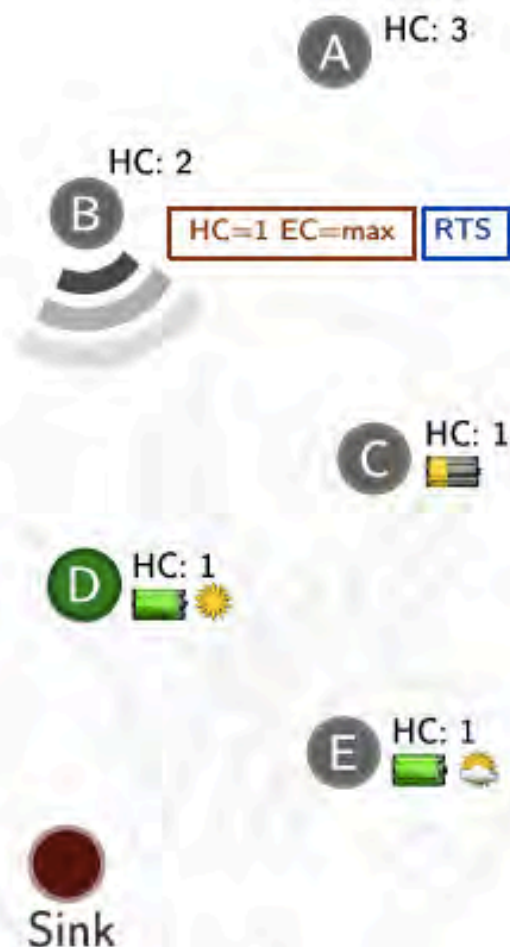
1 $T_{low} < \text{battery level} \leq T_{high}$

0 battery level $\leq T_{low}$

► Node B has a packet to transmit

► Sends RTS only to nodes with hopcount = 1 and energy = max. Then it goes to sleep

► Only node D wakes up. Other nodes continues to sleep





GREEN-WUP

- ▶ Example: energy classes

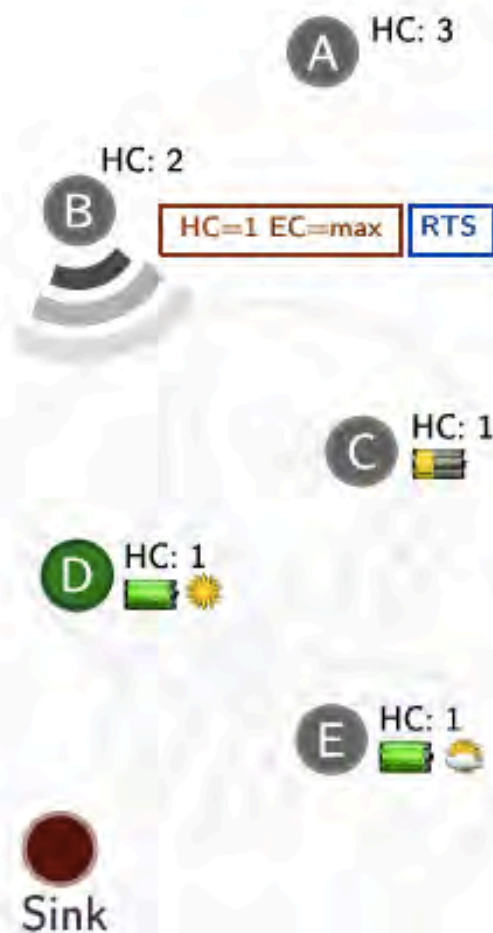
max battery level $>$ threshold T_{high} and excess energy from harvesting

2 battery level $> T_{high}$

1 $T_{low} < \text{battery level} \leq T_{high}$

0 battery level $\leq T_{low}$

- ▶ Node B has a packet to transmit
- ▶ Sends RTS only to nodes with hopcount = 1 and energy = max. Then it goes to sleep
- ▶ Only node D wakes up. Other nodes continues to sleep
- ▶ Iterate on energy class if no relay found





GREEN-WUP

- ▶ Example: energy classes

max battery level $>$ threshold T_{high} and excess energy from harvesting

2 battery level $> T_{high}$

1 $T_{low} < \text{battery level} \leq T_{high}$

0 battery level $\leq T_{low}$

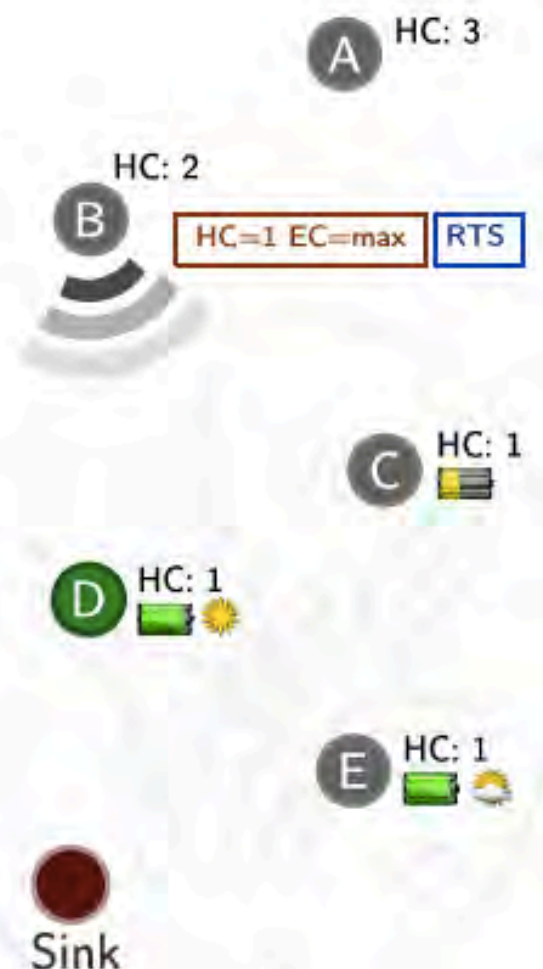
- ▶ Node B has a packet to transmit

- ▶ Sends RTS only to nodes with hopcount = 1 and energy = max. Then it goes to sleep

- ▶ Only node D wakes up. Other nodes continues to sleep

- ▶ Iterate on energy class if no relay found

- ▶ CTS, DATA, ACK..





Different concept of wake up radio

- Active, higher energy consumption
- + Semantic WUP radio addresses
- + Only one transceiver (TX)

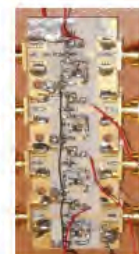
Key feature of the proposed WuR

- ▶ Selective addressing of nodes combining **frequency-domain** and **time-domain** addressing space
- ▶ **Wake-up signal**: sequence of continuous-wave pulses OOK modulated over c IEEE 802.15.4 channels (2.4 GHz ISM band)



Prototyping and design validation

- ▶ Prototype with 4 channels at 2410, 2435, 2455 and 2480 MHz
- ▶ Lab experiments: sensitivity of -83 dBm
- ▶ In-field experiments: RX node (TelosB + WuR), TX node (MTM-CM3300)
- ▶ Varying distance up to 120 m
- ▶ TX node sends 4 different wake-up sequences (8 symbols) 100 times
- ▶ Wake-up statistics recorded by RX node
- ▶ **False positive and false negative both < 1%**
- ▶ Simulation for power consumption scaling: 168 μ W per filter, 1.6 mW overall (including LNA)

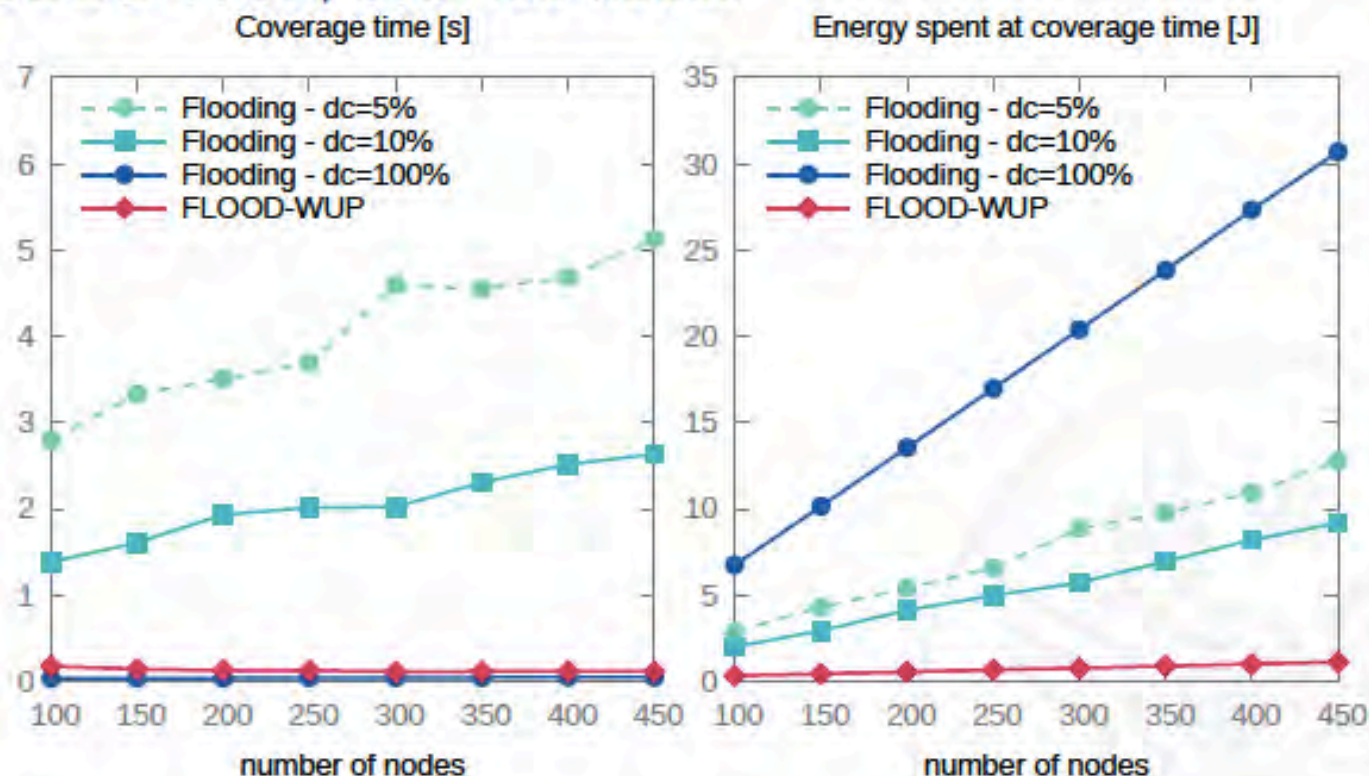


Green Castalia simulations

Chiara Petrioli, Dora Spenza, Pasquale Tommasino, Alessandro Trifiletti
A Novel Wake-Up Receiver with Addressing Capability for Wireless
Sensor Nodes. IEEE DCOSS 2014: 18-25



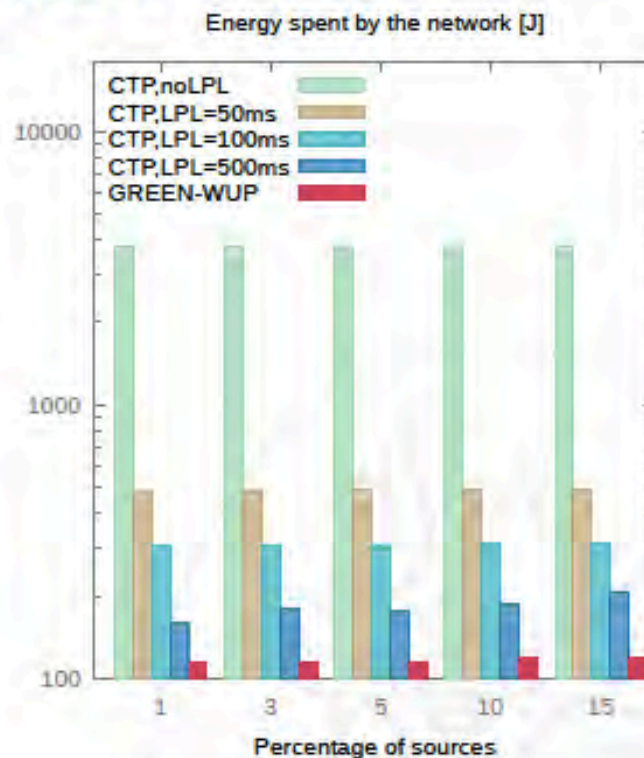
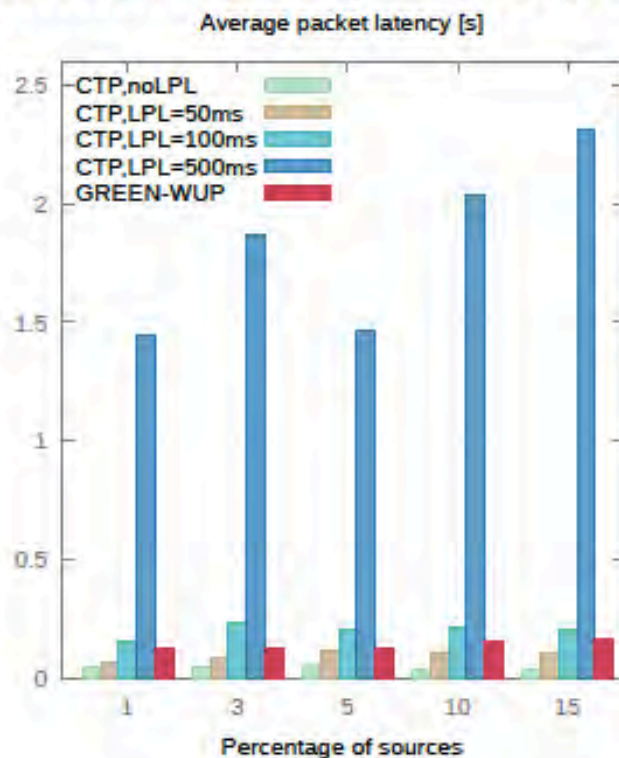
FLOOD-WUP, 100-450 nodes



Coverage time similar to Flooding with 100% DC
Energy consumption reduced of up to $\approx 96\%$
vs Flooding10%: -24x coverage time, -8x energy



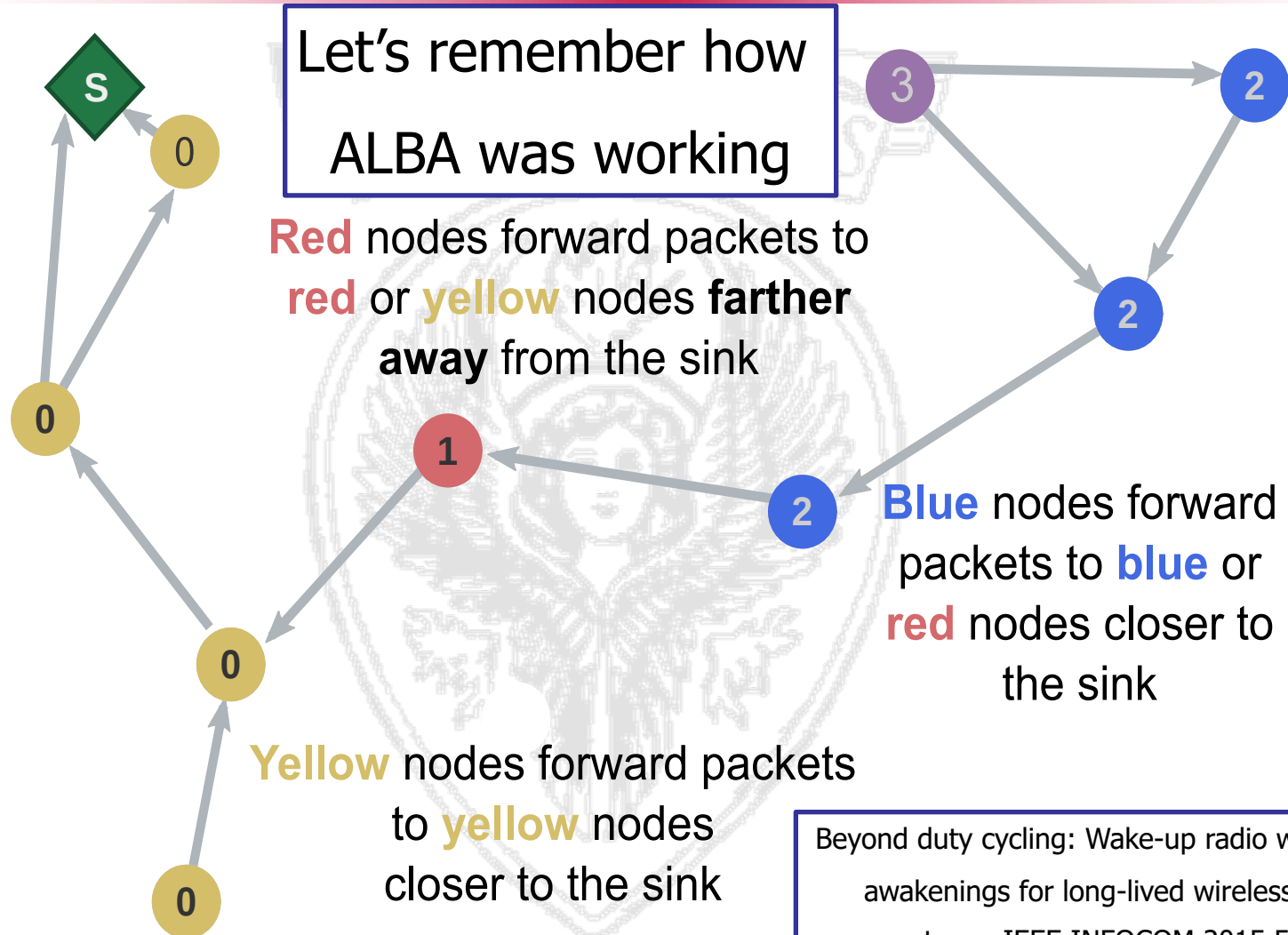
GREEN-WUP, network of 100 nodes



Average latency 100 ms higher than CTP without LPL

Energy consumption reduced of up to $\approx 33\times$!

vs CTP+LPL=500ms: latency -16x, -45% energy



Beyond duty cycling: Wake-up radio with selective awakenings for long-lived wireless sensing systems. IEEE INFOCOM 2015 522-530



- ALBA-R: The best relay is selected among the nodes that are awake
- ALBA-WUR: We wake up **good** potential relays when we need them
- **Semantic addressing**: WUR addresses reflect fundamental parameters—color, available queue space and QPI



- When a node has a packet to send, it wakes up only good potential relay

Color = Red	Burst size = 2	Target QPI = 1
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- Each node maintains a pool of WUR addresses, each corresponding to a request it can serve
- GPI is taken into account when answering to WUR requests



- Receiver:

- Color: Red; queue occupancy: 1 (of 3); moving average of recent transmissions: 2, and maximum number of packets that can be sent in a burst: 2

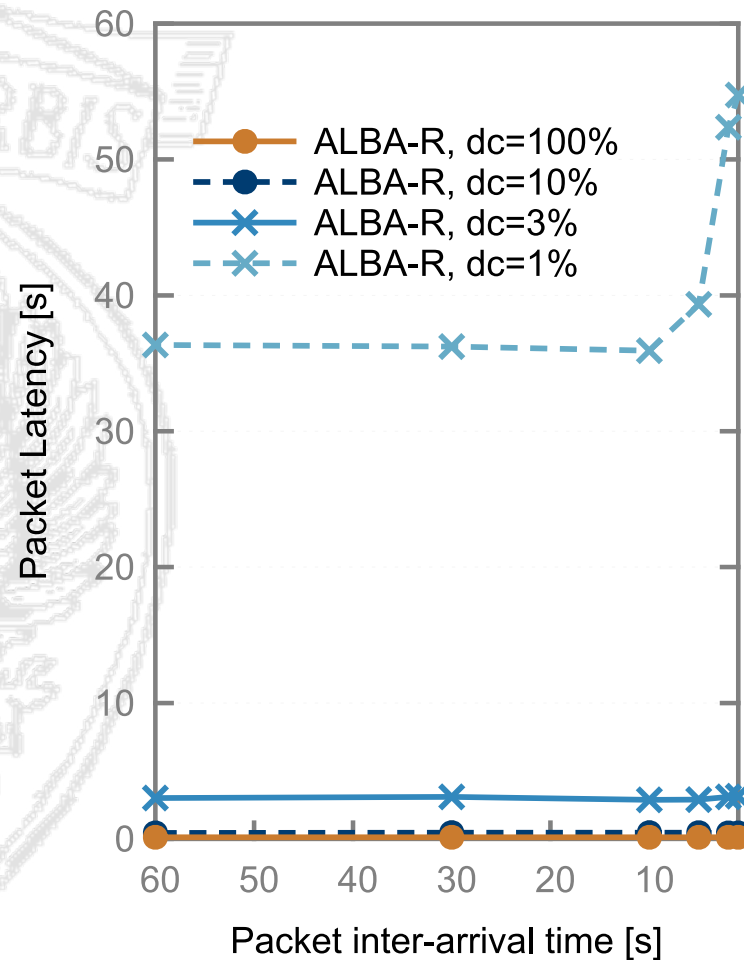
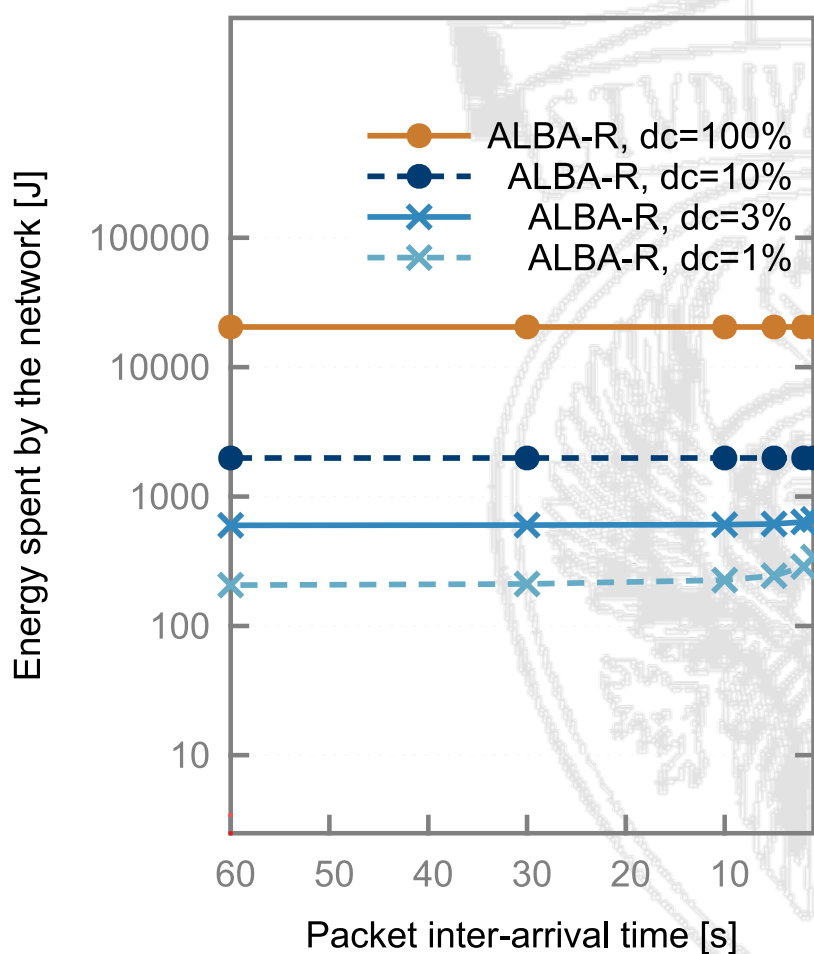
Color = Red	Burst Size = 1	QPI = 1
Color = Red	Burst Size = 2	QPI = 2
Color = Blue	Burst Size = 1	QPI = 1
Color = Blue	Burst Size = 2	QPI = 2

- Sender:

Color = Blue	Burst size = 1	Target QPI = 1
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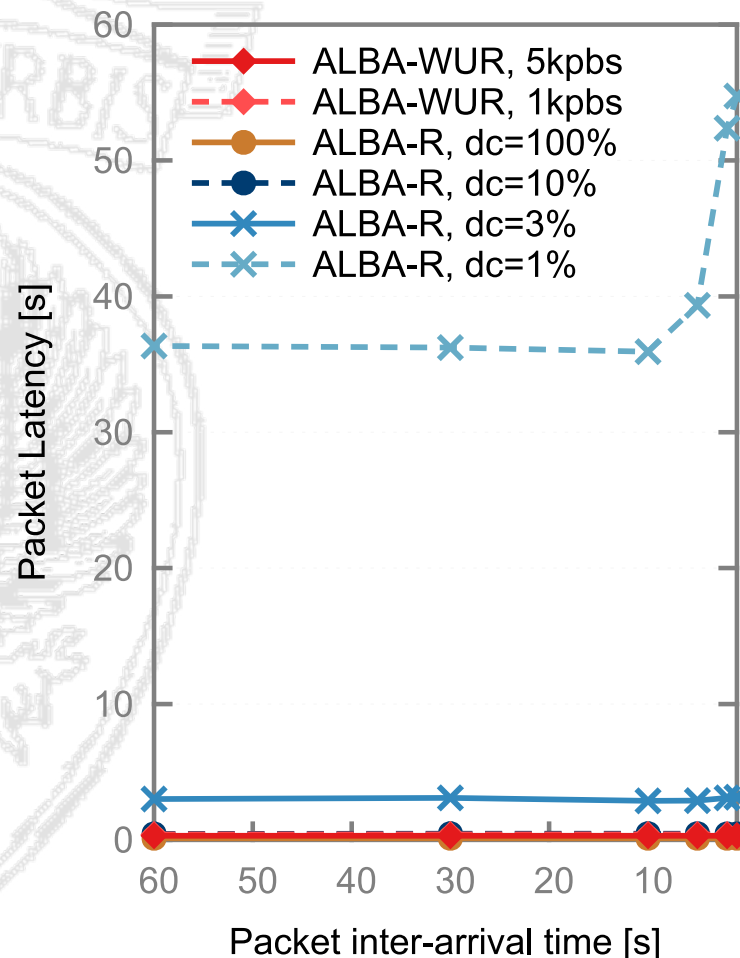
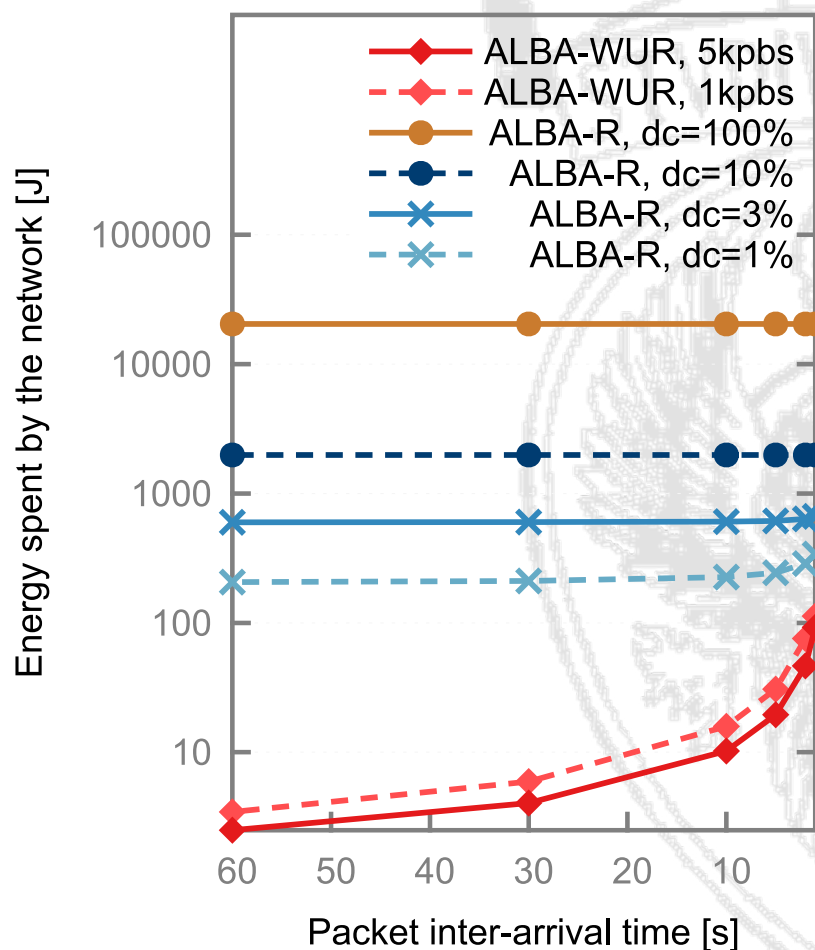


- Simulation framework: Green Castalia
- Developed extensions: MagoNode, WUR, module, WTx module
- Realistic energy and WUR models based on actual measurements and experiments
- Comparison with ALBA-R with duty cycles: 100%, 10%, 3%, 1%
- 120 nodes distributed randomly and uniformly over a 200x200m field
- Data traffic: λ packets per second (Poisson process)



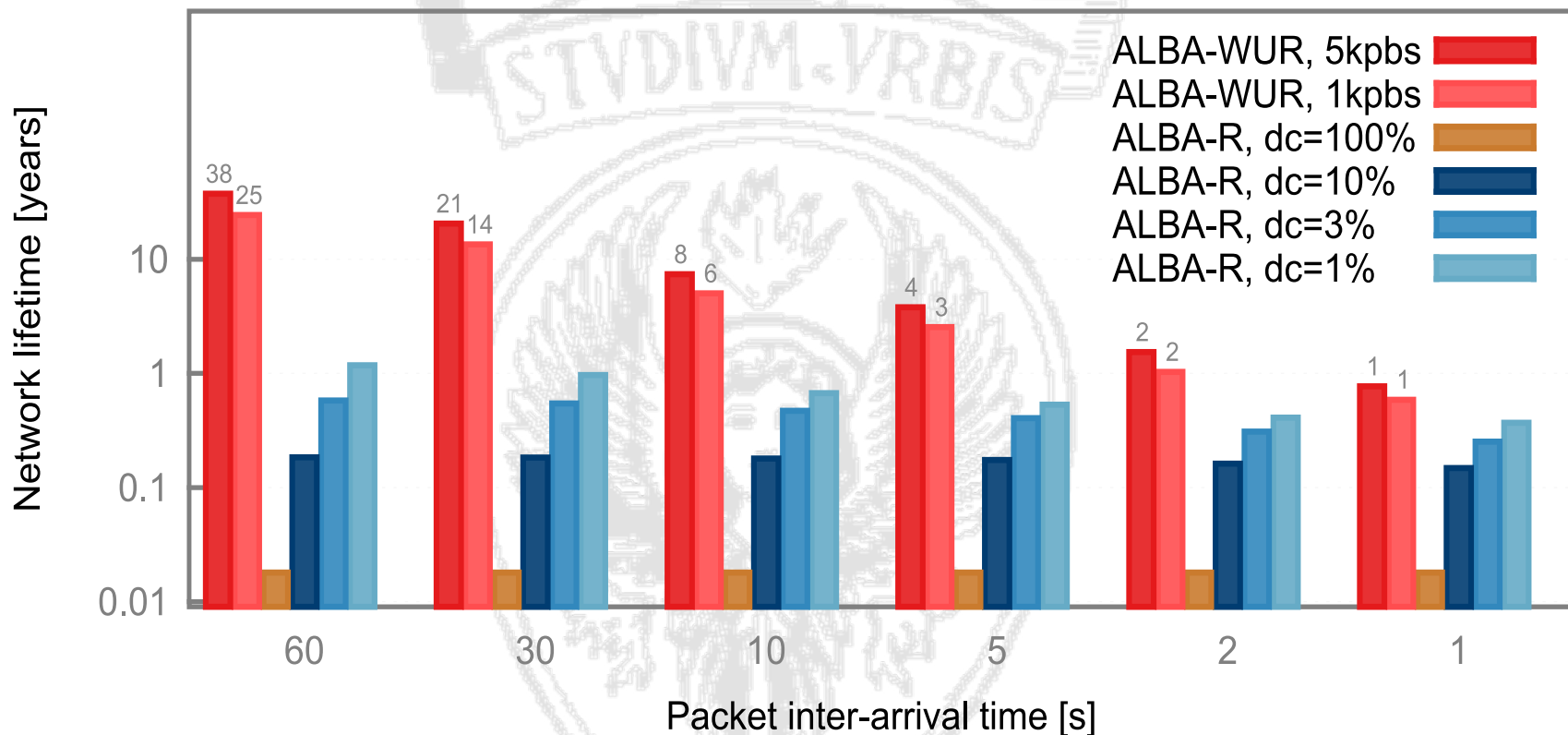


ALBA-WUR vs. ALBA-R: Energy Consumption and Latency





- Energy consumption reduced by up to **three** orders of magnitude
- Latency comparable to that of ALBA-R with 100% duty cycle



- Lifetime of **several decades!**
- Network with 1% duty cycle and **no traffic** = less than 2 years



- For applications (shorter range/dense deployments) in which wake up radio enabled sensor networks can be adopted WUP-WSNs allow to achieve very long lasting networks at the same time allowing real-time data communications.
- Wake up radio with semantic addresses: Paradigm shift introduced by our recent works
 - + Opens up a lot of research directions
 - + much still to investigate
 - Technology still under development
- Best students in the class could join the group of PhD and master students working on this research@SENSES!