



# System Performance Evaluation

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# System Performance Evaluation



# System Performance Evaluation



- Allows to obtain the highest performance at the lowest cost.
- Allows performance comparison of a number of alternative designs/solutions to find the best one.
- Gives good insights on how well a system is performing and whether any improvements need to be made.
  - Useful at any stage of the system's life cycle, i.e., design, manufacturing, use, upgrade, etc..



# A systematic approach



- Most performance problems are unique.
- Evaluation techniques used for one problem generally cannot be used for a different problem.
- Steps common to all performance evaluation projects:
  1. State goals and define the system under evaluation
    - Define the boundaries of the system.



# A systematic approach



## 2. List services and outcomes

- Each system provides a set of services
- E.g., A computer network allows its users to send packets to specified destinations
- A list of services and possible outcomes is useful in selecting the right metrics and workloads.

## 3. Select metrics

- Select the criteria(metrics) to compare the performance
- E.g., delay, accuracy, speed etc..





# A systematic approach



4. List of parameters that affect the performance
  - System parameters (hardware and software)
  - Workload parameters (depend on users' requests)
5. Select factors to study
  - Some parameters will be varied during the simulation (factors) and will get different values (levels)
6. Select evaluation technique
  - Analytical modeling
  - Simulation
  - Real test-bed



# A systematic approach



## 7. Select Workload

- A list of service requests to the system
- Analytical modeling: A probability of various requests
- Simulation: Trace of requests measured on a real system
- Test-bed: Scripts to be executed on the system.

## 8. Design Experiments

- Decide on a sequence of experiments that offer maximum information with minimal effort
- Varying number of factors and levels to determine their relative effect.



# A systematic approach



## 9. Analyze and Interpret Data

- The analysis produces results (not conclusions)
- Each repetition of an experiment gives has a different outcome.

## 10. Present results

- They should be presented in a manner that is easily understood, e.g., in a graph form
- If it is needed, redefine system boundaries, included other factors and performance metrics...(several cycles).





# Selecting an evaluation technique



Criterion	Analytical modeling	Simulation	Measurement
Stage	Any	Any	Postprototype
Time required	Small	Medium	Varies
Tools	Analysts	Computer Languages	Instrumentation
Accuracy <sup>a</sup>	Low	Moderate	Varies
Trade-off evaluation	Easy	Moderate	Difficult
Cost	Small	Medium	High
Scalability	Low	Medium	High

<sup>a</sup> In all cases, result may be misleading or wrong.

# Selecting an evaluation technique



- Three rules of validation:
  1. Do not trust the results of a simulation model until they have been validated by analytical modeling or measurements.
  2. Do not trust the results of an analytical model until they have been validated by a simulation model or measurements.
  3. Do not trust the results of a measurement until they have been validated by simulation or analytical modeling.



# Selecting performance metrics

- For each performance study, a set of performance criteria must be chosen.
- Time to execute a task
  - Execution time, response time, latency
- Number of tasks per day, hour, sec, ns, etc.
  - Throughput, bandwidth.



Aircraft	DC to Paris	Speed (mph)	Passengers	Throughput (pmph)
Boeing 747	6.5 hours	610	470	286,700
Concorde	3 hours	1350	132	178,200

# Selecting performance metrics

- Flight time of Concorde vs. Boeing 747?
  - Concorde:  $1350 \text{ mph} / 610 \text{ mph} = 2.2$  times faster  
 $= 6.5 \text{ hours} / 3 \text{ hours}$
- Concorde is 2.2 times («120%») faster in terms of flight time.



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 $= 6.5 \text{ hours} / 3 \text{ hours}$
  - Concorde is 2.2 times (120%) faster in terms of flight time.
- Throughput = profit per passenger = speed per passenger (pmph)
  - Boeing 747 = 286,700 pmph
  - Concorde = 178,200 pmph
    - Boeing 747 produces  $286,700 \text{ pmph} / 178,200 \text{ pmph} = 1.6$  times (60%) more profit in terms of throughput.



# Selecting performance metrics



- Global metrics: Reflect the systemwide utility
  - Resource utilization, reliability, availability.
- Individual metrics: Reflect the utility of each single user
  - Response time, throughput.
- There are cases when the decision that optimizes individual metrics is different from the one that optimizes the system metric.





# Selecting performance metrics



- E.g.: Total vs. per node throughput
  - Keep the system throughput constant while increasing the number of packets from one source may lead to increasing its throughput, but it may also decrease someone's else throughput.
- Using only the system throughput or the individual throughput may lead to unfair situations.



# Selecting performance metrics



1. Low variability: Reduce the number of repetitions required to obtain a given level of statistical confidence.
2. Nonredundancy: Similar metrics should be avoided.
3. Completeness: All possible outcomes should be reflected in the set of performance metrics.

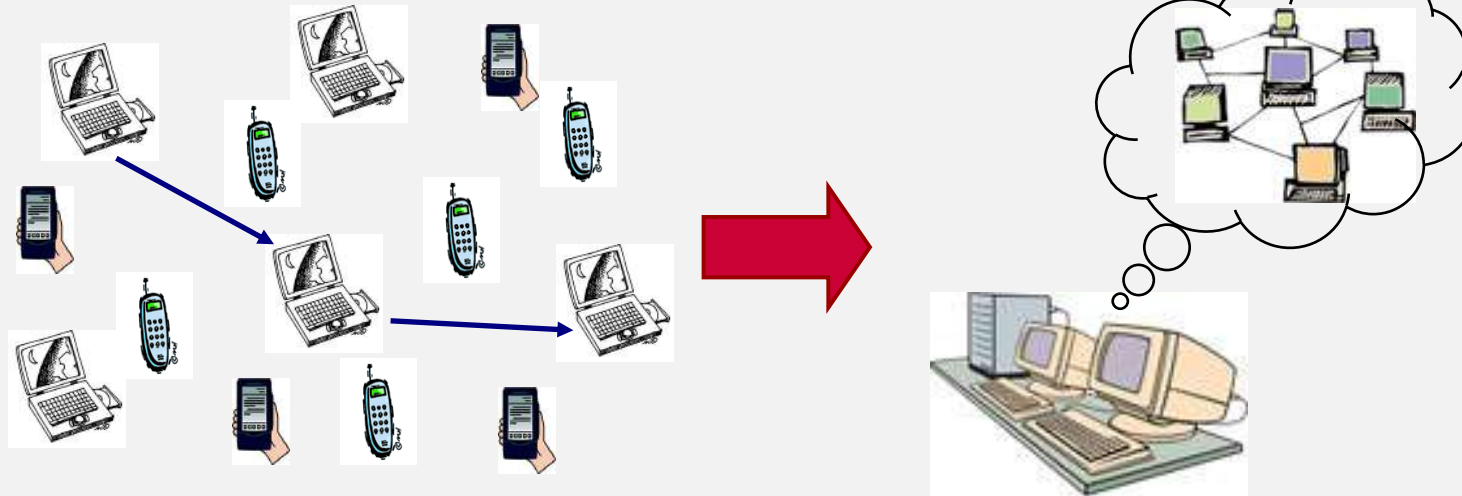




# Introduction to Simulation



# Introduction to Simulation



- What is a network simulator?
  - A software for modeling network applications and protocols (wired and wireless).
  - What is it used for?
    - Rebuilding a system that evolves like the real system according to certain aspects, based on a model.

# Simulation: When to use it

- Study and experimentation of the internal interactions of a complex system.
- System performance evaluation before the prototype.
- Verify analytical solutions.
- Common approach in research:
  - Design of new protocols
  - Comparison of protocols
  - Traffic analysis



# Simulation: Why to use it



- Only one workstation is enough to run simulations.
- Allows the study of a wide range of scenarios in a relatively short time.
- Allows realization of complex and expensive networks to be implemented in a real test-bed.
- Easy to test/check the impact of changes in a simulated solution.





# Simulation: Pros & Cons



- Pros

- System verification before the production of a prototype
- Easy debugging of the simulated protocol
- Possibility to analyze the system's scalability
- Identification of system vulnerabilities
- Flexibility on studying the behavior of the system.

- Cons

- The design/implementation of a model and its validation require the understanding of the simulation tool.
- It is not always possible to capture the various aspects of the simulated system.



# Simulation: Terminology



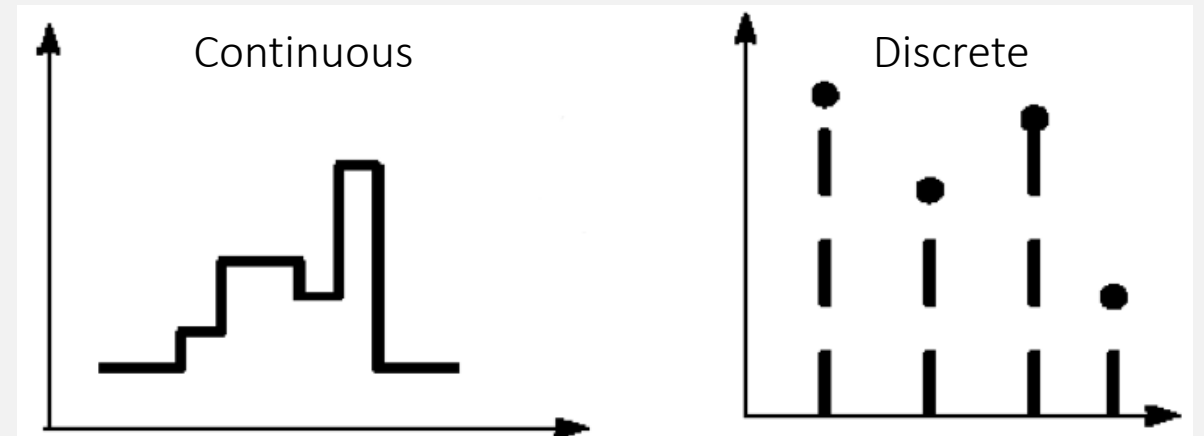
- **State variables:**
  - The variables whose values define the state of the system
  - Network simulation: number of nodes, packet queue, mac and routing protocols used etc..
- **Event:**
  - A change in the system state.
    - Network simulation: packet transmission, packet reception etc..



# Simulation: Terminology

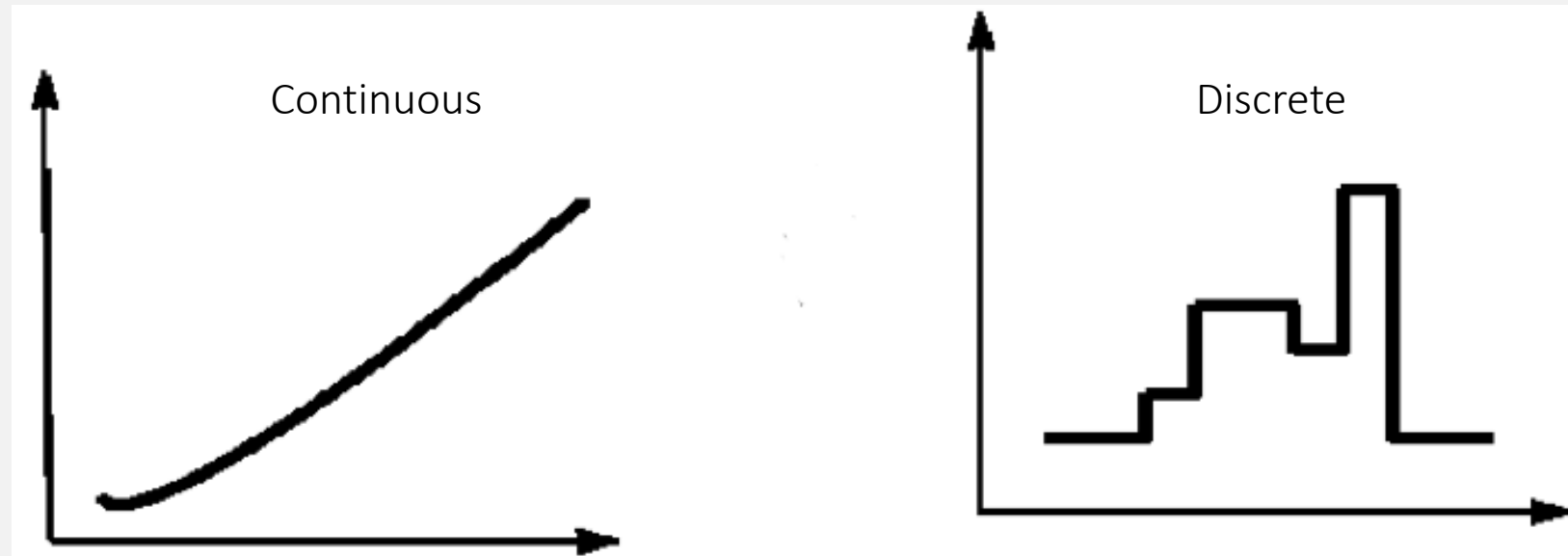


- Continuous-Time and Discrete-Time models:
  - *Continuous time model*: A model in which the system state is defined at all times.
    - Network simulation: number of nodes, communication among nodes is defined at any time.
  - *Discrete-Time model*: The system state is defined only at particular instants in time.
    - Classes: weekly



# Simulation: Terminology

- Continuous-State and Discrete-State models:
  - *Continuous*: State variables are continuous.
  - *Discrete*: State variables are discrete.
    - Network simulation: number of nodes, packet queue length.



# Simulation: Terminology



- Continuous-state models = Continuous-event models
- Discrete-state models = Discrete-event models
- **Continuity of time does not imply continuity of state and vice versa!**
- Four possible combinations:
  1. Continuous state/continuous time
  2. Discrete state/discrete time
  3. Continuous state/discrete time
  4. Discrete state/continuous time



# Simulation: Terminology



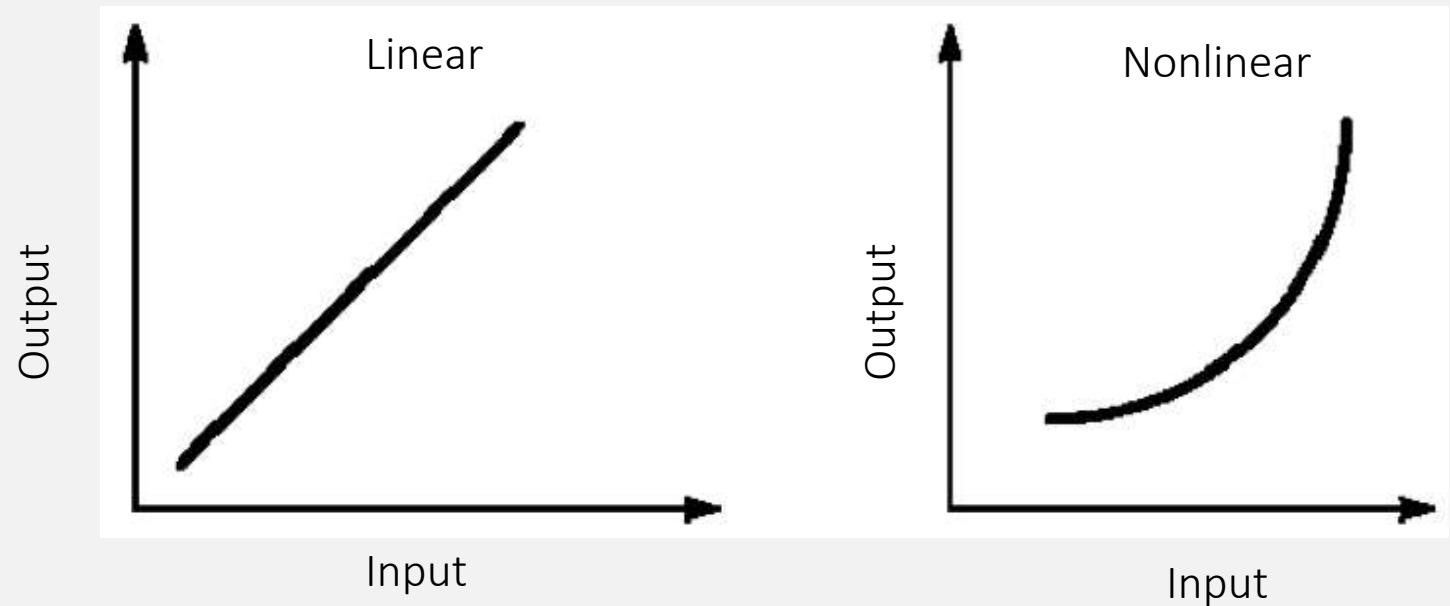
- **Deterministic and Probabilistic models:**
  - *Deterministic:* The output (results) of a model can be predicted with certainty.
  - *Probabilistic:* For the same set on input parameters, each repetition gives a different output.
- **Static and Dynamic models:**
  - *Static:* Time is not a variable.
  - *Dynamic:* The system state changes with time.
- **Open and Closed models:**
  - *Open:* The input is external to the model and is independent of it.
  - *Closed:* No external input.





# Simulation: Terminology

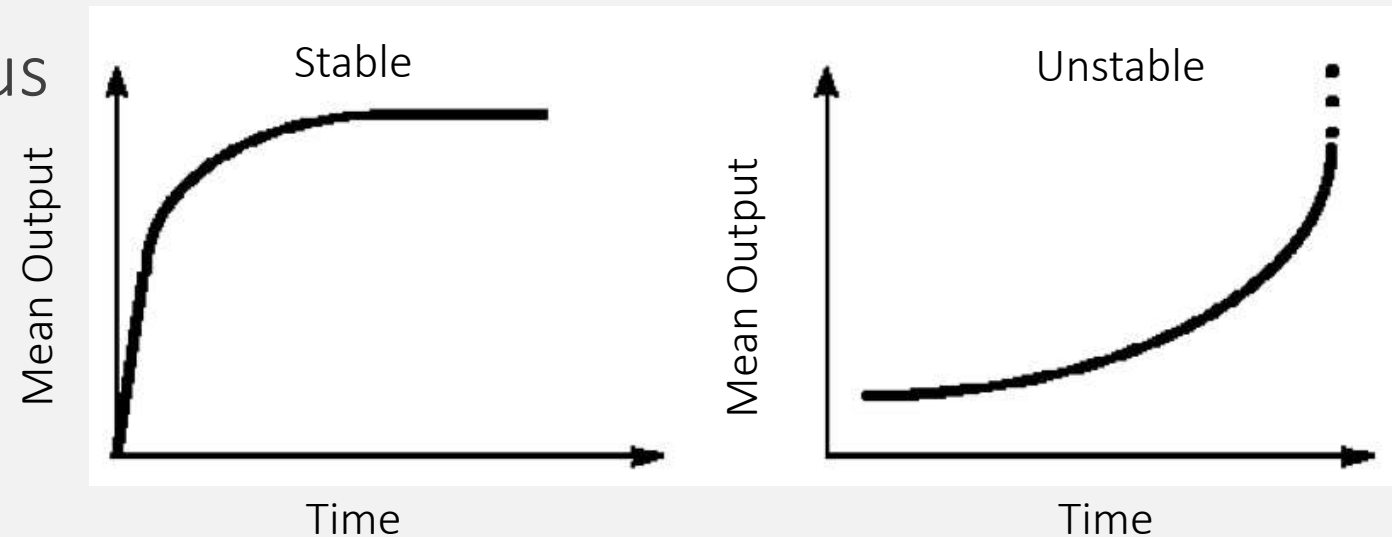
- Linear and Nonlinear models:
  - *Linear*: The output parameters are a linear function of the input parameter.
  - *Nonlinear*: Otherwise.



**Computer system models:** tempo continuo, stato discreto, probabilistico, dinamico e non lineare. Aperti o chiusi, stabili o instabili.

# Simulation: Terminology

- Stable and Unstable models:
  - *Stable*: The dynamic behavior of the model settles down to a steady state.
  - *Unstable*: The behavior of the model is continuous changing.



**Computer system models:** tempo continuo, stato discreto, probabilistico, dinamico e non lineare. Aperti o chiusi, stabili o instabili.

# Simulation: Types



- **Model Carlo method:**
  - Static simulation without a time axis.
  - Model probabilistic phenomena that do not change characteristics with time.
- **Trace-driven:**
  - The simulation uses a trace as its input (a time-ordered record of events on a real system.)
- **Discrete-event:**
  - Discrete-state model of system.
    - Network simulation: number of packets in the queue.
    - Discrete- or continuous-time values.



# Discrete-event Simulation



- Components:
  1. *Event scheduler*: It keeps a linked list of events waiting to happen.
  2. *Simulation clock*: Each simulation has a global variable representing simulated time.
    - The scheduler is responsible for advancing this time.
      - ***Unit time***: Increments time by small increment and then checks to see if there are any events that can occur.
      - ***Event-driven***: Increments the time automatically to the time of the next earliest occurring time.



# Discrete-event Simulation



- Components:
  3. *Event routine*: Each event is simulated by its routine.
  4. *Input routines*: Get the model parameters.
  5. *Initialization routines*: Set the initial state of the system.
  6. *Trace routines*: Print out intermediate variables as the simulation proceeds; Useful on debugging.
  7. *Report generator*: Output routines executed at the end of the simulation; Calculate the final result.
  8. *Main program*: It brings all the routines together.



# Common mistakes



1. Inappropriate level of detail
  - More details => Longer simulations => More bugs => More computations => More parameters  $\neq$  Higher accuracy
2. Inappropriate experimental design
  - Too much generic => longer simulations and less accurate
3. Unverified models
  - Bugs in the code
4. Invalid models
  - Non realistic results





# Common mistakes



5. Improperly handled initial conditions
  - Generally not representative of the system behavior in a steady state.
6. Too short simulations
7. Poor random-number generators
8. Improper selection of seeds
  - The seed for different random-number streams should be carefully chosen to maintain independence among the streams.



# Model Verification and Validation



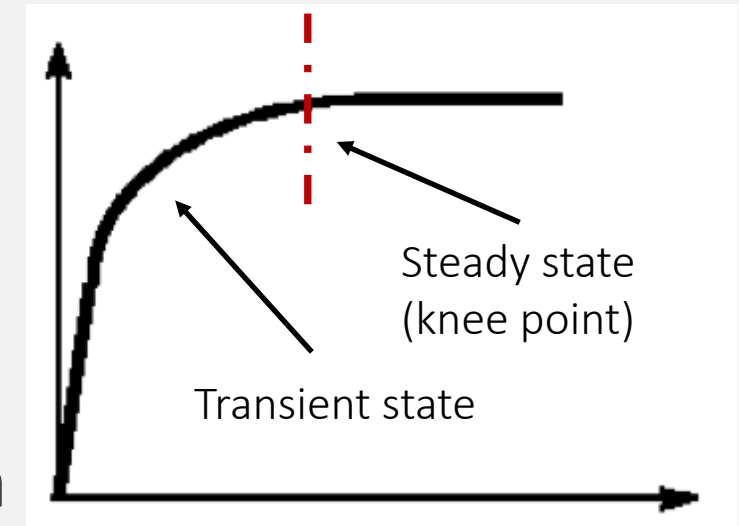
1. **Antibugging:** Include additional checks and output in the program that will point out the bugs (if any).
  - E.g. 1: Check if the probabilities for certain events add up to 1.
  - E.g. 2: Packets received = pkts generated – pkts lost/dropped.
2. **Structured walk-through:** Explain the code to another person or a group. (It works even when the others do not understand the model!).
3. **Run simplified cases:** Easy to analyze them.
4. **Consistency test:** Check that the model produces similar results for input parameter values that have similar effects.
5. **Degeneracy test:** Check that the model works for extreme values of system configuration or workload parameters.



# Simulation Results Analysis

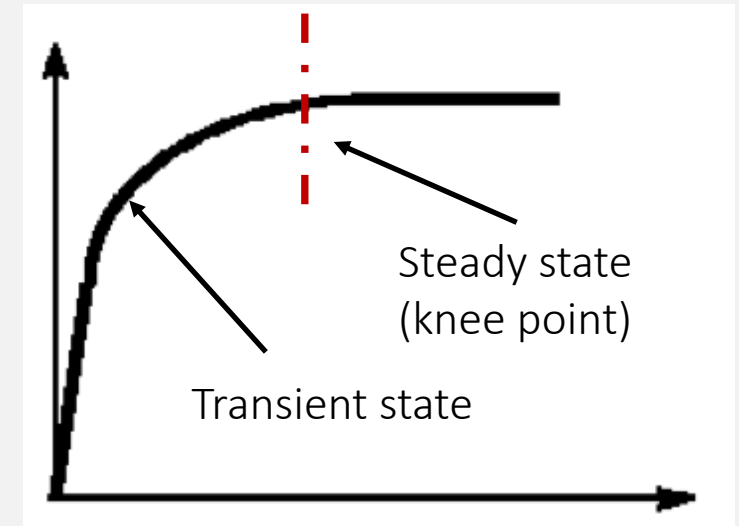


- In most simulations, only the **steady-state** performance is of interest!
- Results of the initial part of the simulation should not be included in the final computations.
- **Transient removal:** Identify the end of the transient state.
  - It is not possible to define exactly what constitutes the transient state and when the transient state ends.
  - All methods for transient removal are heuristic.



# Simulation Results Analysis

- Six methods for transient removal:
  1. Long runs
  2. Proper initialization
  3. Truncation
  4. Initial data deletion
  5. Moving average of independent replications
  6. Batch means



# Terminating Simulations



- Short simulations => low degree confidence
- Long simulations => waste of resources
- There are systems that never reach a steady-state performance.
  - These systems always operate under transient conditions.
  - Such simulations are called **terminating simulations**; they do not require transient removal.
  - E.g.: A system shuts down at 5pm every day.
- To increase data confidence take the average over several independent repetitions.

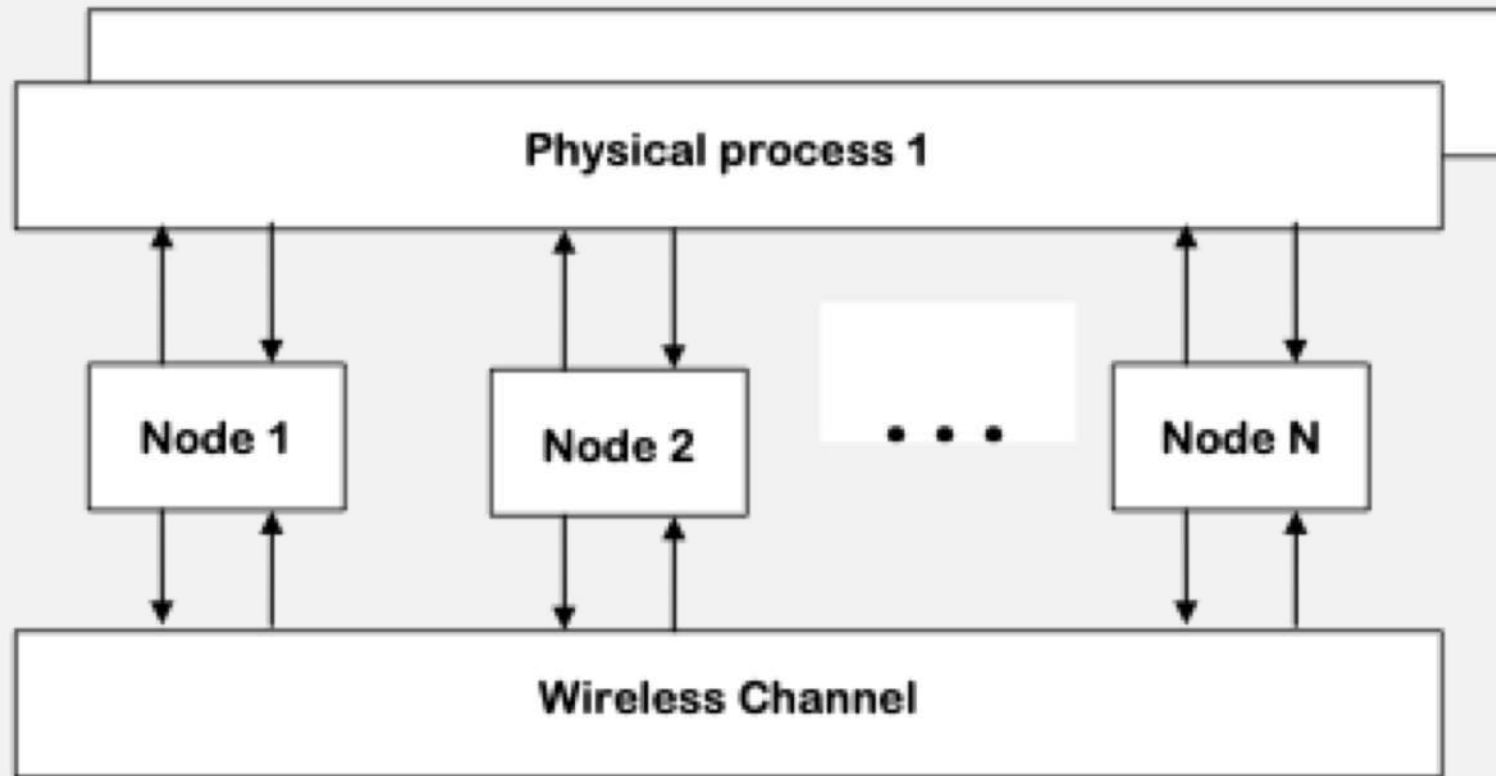




# GreenCastalia: An energy harvesting-enabled simulator for IoT (Cont.)

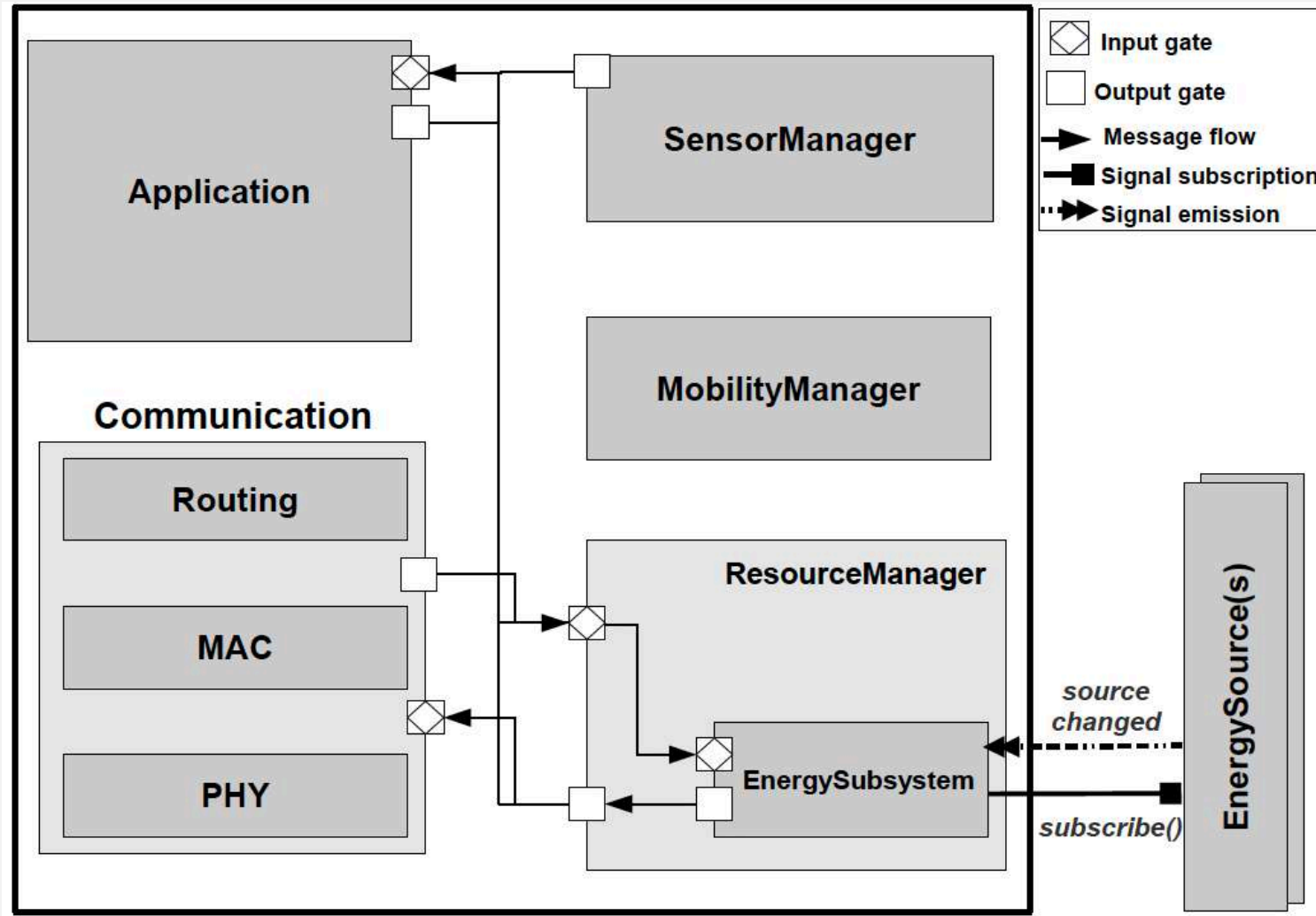


# GreenCastalia Structure





# SensorNode module



# Modeling in GC



- Different aspects of a wireless sensor network from communications to physical processes.
- Single common point for all non-composite modules:
  - A parameter called `collectTraceInfo`
  - Is set by default to false; If set to true, then the module will produce trace information
  - Traces will be written in the `Castalia-Trace.txt` file (in the directory of the simulation scenario folder)



# The wireless channel



- GC implements a realistic wireless channel for IoT systems, such as WSNs and BANs.
- Average path loss modeling
  - Lognormal shadowing model has been shown to give accurate estimates.
- Path loss in dB as a function of the distance between two nodes



$$PL(d) = PL(d_0) + 10 \cdot \eta \cdot \log\left(\frac{d}{d_0}\right) + X_\sigma$$

# The wireless channel



- Directory:  
`~/Castalia/src/wirelessChannel/defaultChannel/`
- File `WirelessChannel.ned`:
  - Defines parameters related to the wireless channel
  - `pathLossExponent`, `PLd0`, `d0`, `sigma`
- To access these parameters in the .ini file you have to prefix their name with “`SN.wirelessChannel.`”



# Node mobility



- Taking the path loss between two nodes is not enough.
- Keep state about the path losses between points in the space.
- Space is broken in discrete cells and calculate the path losses from each cell to each other cell.
- Use cell locations and cell IDs instead of specific node locations and node IDs.



# Node mobility



- Parameters that set the cell size (default=5m)
  - `SN.wirelessChannel.xCellSize`
  - `SN.wirelessChannel.yCellSize`
  - `SN.wirelessChannel.zCellSize`
- No mobility
  - `SN.wirelessChannel.onlyStaticNodes`



# The radio module



- Captures many features for real low-power radios.
- Main features include:
  - Multiple states: Transmit, receive, listen, configurable sleep states.
  - Transition delays from one state to another.
  - Different power consumption for the different states and Tx levels used.
  - ...
  - GC includes 3 already defined radios.





# The radio module



- Directory: `~/Simulations/Parameters/Radio/`
- Available radios
  - `BANRadio.txt`: defines the narrowband radio proposed in the IEEE 802.15 Task Group 6 documents
  - `CC1000.txt`: defines the CC1000 real radio by Texas Instruments
  - `CC2420.txt`: defines the CC2420 real radio by Texas Instruments
- In the `omnetpp.ini` file the parameter `RadioParametersFile` of the radio module points to one of these files.



# The radio module

- Directory
  - ~ / Simulations / Parameters / Radio /
- E.g.: CC2420.txt
- Radio parameters file
  - RX MODES
  - TX LEVELS
  - DELAY TRANSITION MATRIX
  - POWER TRANSITION MATRIX
  - SLEEP LEVELS



# The radio module



- A set of parameters can be specified in the configuration file
- Select the starting RX mode; default empty value means that the first mode listed will be used: `string mode = default ("")`
- Select the starting state once simulation begins; default value is set to listening (receiving) state: `string state = default ("RX")`
- Starting transmission output power level; only levels declared in the radio parameter file can be used; default empty value means that the highest value will be used:  
`string TxOutputPower = default ("")`

# Creating modules



- Determine the correct location for the new code.
- Create a dedicated directory for the source code of the new module.
- Possible locations:
  - Application: `~/Castalia/src/node/application`
  - Routing: `~/Castalia/src/node/communication/routing`
  - MAC: `~/Castalia/src/node/communication/mac`
  - Mobility:  
`~/Castalia/src/node/communication/mobilityManager`

# Creating modules

- Define the module using the NED language; the `.ned` file is named by the name of the module:
  - E.g.: new module: `newCastaliaModule`
- Then the name of the corresponding `.ned` file will be `NewCastaliaModule.ned`
- The dedicated directory starts with a lower case letter, while the name of the `.ned` file starts with an upper case letter.



# Creating modules



- In the `.ned` file define the following:
  - The package of the module
  - Obtain the package by taking the current directory path to the Castalia's `src/` directory and by replacing each `"/"` symbol with `."`
- Include all the parameters to be passed to the module at runtime from the simulation configuration; Some parameters are mandatory for all modules.



# Creating modules: An example

```
package node.communication.mac.newCastaliaModule;
simple NewCastaliaModule like node.communication.mac.iMac {
parameters:
bool collectTraceInfo = default(false);
int macMaxPacketSize = default(0);
int macBufferSize = default(16);
int macPacketOverhead = default(8);
int newParameter1;
string newParameter2 = default("default value");
bool newParameter3 = default(false);
gates:
output toNetworkModule;
output toRadioModule;
input fromNetworkModule;
input fromRadioModule;
input fromCommModuleResourceMgr;
}
```

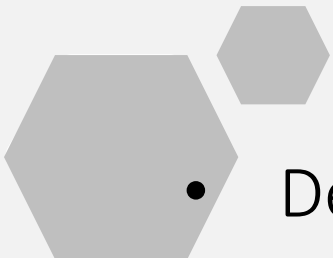




# Creating modules



- The next step is to include (and write in C++) the actual code of the module.
- The new module has to inherit some "properties" from appropriate base classes that are provided (Virtual classes).
- A .h file and a .cc file have to be created.
- In the source code file (.cc)
  - Include the .h file
  - Register the new creating as an OMNeT module
    - `Define_Module(NewCastaliaModule);`
  - Define the methods that the virtual class implements.



# Creating modules



- Application:

```
class NewCastaliaModule : public VirtualApplication{
```

- Routing:

```
class NewCastaliaModule : public VirtualRouting{
```

- MAC:

```
class NewCastaliaModule : public VirtualMac{
```

- MobilityManager:

```
class NewCastaliaModule : public VirtualMobilityManager{
```



# Defining an application packet



- Default application packets have only one field (double) to carry data.
- Create a new .msg file in the new application directory

```
cplusplus {{
#include "ApplicationPacket_m.h"
}}
class ApplicationPacket;
struct info {
unsigned short nodeID; //the ID of the Node
double locX; // x-coordinate of the node
double locY; // y-coordinate of the node
}
packet MyPacket extends ApplicationPacket {
info extraData;
}
```



# Defining a new Routing module



- Directory: `~/src/node/communication/routing`
- The VirtualRouting class defines a set of methods
  - Callback methods: Allow the specific routing protocol to react to certain events.
  - Pre-defined methods that perform generic operations.

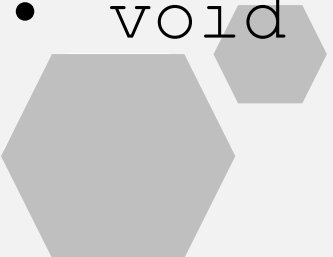


# Defining a new Routing module



## Callbacks:

- `void startup()`
- `void finishSpecific()`
- `void fromApplication Layer(cPacket *pkt, const char*dstAddr)`
- `void fromMacLayer(cPacket *pkt, int srcMacAddress, double RSSI, double LQI)`
- `void handleNetworkControlCommand(cMessage *)`
- `void handleMacControlMessage(cMessage *)`
- `void handleRadioControlMessage(cMessage *)`



# Defining a new Routing module

## Methods:

- `void encapsulatePacket(cPacket *, cPacket *)`
- `int bufferPacket(cPacket *pkt)`
- `cPacket *decapsulatePacket(cPacket *)`
- `void toApplicationLayer(cMessage *msg)`
- `void toMacLayer(cMessage *msg)`
- `void toMacLayer(cPacket *pkt, int macAddr)`
- `int resolveNetworkAddress(const char *)`
- `bool is NotDuplicatePacket(cPacket *pkt)`



# Additional Resources



- R. Jain, "*The Art of Computer Systems Performance Analysis: Techniques for Experimental Design, Measurement, Simulation, and Modeling*", Wiley-Interscience, New York, NY, April 1991. (Chapters 2, 3, 24)







Questions?