

IoT: lecture

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EPCglobal Class-1 Generation-2 Anti-collision Protocol

Anti-collision in most RFID Systems



- ■Use time division duplex (**TDD**) to implement the two way communication between **reader** and **tags**
- Adopt time division multiple access (**TDMA**) to simultaneously read the tags
- Anti-collision scheme becomes a strategy to solve the multiple-access problem
- Efficiency problems when the tag number is large





EPCglobal

- Non-profit standard organization working to commercialize the use of electronic product code (EPC)
- Developed a standard called EPCglobal Class-1 Generation-2 which:
 - Meets the performance for reading a dense tag number
 - Is an interrogator-talks-first (ITF) system operating in the 860 MHz-960 MHz frequency range (UHF)
 - Can support reading speed up to hundreds of tags per second





EPC Gen2 Anti-Collision Q-Algorithm



Q-Algorithm Overview

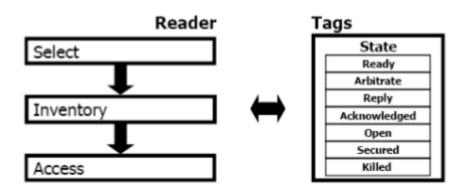
- Based on **Dynamic FSA** that allows readers to **adjust** frame length at any slotted time
- Improves performance when the number of tags is much less or much more than the frame length
- In literature there are different solutions to improved schema of the Q-Algorithm (more on this in the next slides)





Q-Algorithm Procedures

- Dynamic Frame Slotted ALOHA generates an adaptive frame size to the next reading round according to what happened in the previous one
- **Three** procedures which comprise one or more commands each:
 - Select
 - Inventory
 - Access



Q-Algorithm Select & Access



■ Select:

- An interrogator selects a tag population for inventory and access
- May do more select commands to grab the particular tag population

Access:

- An interrogator transacts with (reads from or writes to) the individual tags
- An individual tag with an EPC must be uniquely identified prior to access



Q-Algorithm Inventory (I)



Inventory:

- An interrogator identifies all tags to be accessed
- A round begins by transmitting a Query command (with a Q-value) to which one or more tags may reply
- The interrogator detects a single tag reply and identifies this single tag
- A series of Query commands is repeated for the possible backlog of tags
- Each inventory round includes **several time-slots**
 - The number of time-slots (frame size) is required to be determined by the DFSA



Q-Algorithm Inventory (II)



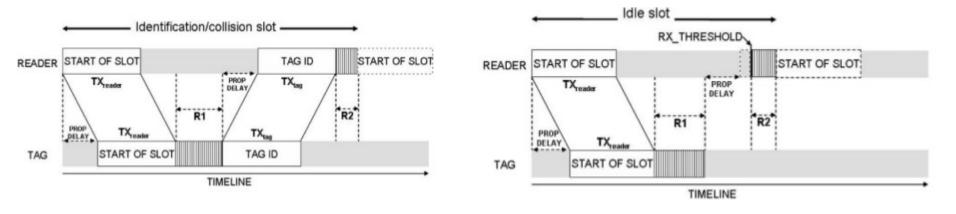
- After the Query command is sent with a **Q value** all the receiving tags generate a 16 bit random number (**RN16**) and get a random number from the last Q-bits of the RN16 \in [0, (2^Q)-1]
- ■The tags will count down their slot numbers under the control of the reader and send their own RN16 when the **counter decreases to 0**
- ■There are three possible outcomes for tag responses: single tag reply (**ACK** is sent to the tags), collided reply (**no response** is sent or **NACK** based on the chosen strategy), and no reply



Q-Algorithm Inventory (III)



■ Single tag reply: the acknowledged tag sends the Protocol Counter (PC), its EPC and the CRC16 (Cyclic Redundant Check) to the interrogator



■ **No reply**: the interrogator will realize this after some time T1+T2 whereupon the slot gets automatically closed



Q-Algorithm QueryRep & QueryAdj



- After a Query command, the interrogator typically sends one or more **QueryRep/QueryAdj** commands.
 - QueryRep repeats a previous query without changing any parameters
 - QueryAdj repeats a previous query and may increase or decrease the Q value by one → adjust the frame length at each time slot
- The interrogator maintains a floating-point parameter Q_{fp} and a constant C for the frame length adjustment





Q_{fp} and C adjustments (I)

Single identification slot:

- Q_{fp} remains unchanged
- If the round value Q_{fp} is different from the current Q value, the interrogator sends QueryAdj → too many idle or colliding slots

Collision slot:

Sum C to Q_{fp}

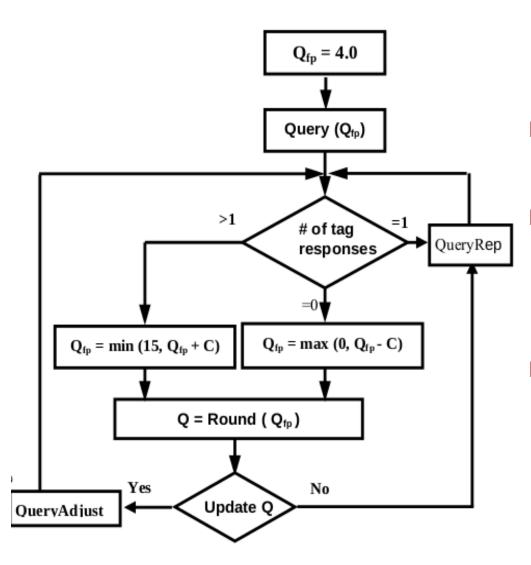
Idle slot:

Q_{fp} decreases by C



Q_{fp} and C adjustments (II)





- Typical values for C are between 0.1 and 0.5
- An interrogator adopts small values of C when Q is large and adopts large values of C when Q is small
- Optimal value C = 0.2





Chen and Kao's Q-Algorithm

Assumptions

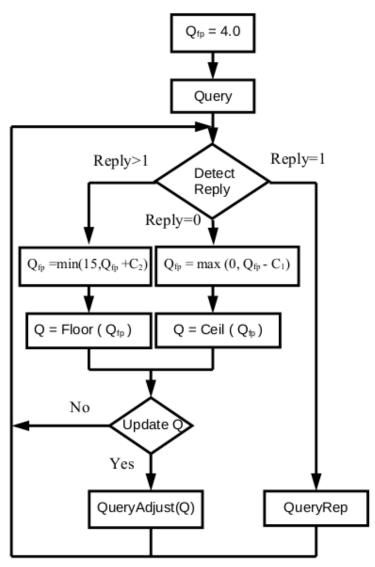


- Idle conditions occupy less time interval than the collided ones
- To speed up the read procedure for all tags, expect **more idle slots** than collision slots
 - The decrement of Q_{fp} should be less than its increment under the consideration of read performance
- Need of **different C** values (C_1 and C_2) for the adjustment of Q_{fp} value \rightarrow a new sch eme for the Q-algorithm is proposed
 - $0.1 < C_1 < C_2 < 0.5$
 - These two values effect on the total time spent in reading tags



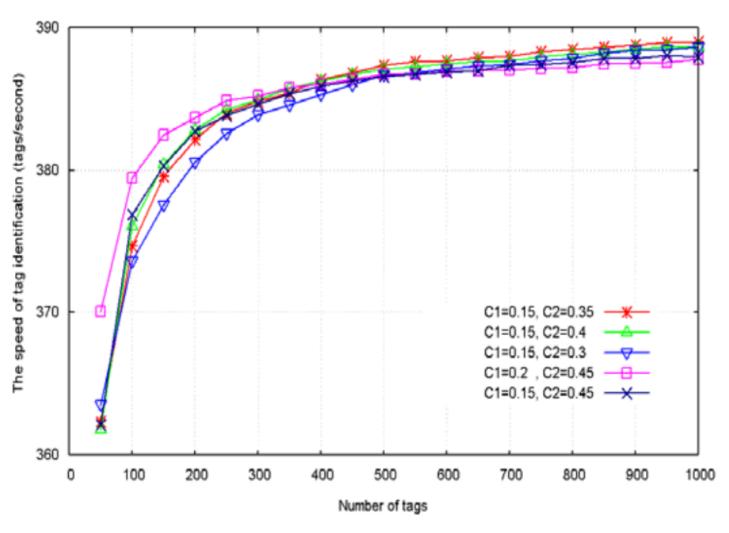
Modified Q-Algorithm flow





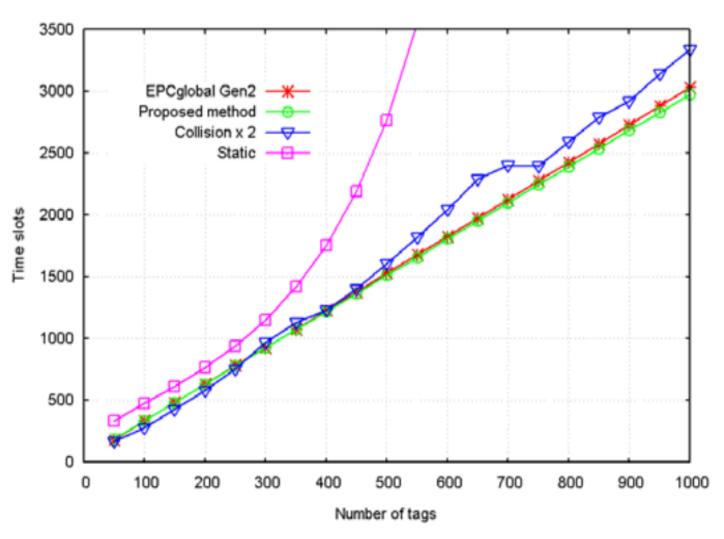
Tag identification speed





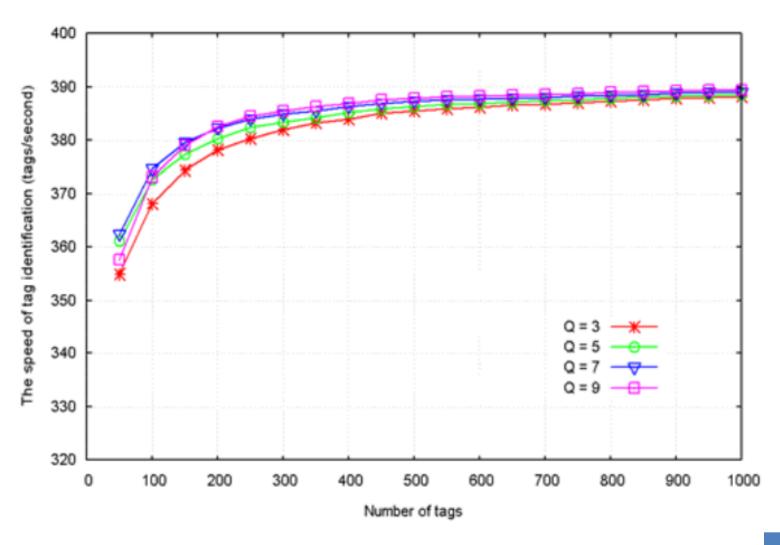
Time slot number for tag identification





2^Q-sized frame read speed effect





Readings



- W. T. Chen, W. B. Kao, A novel Q-algorithm for EPCglobal class-1 generation-2 anti-collision protocol, in World Academy of Science, Engineering and Technology, 78, 801-804, 2011.
- W. T. Chen, A New RFID Anti-collision Algorithm for the EPCglobal UHF Class-1 Generation-2 Standard, in UIC-ATC '12 Proceedings of the 2012 9th International Conference on Ubiquitous Intelligence and Computing and 9th International Conference on Autonomic and Trusted Computing, 811-815, September 2012.

