

Formal Methods in Software Development

Automata Theory and Model Checking

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Lesson 4a:

Regular Properties and Finite Automata

Non-Determ. Finite Automata

A **nondeterministic finite automata** (**NFA**) \mathcal{A} is a tuple $(\Sigma, Q, \delta, Q_0, F)$ where:

- Σ is the finite input **alphabet**
- Q is the finite set of **states**
- $\delta \subseteq Q \times \Sigma \times Q$ is the **transition relation**
- $Q_0 \subseteq Q$ is the set of **initial states**
- $F \subseteq Q$ is the set of **accepting states**

Let w be a word in Σ^* of length $|w| = n$.

A **run** over w is a finite sequence of states $q_0 q_1 \dots q_n$ such that $q_0 \in Q_0$ is an initial state and $(q_i, w_{i+1}, q_{i+1}) \in \delta$ for all $0 \leq i < n$.

A run is **accepting** if $q_n \in F$.

The automaton \mathcal{A} **accepts** w if **there exists** an accepting run over w

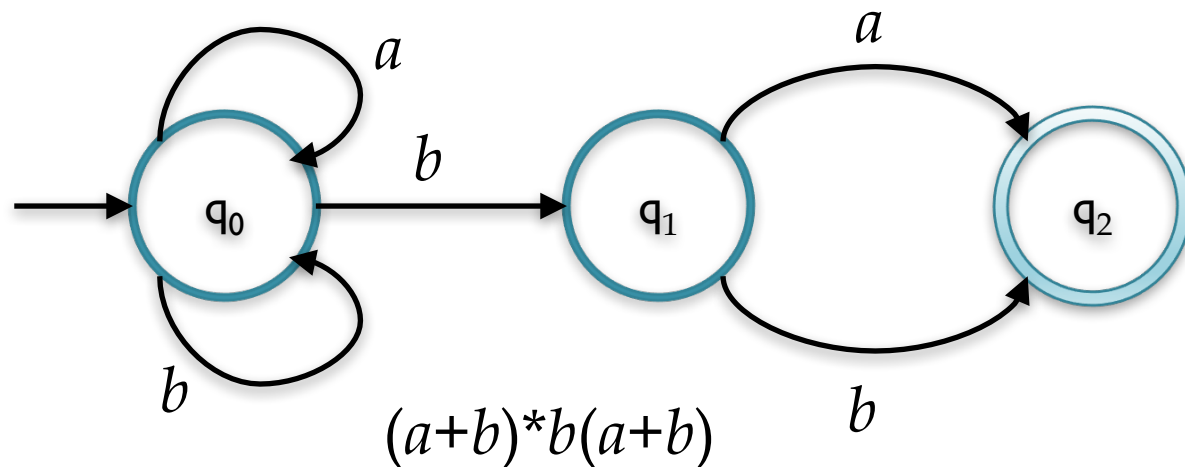
The **language** $\mathcal{L}(\mathcal{A}) \subseteq \Sigma^*$ consists of all words accepted by \mathcal{A} .

(Non-Det.) Finite Automata

An automaton \mathcal{A} is **deterministic** if δ is a **function** [for all states s and all symbols a there exists a **unique next state** $\delta(s, a)$] and there exists a **unique initial state** ($|\delta(s, a)| \leq 1$ and $|Q_0| = 1$).

For each non-deterministic automaton \mathcal{A} there exists an automaton \mathcal{A}' such that $\mathcal{L}(\mathcal{A}) = \mathcal{L}(\mathcal{A}')$. However, the size of \mathcal{A}' **can be exponential** w.r.t. the size of \mathcal{A} .

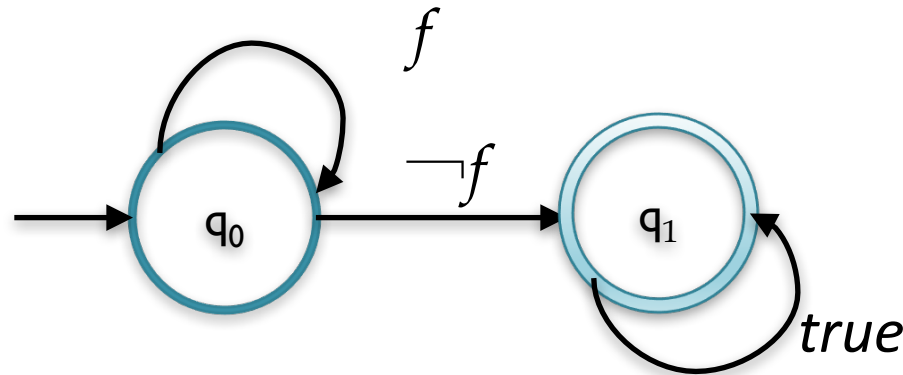
The class of languages accepted by finite automata is the class of **regular languages**, that can be characterized by **regular expressions**.



Regular Safety Properties (1)

Definition. A safety property P is **regular** if its **set of bad prefixes is a regular** language over 2^{AP} .

Example: Every **invariant is a regular property**. Let f be the invariant property. The language of bad prefixes is $f^*(\neg f)\text{true}^*$ (**we use a propositional formulas to identify subsets of AP**).

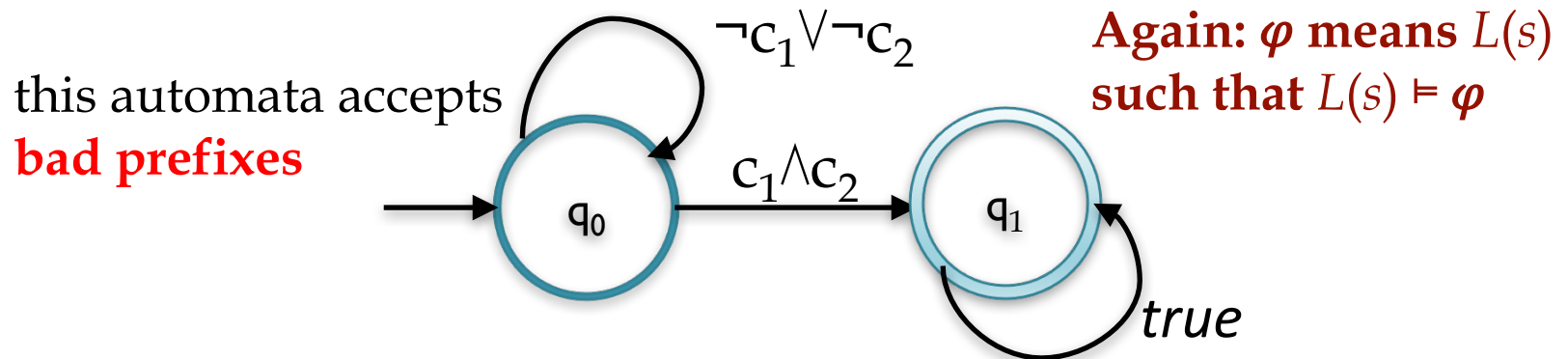


This automaton accepts words that **violates** the invariant f .

Remark: Here we assume f be a shorthand for $L(s) \models f$

Regular Safety Properties (2)

Example. The mutual exclusion property can be easily modeled by a NFA as follows:



If we remove the transition labeled *true*, this automaton accepts **minimal** bad prefixes of the mutual exclusion property (words that end at the first violation).

This is not incidental!

Theorem. A safety property P is regular iff the set of **minimal** bad prefixes for P is regular.

A non-regular safety property

Example: Let us consider again the Beverage vending machine and the property: “*The number of inserted coins is always at least the number of dispensed drinks*”

The language of **minimal bad prefixes** over the alphabet $\Sigma = \{pay, drink\}$ is (first violation of the property):

$$\{ w \cdot drink \mid \#_{drink}(w) = \#_{pay}(w) \}$$

which **is not regular**, but context-free (usually **counting properties are never regular**, because they require memory to count occurrences and this is not possible with a NFA).

Verifying Regular Safety Prop.

Idea: Run **in parallel** the system model \mathcal{M} and the automaton for $\neg f$. $\mathcal{M} \models f$ **iff** $\text{traces}_{\text{fin}}(\mathcal{M}) \cap \text{badPrefixes}(P_f) = \emptyset$
iff $\text{traces}_{\text{fin}}(\mathcal{M}) \cap \mathcal{L}(\neg f) = \emptyset$

Ingredients:

- build an automata for the **intersection of two languages**
- checking **language emptiness**

Definition: [**Product of a Transition System \mathcal{M} and a NFA**]

Let $\mathcal{M} = (S, A, I, \rightarrow, AP, L)$ and $\mathcal{A} = (\Sigma, Q, \delta, Q_0, F)$, such that $\Sigma = 2^{AP}$ and $Q_0 \cap F = \emptyset$. Then $\mathcal{M} \otimes \mathcal{A} = (S', A, I', \rightarrow', AP', L')$ where:

- $S' = S \times Q$
- $(s, q) \rightarrow'_a (s', q')$ whenever $s \rightarrow_a s'$ and $\delta(q, L(s'), q')$
- $I' = \{(s, q) \mid s \in I \wedge \exists q_0 \in Q_0. (q_0, L(s), q)\}$
- $AP' = Q$
- $L': S \times Q \rightarrow 2^Q$ is given by $L'(s, q) = \{q\}$

This construction works also for **Kripke structures**.

Verifying Regular Safety Prop.

Let us define: $\neg F = P_{\text{inv}} = \bigwedge_{q_i \in F} \neg q_i$

Theorem. Let \mathcal{A} be a NFA such that $\mathcal{L}(\mathcal{A}) = \text{badPrefixes}(P)$ of some safety property P and let \mathcal{M} be a transition system. Then the following statements are equivalent:

- $\mathcal{M} \models P$
- $\text{traces}_{\text{fin}}(\mathcal{M}) \cap \mathcal{L}(\mathcal{A}) = \emptyset$
- $\mathcal{M} \otimes \mathcal{A} \models P_{\text{inv}}$

Checking a **regular safety property** has been reduced to a **invariant checking**, that in turn it can be solved by a **reachability**.

Equivalently, **emptiness** of a regular language is a **reachability** problem (check whether **accepting states are reachable** from **initial states**)

The accepted words are **counterexamples**

Lesson 4b:

Finite Automata over Infinite Words

ω -regular Languages

ω -regular languages are subsets of infinite words Σ^ω over a finite alphabet Σ generated by ω -regular expressions.

Example: $(ab)^\omega = ababababab\dots$. Observe that $(ab)^*$ is **an infinite set of finite** words, but $(ab)^\omega$ is **one infinite word**.

The operator $^\omega$ lifts to languages. $\mathcal{L}^\omega = \{ w_1 w_2 w_3 \dots \mid w_i \in \mathcal{L} \}$

Definition: An **ω -regular expression** over Σ has the form:

$$G = E_1 \cdot F_1^\omega + \dots + E_n \cdot F_n^\omega$$

where $n \geq 1$ and $E_1, F_1, \dots, E_n, F_n$ are regular expressions.

$$\mathcal{L}(G) = \mathcal{L}(E_1) \cdot \mathcal{L}(F_1)^\omega \cup \dots \cup \mathcal{L}(E_n) \cdot \mathcal{L}(F_n)^\omega$$

\mathcal{L} is ω -regular if $\mathcal{L} = \mathcal{L}(G)$ for some ω -regular expression G .

ω -regular languages are closed under **union**, **intersection** and **complementation**.

Examples: $(a+b)^* \cdot b^\omega$ is the language of words with finitely many a's. $(b^*a)^\omega$ is the language of words with infinitely many a's.

(Non-Det.) Büchi Automata

A **non-deterministic Büchi automata** \mathcal{A} is a 5-tuple $(\Sigma, Q, \delta, Q_0, F)$ where:

- Σ is the finite input **alphabet**
- Q is the finite set of **states**
- $\delta \subseteq Q \times \Sigma \times Q$ is the **transition relation**
- $Q_0 \subseteq Q$ is the set of **initial states**
- $F \subseteq Q$ is the set of **accepting states**

This definition is exactly the same of NFA, but the semantics of accepted words change!

Let w be an **infinite** word in Σ^ω . A **run** ρ over w is an **infinite sequence** of states $q_0q_1\dots q_n\dots$ such that $q_0 \in Q_0$ is an initial state and $(q_i, w_{i+1}, q_{i+1}) \in \delta$ for all $i \in \mathbb{N}$. **inf**(ρ) is the set of states that occur infinitely often in ρ .

A run is **accepting** if $q_j \in F$ for **infinitely many** i .

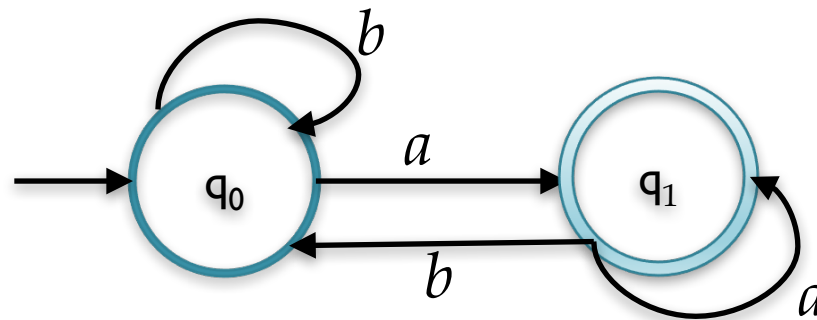
The automaton \mathcal{A} **accepts** w if **there exists** an accepting run ρ over w such that $\text{inf}(\rho) \cap F \neq \emptyset$

The **language** $\mathcal{L}(\mathcal{A}) \subseteq \Sigma^\omega$ consists of all the words accepted by \mathcal{A} .

Büchi Autom. and ω -regular lang.

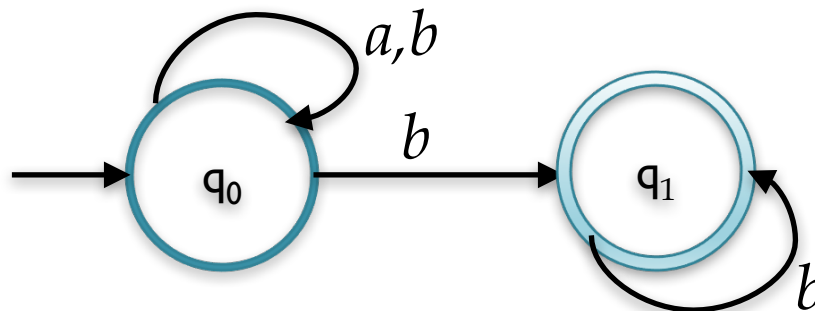
Theorem. The class of languages accepted by NBA's is exactly the class of ω -regular languages.

Examples: Infinitely many a 's: $(b^*a)^\omega$



deterministic

Finitely many a 's: $(a+b)^*.b^\omega$



non-deterministic
 b in q_0 : two trans.

The automaton “**knows**” when the sequence of finitely many a 's stops

NBA for $\mathcal{L}_1 + \mathcal{L}_2$ with $\mathcal{L}_1, \mathcal{L}_2$ ω -reg

Theorem. If \mathcal{L}_1 and \mathcal{L}_2 are ω -regular, then $\mathcal{L}_1 \cup \mathcal{L}_2$ is ω -regular.

Proof: Given an automaton $\mathcal{A}_1 = (\Sigma, Q_1, \delta_1, I_1, F_1)$ accepting \mathcal{L}_1 and an automaton $\mathcal{A}_2 = (\Sigma, Q_2, \delta_2, I_2, F_2)$ accepting \mathcal{L}_2 we build the automata

$$\mathcal{A} = \mathcal{A}_1 + \mathcal{A}_2 = (\Sigma, Q_1 \cup Q_2, \delta, I_1 \cup I_2, F_1 \cup F_2)$$

where $(q, a, q') \in \delta$ if $(q, a, q') \in \delta_1$ **or** $(q, a, q') \in \delta_2$.

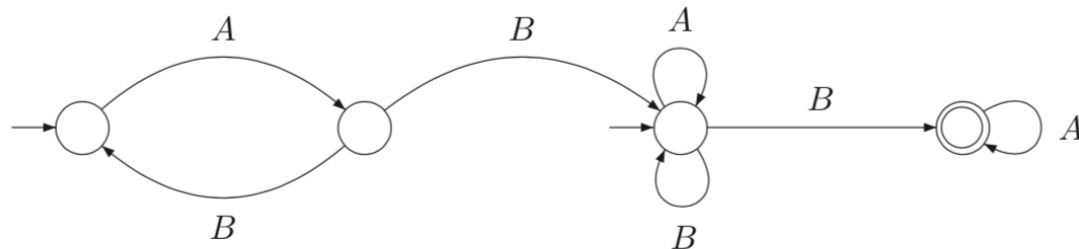
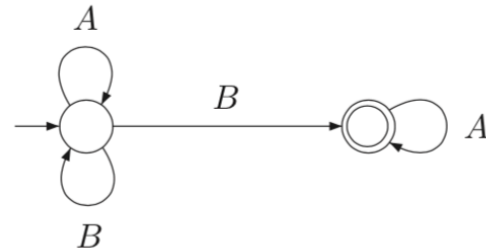
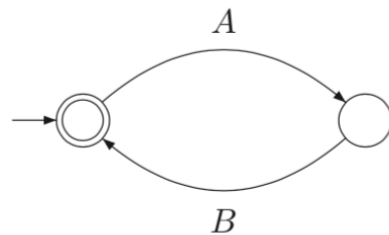
It is easy to see that $\mathcal{A}_1 + \mathcal{A}_2$ accepts $\mathcal{L}_1 \cup \mathcal{L}_2$. (**Exercise** ☺). \square

NBA for $\mathcal{L}_1 \cdot \mathcal{L}_2$, \mathcal{L}_1 reg. \mathcal{L}_2 ω -reg

Idea: Taking the NFA \mathcal{A}_1 accepting \mathcal{L}_1 , the basic trick is **adding a transition** to an **initial state** of the NBA \mathcal{A}_2 accepting \mathcal{L}_2 , whenever there is a transition **to a final state of \mathcal{A}_1** .

Final states are those of the NBA \mathcal{A}_2 . Observe that possible infinite runs inside \mathcal{A}_1 are not accepting.

Example: Let us consider $\mathcal{L}_1 = (ab)^*$, $\mathcal{L}_2 = (a+b)^*ba^\omega$ and $\mathcal{L}_1 \cdot \mathcal{L}_2 = (ab)^*(a+b)^*ba^\omega$

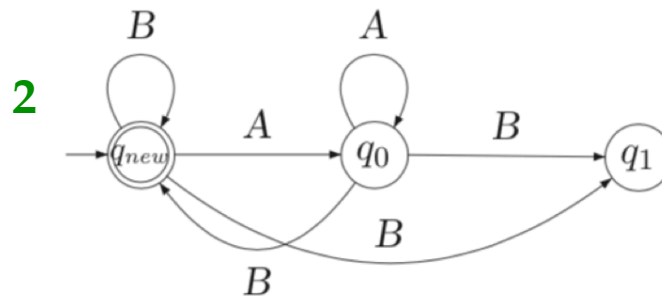
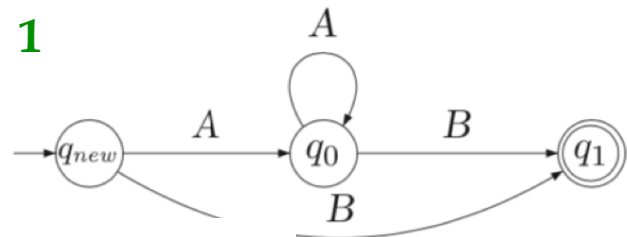
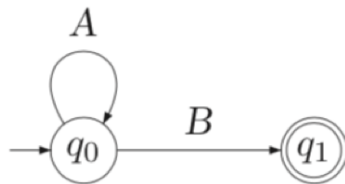


NBA accepting \mathcal{L}^ω , \mathcal{L} regular

Idea: Insert a **new initial** (and **accepting** state) q_{new} and:

1. put a transition from q_{new} to any successor of initial states;
2. put a transition to q_{new} from any accepting state.
[q_{new} is not necessary if initial states are without ingoing transitions and they are not accepting]

Example: $\mathcal{L}=a^*b$.



Non blocking NBA

As usual, we want automata with a total transition relation (**non-blocking**). If a computation **gets stuck**, it's not a problem for theory, it is just a **non-accepting computation** (the same for non-deterministic NFAs).

Proposition: For each NBA \mathcal{A} there exists a non-blocking equivalnet NBA \mathcal{A}' equivalent to \mathcal{A} .

Proof: Just add a sink (or trap) state q_{trap} and transitions to whenever a transition is not defined in some state. \square

More or less, the same trick works for Kripke structures and NFAs.

Remark: \mathcal{A} **equivalent** to \mathcal{A}' means that $\mathcal{L}(\mathcal{A}) = \mathcal{L}(\mathcal{A}')$

The need for non-determinism

Deterministic Büchi automata are **less expressive**.

Theorem. There is **no deterministic Büchi automata** that accepts the language $(a+b)^*b^\omega$.

Proof: Assume that there exists such automaton. The word b^ω belongs to the language. There exists an accepting state q_1 such that $\delta^*(q_0, b^{n_1}) = q_1$ (δ is a function!).

The word $b^{n_1}ab^\omega$ belongs to the language. There exists an accepting state q_2 such that $\delta^*(q_0, b^{n_1}ab^{n_2}) = q_2$.

The word $b^{n_1}ab^{n_2}ab^\omega$ belongs to the language. There exists an accepting state q_3 such that $\delta^*(q_0, b^{n_1}ab^{n_2}ab^{n_3}) = q_3$ **and so on**.

But **there are finitely many states**. Therefore there must be that some $q_i = q_j$ and hence $\delta^*(q_0, b^{n_1}ab^{n_2} \dots ab^{n_i}) = \delta^*(q_0, b^{n_1}ab^{n_2} \dots ab^{n_j})$, but this implies that there is an accepting run for the word $b^{n_1}ab^{n_2} \dots ab^{n_i}(ab^{n_{i+1}} \dots ab^{n_j})^\omega$ that contains infinitely many a 's. Contradiction. \square

The need for non-determinism

Properties of the form “**eventually forever**” has exactly the shape of the ω -regular language $(a+b)^*b^\omega$.

Definition: A **persistence property** is a linear time property $P \subseteq 2^{AP}$ such that for some propositional formula φ :

$$P = \{A_0A_1A_2\ldots \in (2^{AP})^\omega \mid \exists i \geq 0 \forall j \geq i. A_j \models \varphi\}$$

A persistence property can be modeled in LTL as $F G \varphi$.

Alternatively, they can be formalised as “ **$\neg\varphi$ holds finitely many times**”.

Remark: $\exists i \geq 0 \forall j \geq i$ is sometimes written \forall^∞ and can be read “**almost always**”

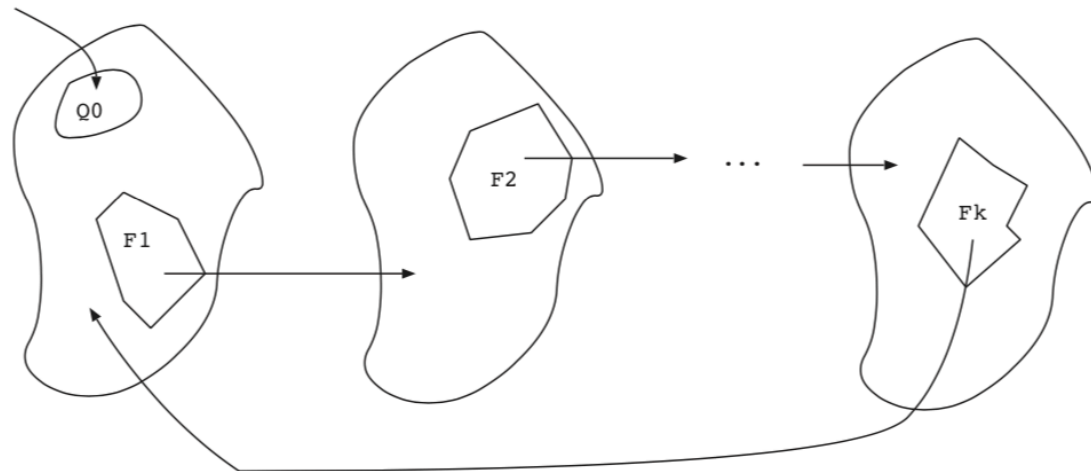
Generalised Büchi Automata

A **generalised Büchi automata** \mathcal{A} is a 5-tuple $(\Sigma, Q, \delta, Q_0, \mathcal{F})$ where Σ, Q, δ, Q_0 are as for NBA, and $\mathcal{F} = \{F_1, \dots, F_n\}$ is a possibly empty subset of 2^Q . F_1, \dots, F_n are called *accepting sets*.

The automaton \mathcal{A} **accepts** w if **there exists** an accepting run ρ over w such that for all sets $F_i \in \mathcal{F}$ we have $\text{inf}(\rho) \cap F_i \neq \emptyset$.

Theorem. For each GNBA \mathcal{A} there exists a NBA \mathcal{A}' such that $\mathcal{L}(\mathcal{A}) = \mathcal{L}(\mathcal{A}')$.

Proof: make n copy of \mathcal{A} and jump to $i+1^{\text{th}}$ copy whenever we go through a state in F_i .



Intersection of ω -regular lang.

Theorem. If \mathcal{L}_1 and \mathcal{L}_2 are ω -regular, then $\mathcal{L}_1 \cap \mathcal{L}_2$ is ω -regular.

Proof: Given an automaton $\mathcal{A}_1 = (\Sigma, Q_1, \delta_1, I_1, F_1)$ accepting \mathcal{L}_1 and an automaton $\mathcal{A}_2 = (\Sigma, Q_2, \delta_2, I_2, F_2)$ accepting \mathcal{L}_2 we build a **generalised automata** $\mathcal{A} = (\Sigma, Q, \delta, I, \mathcal{F})$ accepting \mathcal{L} . We define $\mathcal{A} = \mathcal{A}_1 \otimes \mathcal{A}_2 = (\Sigma, Q_1 \times Q_2, \delta, I_1 \times I_2, \{F_1 \times Q_2, Q_1 \times F_2\})$, where $((q_1, q_2), a, (q'_1, q'_2)) \in \delta$ iff $(q_1, a, q'_1) \in \delta_1$ and $(q_2, a, q'_2) \in \delta_2$. \square

We will use this trick in verification, building an **automata for the model, one for specifications** (or better, for **bad behaviours**) and **we will check if their intersection is empty**.

This strategy will also lead to an **alternative algorithm for LTL model checking**. There is an algorithm (based again on atoms) that allow to build an automata from an LTL formula.

Lesson 4c:

***Automata Theory
and
Model Checking***

ω -Regular Properties

Definition: A linear time property P over AP is **ω -regular** if P is an ω -regular language over the alphabet 2^{AP} .

Examples:

❖ **Invariants** are ω -regular. If φ is a property over AP defining the invariant, φ^ω is a ω -regular language.

❖ **Regular safety properties** are ω -regular.

$$(2^{AP})^\omega \setminus P_{\text{safe}} = \text{badPrefixes}(P_{\text{safe}}) \cdot (2^{AP})^\omega$$

[Remember that ω -regular are **closed under complementation**]

❖ Many **liveness** properties are typical examples of ω -regular (**not regular**) properties.

Example: $((\neg \text{crit})^* \text{crit})^\omega$ = “a process enters critical section infinitely often”

$((\neg \text{wait})^* \text{wait} \cdot \text{true}^* \cdot \text{crit})^\omega + ((\neg \text{wait})^* \text{wait} \cdot \text{true}^* \cdot \text{crit})^* (\neg \text{wait})^\omega$
= “whenever a process is waiting, it will enter its critical section eventually later” (**starvation freedom**)

Checking ω -regular properties

Similar to regular safety properties. However, here we have **to check language emptiness** for a (generalised) **non deterministic Büchi automata**.

Again, the idea is related to **strongly connected components** of a directed graph.

Definition: [Product of a Transition System \mathcal{M} and a NBA]

Let $\mathcal{M} = (S, A, I, \rightarrow, AP, L)$ and $\mathcal{A} = (Q, \Sigma, \delta, Q_0, F)$ be a non-blocking NBA, such that $\Sigma = 2^{AP}$. Then $\mathcal{M} \otimes \mathcal{A} = (S', A, I', \rightarrow', AP', L')$ where:

- $S' = S \times Q$
- $(s, q) \rightarrow'_a (s', q')$ whenever $s \rightarrow_a s'$ and $\delta(q, L(s'), q')$
- $I' = \{(s, q) \mid s \in I \wedge \exists q_0 \in Q_0. (q_0, L(s), q)\}$
- $AP' = Q$
- $L': S \times Q \rightarrow 2^Q$ is given by $L'(s, q) = \{q\}$

Verifying ω -regular Properties

Let us define: $\neg\varphi = \bigwedge_{q_i \in Q} \neg q_i$ and $P_{\text{persistence}} = \mathbf{F G} \neg\varphi$

Theorem. Let \mathcal{M} be a finite transition system and let P an ω -regular property over AP and let \mathcal{A} be a nonblocking NBA such that $\mathcal{L}_\omega(\mathcal{A}) = (2^{AP})^\omega \setminus P$. Then the following are equivalent:

- $\mathcal{M} \models P$
- $\text{traces}(\mathcal{M}) \cap \mathcal{L}_\omega(\mathcal{A}) = \emptyset$
- $\mathcal{M} \otimes \mathcal{A} \models P_{\text{persistence}}(\mathcal{A})$

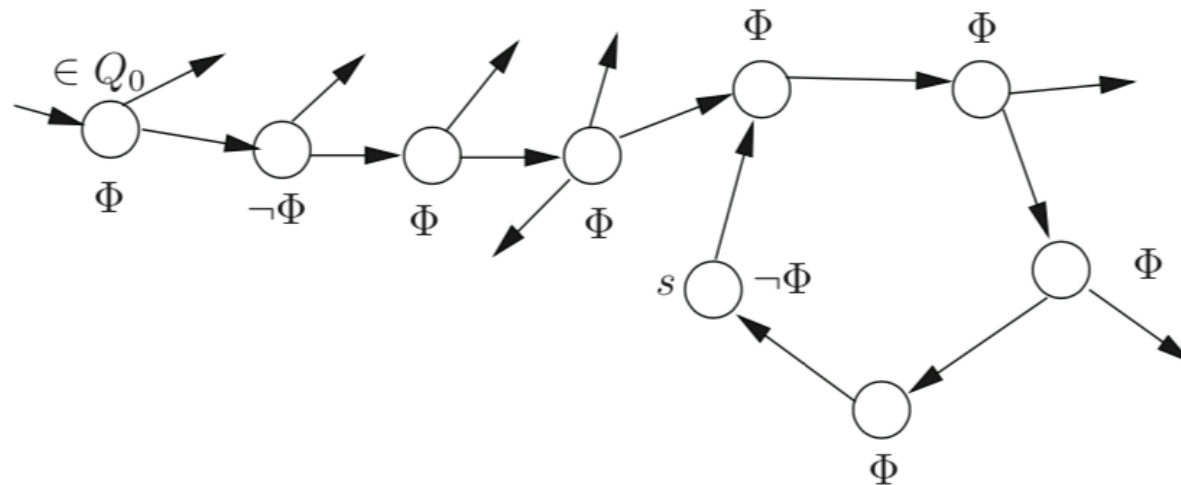
Checking a **ω -regular property** has been reduced to a **checking** a **persistence property**.

Equivalently, **emptiness** of a ω -regular language is a problem of detecting **cycles**: checking whether accepting states belong to a cycle reachable from some initial state.

In this case, **counterexamples** have the form $u \cdot v^\omega$

Counterexamples

In this case, **counterexamples** have the form $u \cdot v^\omega$, where for some q in v , $L(q) \models \neg\varphi$.



Checking a persistence property

Once again, a SCC decomposition of the graph $\mathcal{M} \otimes \mathcal{A}$ would solve the problem. $\text{traces}(\mathcal{M}) \cap \mathcal{L}_\omega(\mathcal{A}) = \emptyset$ if and only if **there is a SCC C that contains a state not satisfying φ and C is reachable from an initial state.**

This algorithm is optimal, in the sense that it is **linear** with the size of $\mathcal{M} \otimes \mathcal{A}$.

However, **in practice** cycle checking can be performed more efficiently without decomposing the whole system $\mathcal{M} \otimes \mathcal{A}$ into strongly connected components.

Many model checkers implement a **nested double DFS search**. This approach has several advantages:

- When a counterexample is found, only a small part of $\mathcal{M} \otimes \mathcal{A}$ is visited.
- \mathcal{M} is described by a program, and **states can be generated during the nested DFS (on-the-fly model checking)**.

Double Nested DFS

```
def dfs1(q):  
    mark(q);  
    forall  $p \in \text{succ}(q)$  do  
        if  $p$  is not marked then dfs1(p);  
    if accept(q) then dfs2(q)
```

$\text{dfs1}(q)$ is used to **finds states**
where property holds ($\text{accept}(q)$)

```
def dfs2(q):  
    flag(q);  
    forall  $p \in \text{succ}(q)$  do  
        if  $p$  is in dfs2 stack then return TRUE;  
        else if  $p$  is not flagged then dfs2(p);
```

$\text{dfs2}(q)$ starts when all successors of a
final state q have been explored

State on the stack of dfs1 up to q **are the**
finite prefix u , whereas states on the
stack of dfs2 **are the cycle v**

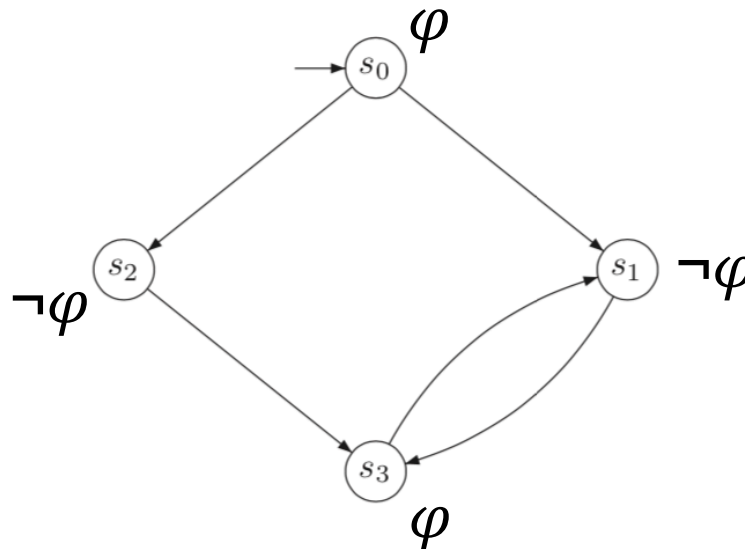
Observe that visited states by dfs1 and dfs2
are **global information**. This is essential to
keep **complexity linear** and to avoid to visit
several times the same state.

Running the Double DFS Search

Start *dfs1* with s_0 . Consider the order of visit $s_0 s_2 s_3 s_1$.

The cycle $s_1 \rightarrow s_3 \rightarrow s_1$ is found when analysing s_1 . Here *dfs2* starts, because $s_1 \neq \varphi$ and all its successors have been already analysed. The counterexample is $s_0 s_2 s_3 (s_1 s_3 s_1)^\omega$.

The order is essential. If we start *dfs2* in s_2 , we fail to find a cycle with a state already onto the stack, but we mark as visited s_3 and s_1 and therefore we later fail to find $(s_1 s_3 s_1)^\omega$.



Correctness of Double DFS (1)

Lemma. Let q be a node that does not appear in any cycle. Then a DFS backtrack from q after all nodes reachable from q have been visited.

Theorem. The Double Nested DFS search returns a counterexample if and only if $\text{traces}(\mathcal{M}) \cap \mathcal{L}_\omega(\mathcal{A}) \neq \emptyset$.

Proof: It is almost trivial to show that if the double DFS returns TRUE, a cycle is found (and hence an **accepted word**).

It is less obvious to show that if a cycle exists, the double DFS finds it. Or equivalently, if it returns FALSE, no cycle exists.

Let us suppose that there exists a cycle from q to a state on the stack of *dfs1* that goes through a state r **already flagged** by *dfs2*. Let q and r be the first states for which this happens and let q' be the root of *dfs2* that flagged r (*dfs2*(q') **started before** *dfs2*(q)).

There are two cases.

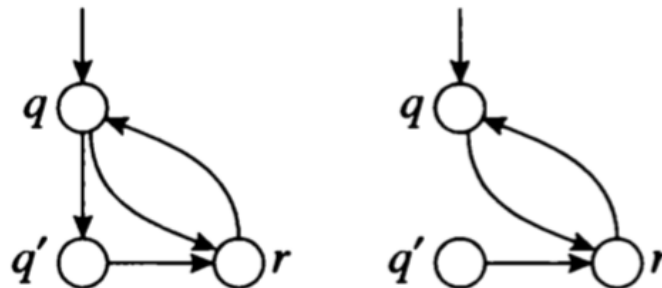
Correctness of Double DFS (2)

If q' is reachable from q , then there exists a cycle that would have been found examining q' : $q' \rightarrow r \rightarrow q \rightarrow q'$ (see picture, **left**)

If q' is not reachable from q , then if q' appears in a cycle, this was missed in a previous iteration, before starting the second DFS from q , contrary to the fact that q is the first state (contradiction).

Therefore q' does not occur in a cycle, **but q is reachable from q' (via r)**. By the Lemma, we have discovered and backtracked from q , **before** starting the DFS from q' , against our assumptions (**r flagged from q'** , see picture, **right**).

□



Lesson 4d:

On the Fly LTL Model Checking

LTl model checking via NBA

Theorem. For any LTL formula φ over AP , there exists a NBA \mathcal{A}_φ with $\text{Words}(\varphi) = \mathcal{L}_\omega(\mathcal{A}_\varphi)$ which can be constructed in time and space $2^{O(|\varphi|)}$.

The proof is rather technical and tedious, but the ingredients are exactly the same of the algorithm based on tableaux, see lesson 3. In particular:

- ❖ automata states represent **maximal consistent sets of $\text{Cl}(\varphi)$** ,
- ❖ **transition relation** is related to presence of subformula of the form **$X \psi$** in $\text{Cl}(\varphi)$, and
- ❖ **accepting states** are related to the presence of some **$\psi_1 \mathbf{U} \psi_2$** in $\text{Cl}(\varphi)$. (Remember that **\mathbf{U}** (and its negation) need to consider infinite paths).

Once one has $\mathcal{M} \otimes \mathcal{A}_{\neg\varphi}$ we just need **to check language emptiness**. **Remark:** even though NBAs are closed under complementation, it is convenient to build $\mathcal{A}_{\neg\varphi}$ rather than complementing \mathcal{A}_φ .

On-the-fly LTL model checking

Usually, the model \mathcal{M} is described by a **high-level language**.

The generation of reachable states of \mathcal{M} can proceed in parallel with the construction of the automaton $\mathcal{A}_{\neg\varphi}$ (remember that states of $\mathcal{M} \otimes \mathcal{A}_{\neg\varphi}$ are pairs).

The product automaton $\mathcal{M} \otimes \mathcal{A}_{\neg\varphi}$ is constructed **on demand**.

A new vertex is only considered if no accepting cycle has been found in the fragment of $\mathcal{M} \otimes \mathcal{A}_{\neg\varphi}$ already explored.

When generating the successor states in $\mathcal{A}_{\neg\varphi}$ we only need to consider those **successors matching the current state in \mathcal{M}** .

On-the-fly technique **is particularly effective** when a **refutation is early found**: in this case a counterexample is returned and large parts of $\mathcal{M} \otimes \mathcal{A}_{\neg\varphi}$ are not generated.

That's all Folks!

Thanks for your attention...
...Questions?