

Formal Methods in Software Development

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Lesson 2d:

Summary of LTL Model Checking

LTL model checking: summary

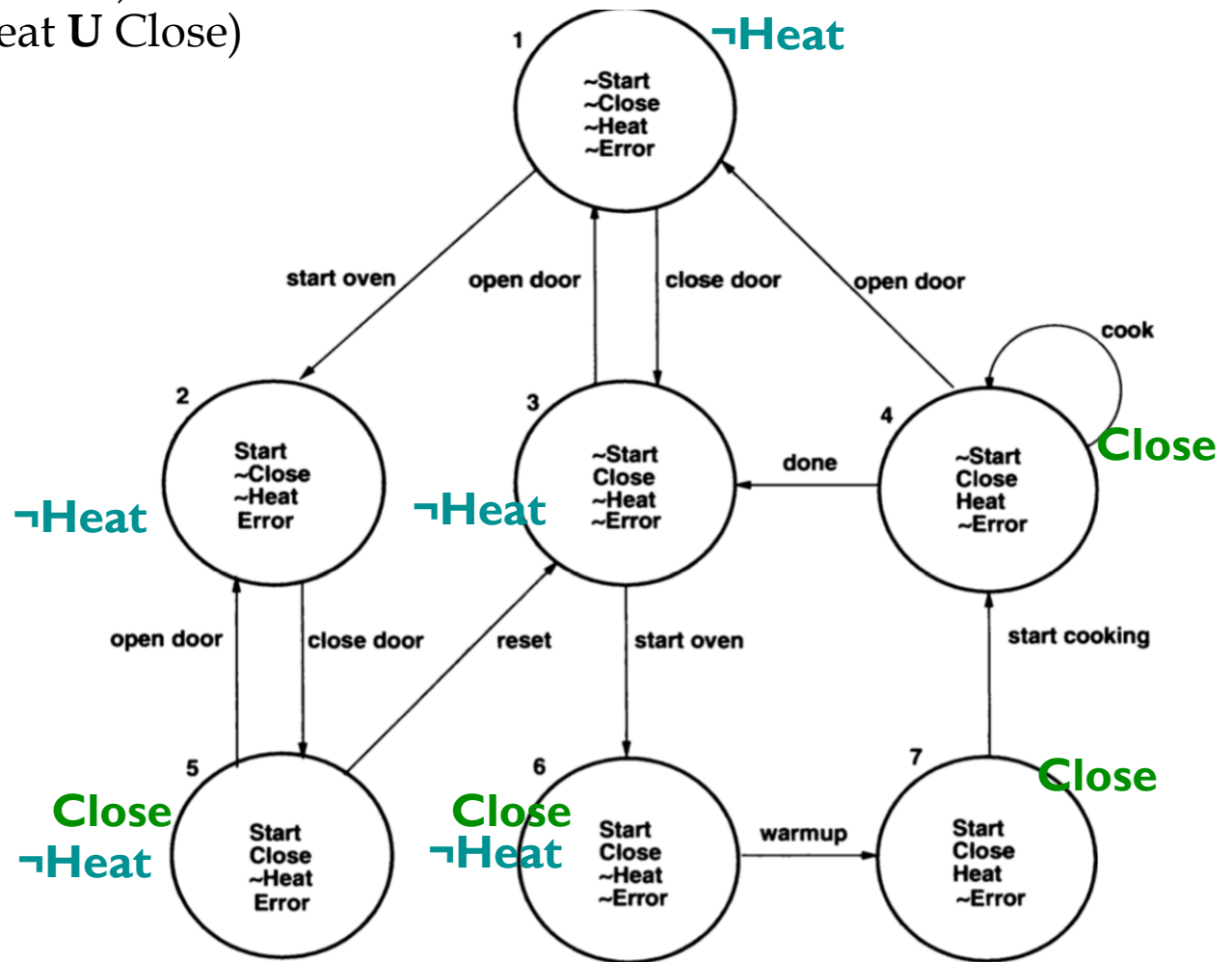
The problem $\mathcal{M}, s \models \mathbf{A} f$ is transformed in the refutation of $\mathcal{M}, s \models \neg \mathbf{E} \neg f$. To verify $\mathcal{M}, s \models \mathbf{E} f$ where $\mathcal{M} = (S, R, L)$:

1. Build the set of formulas: $\text{CL}(f)$.
2. For each state $s \in S$, compute sets K of formulas in $\text{CL}(f)$ consistent with $L(s)$.
3. Build the graph $G^{\mathcal{M}, f}$, that contain an edge from (s, K) to (s', K') whenever (s, s') is in R , $\mathbf{X} g$ in K , and g in K' .
4. Find an eventuality sequence by finding strongly connected components of $G^{\mathcal{M}, f}$

[An **eventuality sequence** is an infinite path π in $G^{\mathcal{M}, f}$ such that if $g_1 \mathbf{U} g_2 \in K$ for some atom (s, K) then there exists an atom (s', K') reachable from (s, K) along π , such that $g_2 \in K'$].

Example: microwave oven

$A(\neg \text{Heat } U \text{ Close})$
 $\equiv \neg E \neg (\neg \text{Heat } U \text{ Close})$



LTL model checking: example 1

Taking $f \equiv (\neg \text{Heat} \text{ U } \text{Close})$

- Compute the closure of f , $\text{CL}(\neg f)$:

$\{\neg f, f, \mathbf{X}f, \neg \mathbf{X}f, \mathbf{X} \neg f, \text{Heat}, \neg \text{Heat}, \text{Close}, \neg \text{Close}\}$

- Compute atoms:

Not just subformulas!

- $\{\neg \text{Heat}, \neg \text{Close}\} \subseteq L(1), L(2)$

$K_1' = \{\neg \text{Heat}, \neg \text{Close}, f, \mathbf{X}f\}$

$K_1'' = \{\neg \text{Heat}, \neg \text{Close}, \neg f, \neg \mathbf{X}f, \mathbf{X} \neg f\}$

- $\{\neg \text{Heat}, \text{Close}\} \subseteq L(3), L(5), L(6)$

Close is not consistent with $\neg f$

$K_2' = \{\neg \text{Heat}, \text{Close}, f, \mathbf{X}f\}$

$K_2'' = \{\neg \text{Heat}, \text{Close}, f, \neg \mathbf{X}f, \mathbf{X} \neg f\}$

- $\{\text{Heat}, \text{Close}\} \subseteq L(4), L(7)$

$K_3' = \{\text{Heat}, \text{Close}, f, \mathbf{X}f\}$

$K_3'' = \{\text{Heat}, \text{Close}, f, \neg \mathbf{X}f, \mathbf{X} \neg f\}$

Compute the graph G

Example of transitions:

$(1, K_1') \rightarrow (2, K_1')$ because $\mathbf{X} f \in K_1', f \in K_1'$, and $(1,2) \in R$

$(1, K_1'') \rightarrow (2, K_1'')$ because $\mathbf{X} \neg f \in K_1', \neg f \in K_1''$, and $(1,2) \in R$

There is no transition $(1, K_1') \rightarrow (2, K_1'')$ since $\mathbf{X} f \in K_1'$ but $f \notin K_1''$

Once the full graph is constructed, it is easy to see that there is no atom (s, K) from which there is a path into a self-fullfilling non trivial strong component of $G^{\mathcal{M}, f}$.

Therefore, no state s is such that $\mathcal{M}, s \models \mathbf{E} \neg f$ and hence all states satisfy $\mathcal{M}, s \models \mathbf{A} g$.

Lesson 3a:

Computation Tree Logic CTL

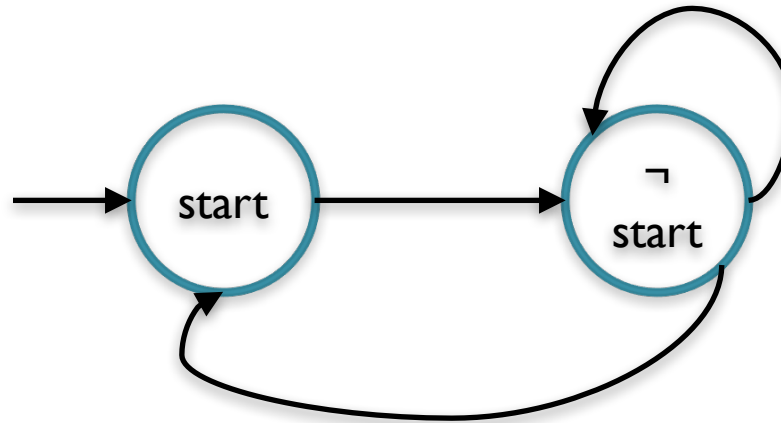
Non Linear Time properties

“For every computation, it is always possible to return to the initial state”

$A \ G \ F \text{ start}$

does not properly work.

It is **too strong**.



This system intuitively satisfies our intended property, but not the linear property $A \ G \ F \text{ start}$

The solution is a **branching notion** of time, allowing nesting of path quantifiers **A** and **E**: in this case $A \ G \ E \ F \text{ start}$.

CTL: syntax

State formulas are formulas that depend on a state of a transition system

- If $p \in AP$, then p is a state formula
- If f, g are state formulas, then so are $\neg f, f \wedge g, f \vee g$
- If f is a path formula, the $A f$ and $E f$ are state formulas

Path formulas are formulas that depend on a computation path

- If f, g are **state** formulas, then $\neg f, f \wedge g, f \vee g, X f, F f, G f, f U g$, and $f R g$ are path formulas

Similar to CTL*, but **each temporal operator** (X, F, G, U, R)
must be preceded by a path quantifier (E or A)

Examples: (il)legal CTL formulas

Let $AP = \{x = 1, x < 2, x \geq 3\}$ be the set of atomic propositions.

Legal CTL formulas are:

EX ($x = 1$), **AX** ($x = 1$), $x = 1 \vee x < 2$

Illegal CTL formulas are:

E ($x = 1 \wedge \mathbf{AX} \ x \geq 3$)

because **AX** $x \geq 3$ is not a path formula

EX ($\text{true} \ \mathbf{U} \ x = 1$)

because **EX** nested with a path formula

By contrast, the following are legal CTL formulas:

EX ($x = 1 \wedge \mathbf{AX} \ x \geq 3$)

EX A ($\text{true} \ \mathbf{U} \ x = 1$)

Common operators: **EF** $\varphi \equiv$ “ φ holds potentially”

AF $\varphi \equiv$ “ φ is inevitable”

EG $\varphi \equiv$ “ φ holds potentially always”

AG $\varphi \equiv$ “invariantly φ ”

Minimal Fragment of CTL

From a theoretical point of view, only 3 operators are really needed: **EX**, **EG**, and **EU**:

$$\mathbf{AX} f \equiv \neg \mathbf{EX} \neg f$$

$$\mathbf{EF} f \equiv \neg \mathbf{E} (\text{true} \mathbf{U} \neg f)$$

$$\mathbf{AG} f \equiv \neg \mathbf{EF} \neg f$$

$$\mathbf{AF} f \equiv \neg \mathbf{EG} \neg f$$

$$\mathbf{A}(f \mathbf{U} g) \equiv \neg \mathbf{E} (\neg g \mathbf{U} \neg f \wedge \neg g) \wedge \neg \mathbf{EG} \neg g$$

$$\mathbf{A}(f \mathbf{R} g) \equiv \neg \mathbf{E} (\neg f \mathbf{U} \neg g)$$

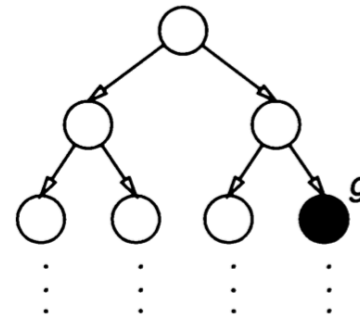
$$\mathbf{E}(f \mathbf{R} g) \equiv \neg \mathbf{A} (\neg f \mathbf{U} \neg g)$$

Attention! that propositional operators (\wedge , \vee , \neg , etc.) **cannot be applied to path formula**, so it is not true that $\mathbf{EG} f \equiv \mathbf{E} \neg \mathbf{F} \neg f$ simply because the latter **is not** a CTL formula.

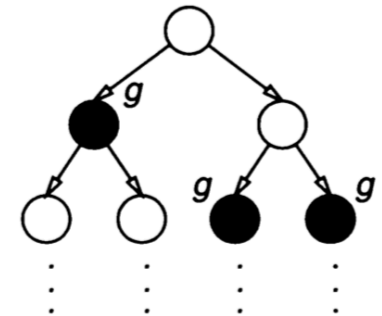
Non Linear Time (LT) examples

The semantics of CTL* formulas are relative to a computation Tree.

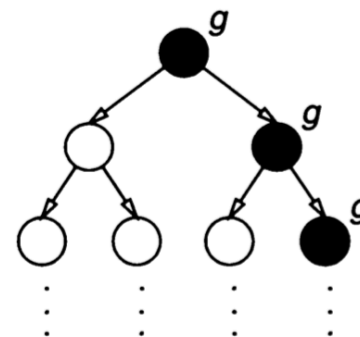
Here some example of computation trees and CTL* formulas valid in such computation trees.



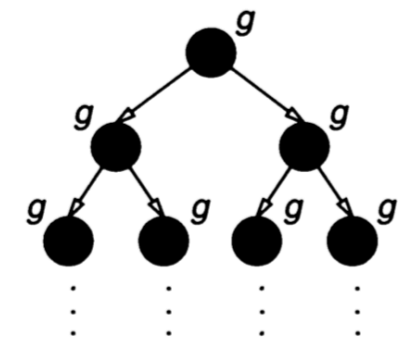
$M, s_0 \models \mathbf{EF} \, g$



$M, s_0 \models \mathbf{AF} \, g$

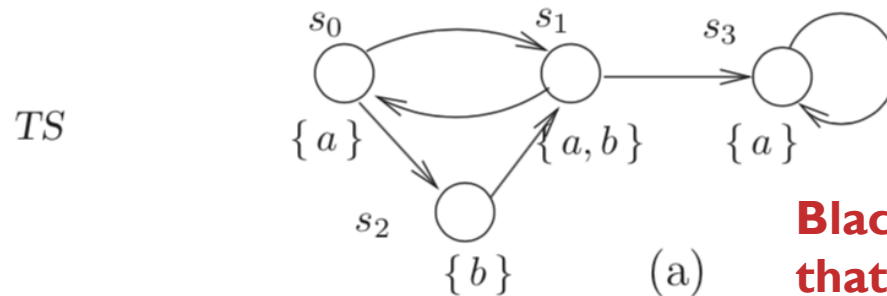


$M, s_0 \models \mathbf{EG} \, g$

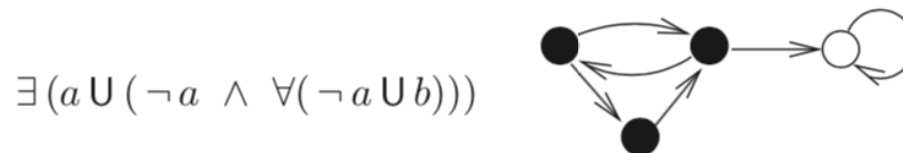
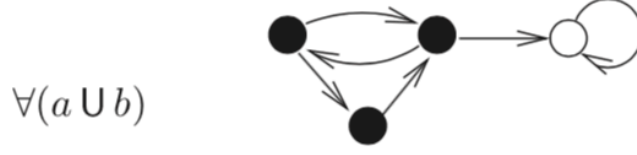
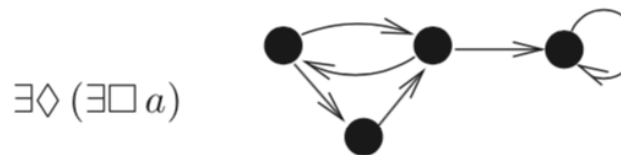
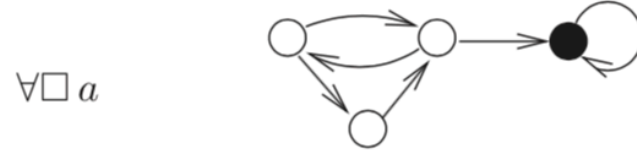
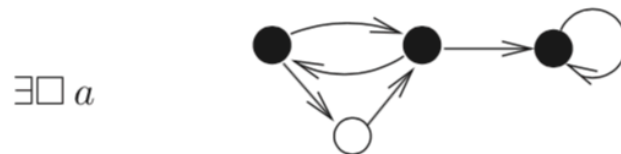
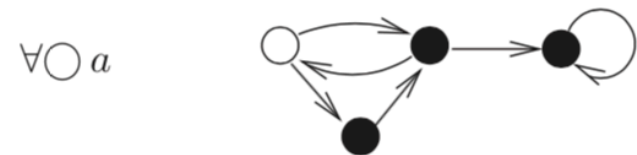
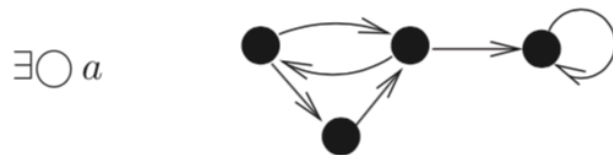


$M, s_0 \models \mathbf{AG} \, g$

Other Examples



Black states are those that satisfy the formula



A remark on negation

A transition system \mathcal{M} satisfies a CTL formula φ , notation $\mathcal{M} \models \varphi$ if and only if $\mathcal{M}, s \models \varphi$ for all $s \in S_0$, where S_0 is the set of initial states of \mathcal{M} .

Be careful that $\mathcal{M}, s \not\models \varphi$ implies $\mathcal{M}, s \models \neg\varphi$, but **it is not true** that $\mathcal{M} \not\models \varphi$ implies $\mathcal{M} \models \neg\varphi$ (**The same holds for LTL!**).

The problem is the universal quantification over initial states!

Example: Both a and $\neg a$ does not hold here:



Equivalent CTL formulas

A CTL formula f is equivalent to g if and only if for all transition system \mathcal{M} , $\mathcal{M} \models f$ iff $\mathcal{M} \models g$

Expansion Laws for CTL:

$$\mathbf{A} (f \mathbf{U} g) \equiv g \vee (f \wedge \mathbf{AX} \mathbf{A}(f \mathbf{U} g))$$

$$\mathbf{AG} f \equiv f \wedge \mathbf{AX} \mathbf{AG} f$$

$$\mathbf{AF} f \equiv f \vee \mathbf{AX} \mathbf{AF} f$$

$$\mathbf{E} (f \mathbf{U} g) \equiv g \vee (f \wedge \mathbf{EX} \mathbf{E}(f \mathbf{U} g))$$

$$\mathbf{EG} f \equiv f \wedge \mathbf{EX} \mathbf{EG} f$$

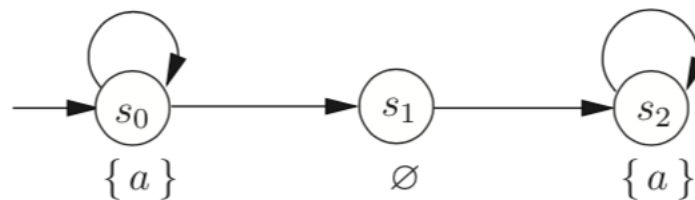
$$\mathbf{EF} f \equiv f \vee \mathbf{EX} \mathbf{EF} f$$

LTL versus CTL: eliminating A

Theorem. Let f be a CTL formula and let f^{LTL} be the LTL formula obtained by eliminating all path quantifiers in f . Then:
 $f \equiv f^{\text{LTL}}$ or there does not exist any LTL formula equivalent to f

Lemma. [PERSISTENCE] The CTL formula $\mathbf{A F A G } a$ and the LTL formula $\mathbf{F G } a$ are not equivalent.

Proof: Just consider the following Kripke structure.



We have $s_0 \models_{\text{LTL}} \mathbf{F G } a$, since all path starting in s_0 will remain forever in s_0 or in s_2 (that satisfy $\mathbf{G } a$).

By contrast $s_0 \not\models_{\text{CTL}} \mathbf{A F A G } a$, since $s_0^{\omega} \not\models_{\text{CTL}} \mathbf{F A G } a$ because of the paths $s_0^* s_1 s_2^{\omega}$ which passes the $\neg a$ -state s_1 . \square

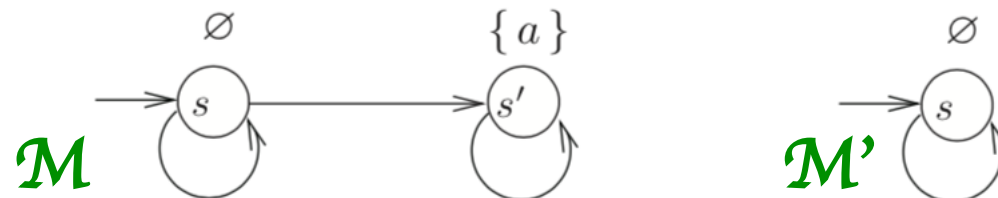
LTL and CTL are not comparable

Theorem.

1. There exist LTL formulas for which no equivalent CTL formula exist. For instance: $\mathbf{F\ G\ } a$ or $\mathbf{F\ (a \wedge \mathbf{X\ } a)}$
2. There exist CTL formulas for which no equivalent LTL formula exist. For instance: $\mathbf{AF\ AG\ } a$ or $\mathbf{AF\ (a \wedge \mathbf{AX\ } a)}$ or $\mathbf{AG\ EF\ } a$

Proof (idea): exhibit suitable transition systems \mathcal{M} and \mathcal{M}' such that $\mathcal{M} \models_{\text{LTL}} g$ and $\mathcal{M}' \not\models_{\text{LTL}} g$ but such that cannot be distinguished by any CTL formula, that is, for all CTL property g , $\mathcal{M} \models_{\text{CTL}} g$ if and only if $\mathcal{M}' \models_{\text{CTL}} g$.

Let us consider $\mathbf{AG\ EF\ } a$. This is satisfied by \mathcal{M} above, but not by \mathcal{M}' . On the other hand since $\text{traces}(\mathcal{M}') \subseteq \text{traces}(\mathcal{M})$, \mathcal{M}' satisfies all LTL formulas satisfied by \mathcal{M} . \square



Lesson 3b:

CTL Model Checking

CTL model checking 1

Idea: Compute a set $label(s)$ in such a way that for each sub-formula g of f , $g \in label(s)$ whenever $\mathcal{M}, s \models g$ holds.

Observation: the number of sub-formulas are linear in the size $|f|$ of a CTL formula f .

Start with the original labeling of states with atomic propositions, i.e. $label(s) = L(s)$.

$g \equiv \neg h \Rightarrow g \in label(s)$ if and only if $h \notin label(s)$

$g \equiv h_1 \vee h_2 \Rightarrow g \in label(s)$ if and only if $h_1 \in label(s)$ or $h_2 \in label(s)$

$g \equiv \mathbf{E X} h \Rightarrow g \in label(s)$ if and only if $h \in label(s')$ for some $s', s \rightarrow s'$

The interesting cases are $g \equiv \mathbf{E G} h$ and $g \equiv \mathbf{E} [h_1 \mathbf{U} h_2]$

CTL model checking 2

When $g \equiv \mathbf{E} [h_1 \mathbf{U} h_2]$ the idea is: start from the set of states such that $h_2 \in \text{label}(s)$ and then proceed backwards on states such that $h_1 \in \text{label}(s)$. Label all these states with g .

```
procedure CheckEU( $f_1, f_2$ )  
   $T := \{ s \mid f_2 \in \text{label}(s) \};$   
  for all  $s \in T$  do  $\text{label}(s) := \text{label}(s) \cup \{ \mathbf{E}[f_1 \mathbf{U} f_2] \};$   
  while  $T \neq \emptyset$  do  
    choose  $s \in T;$   
     $T := T \setminus \{s\};$   
    for all  $t$  such that  $R(t, s)$  do  
      if  $\mathbf{E}[f_1 \mathbf{U} f_2] \notin \text{label}(t)$  and  $f_1 \in \text{label}(t)$  then  
         $\text{label}(t) := \text{label}(t) \cup \{ \mathbf{E}[f_1 \mathbf{U} f_2] \};$   
         $T := T \cup \{t\};$   
      end if;  
    end for all;  
  end while;  
end procedure
```

It is essentially a (backward) visit of a graph. The complexity is $O(|S| + |R|)$

CTL model checking 3

When $g \equiv \mathbf{E} \mathbf{G} h$, we must find infinite paths labeled by h .

In a finite directed graph, such path must enter a strongly connected component where all states are labeled by h .

Roughly speaking:

1. Compute the set of states $S' = \{ s \in S \mid h \in \text{label}(s) \}$.
2. Decompose (S', R') in strongly connected components.
3. Add all states s such that $h \in \text{label}(s)$ and from which one of such strongly connected components is reachable.

CTL model checking 4

Lemma. Let $S' = \{ s' \in S \mid \mathcal{M}, s' \models h \}$. Then Let $\mathcal{M}, s \models \mathbf{E G} h$ if and only if the following conditions are satisfied:

1. $s \in S'$
2. There exists a path from s to a strongly connected component $C \subseteq S'$ and of \mathcal{M}' .

Proof: (If) Let π be an infinite path starting at s satisfying $\mathbf{G} h$. Clearly, $s \models h$. Since π is an infinite, it has the shape $\pi_0 \pi_1$ and in π_1 each state occurs infinitely often. Both states in π_0 and π_1 belongs to $C \subseteq S'$. Since each state appears infinitely often, there is a path between any pairs of state in C that is C is a SCC.

(Only If) There is a finite path π_0 from s to $t \in C$ in S' . Then we can find a finite path π_1 from t back to t . The path $\pi_0 \pi_1^\omega$ satisfies $\mathbf{G} h$. \square

Theorem. Given a Kripke structure $\mathcal{M}=(S, R, L)$ and a CTL formula f , determining if $\mathcal{M} \models_{\text{CTL}} g$ can be decided in time

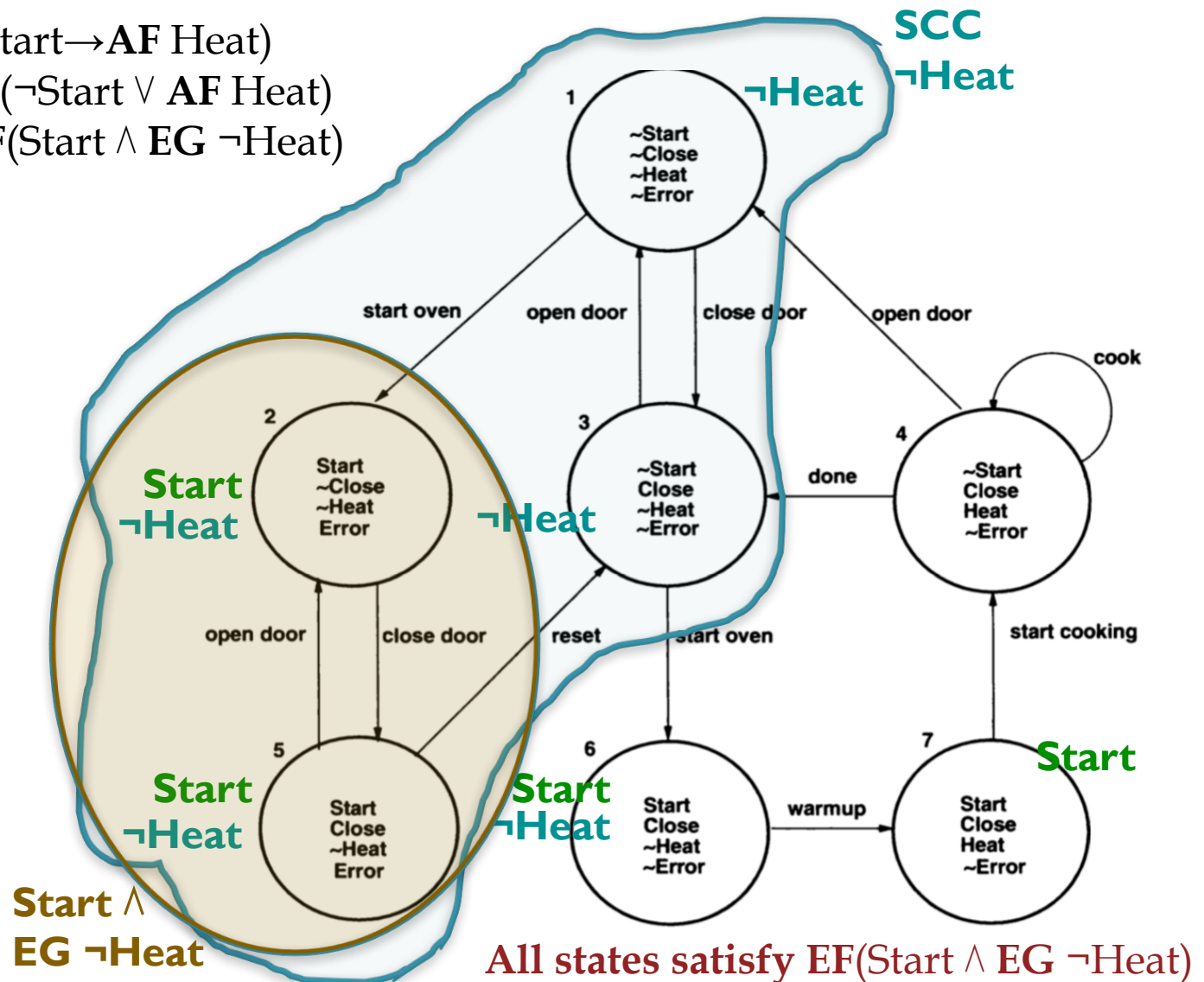
$$O((|S| + |R|) \cdot |f|).$$

CTL model checking 5

```
procedure CheckEG( $f_1$ )  
   $S' := \{ s \mid f_1 \in \text{label}(s) \};$   
   $SCC := \{ C \mid C \text{ is a nontrivial SCC of } S' \};$   
   $T := \bigcup_{C \in SCC} \{ s \mid s \in C \};$   
  for all  $s \in T$  do  $\text{label}(s) := \text{label}(s) \cup \{ \mathbf{EG} f_1 \};$   
  while  $T \neq \emptyset$  do  
    choose  $s \in T;$   
     $T := T \setminus \{s\};$   
    for all  $t$  such that  $t \in S'$  and  $R(t, s)$  do  
      if  $\mathbf{EG} f_1 \notin \text{label}(t)$  then  
         $\text{label}(t) := \text{label}(t) \cup \{ \mathbf{EG} f_1 \};$   
         $T := T \cup \{t\};$   
      end if;  
    end for all;  
  end while;  
end procedure
```

Example: microwave oven

$\text{AG}(\text{Start} \rightarrow \text{AF Heat})$
 $\equiv \text{AG}(\neg \text{Start} \vee \text{AF Heat})$
 $\equiv \neg \text{EF}(\text{Start} \wedge \text{EG} \neg \text{Heat})$



Detour: Hamiltonian path in CTL

Taken a graph $G=(V, E)$, we define a Kripke structure $\mathcal{M}=(S, R, L)$ where:

- $S=E \cup \{b\}$ **b is needed to make R total**
- $R=E \cup \{v \rightarrow b \mid v \in E\}$
- $L(v)=\{v\}$

We define $f = \bigvee_{(i_1, \dots, i_n) \text{ permutation of } (1, \dots, n)} g(v_{i_1}, \dots, v_{i_n})$ and g inductively as follows:

$$g(v_i) = v_i$$

$$g(v_{i_1}, \dots, v_{i_n}) = v_{i_1} \wedge \mathbf{E} \mathbf{X} g(v_{i_2}, \dots, v_{i_n}) \text{ if } n > 1$$

It is easy to see that **$g(v_{i_1}, \dots, v_{i_n})$ holds** if and only if **v_{i_1}, \dots, v_{i_n} is a Hamiltonian path** in G .

Therefore, $\mathcal{M} \models f$ if and only if G has a Hamiltonian path.

Obviously, **this reduction is not polynomial!**

Lesson 3c:

*CTL**

Model Checking

Idea of CTL Model Checking*

Idea: use CTL and LTL model checking procedures on sub-formulas.

Substitute any maximal state sub-formulas with fresh atomic propositions. Like CTL algorithm, the CTL* algorithm works in stages.

Level 0: atomic propositions

Level $i+1$: all state sub-formulas g such that all state sub-formulas of g are of level i or less and g is not contained in any lower level.

Example: $\mathbf{AG}((\neg \text{Close} \wedge \text{Start}) \rightarrow \mathbf{A} (\mathbf{G} \neg \text{Heat} \vee \mathbf{F} \neg \text{Error}))$

Only E quantifier: $\neg \mathbf{EF}((\neg \text{Close} \wedge \text{Start} \wedge \mathbf{E} (\mathbf{F} \text{Heat} \wedge \mathbf{G} \text{Error})))$

Level 0: Close, Start, Heat, Error

Level 1: $\neg \text{Close}$, $\mathbf{E} (\mathbf{F} \text{Heat} \wedge \mathbf{G} \text{Error})$

Level 2: $\mathbf{EF}((\neg \text{Close} \wedge \text{Start} \wedge \mathbf{E} (\mathbf{F} \text{Heat} \wedge \mathbf{G} \text{Error})))$

Level 3: $\neg \mathbf{EF}((\neg \text{Close} \wedge \text{Start} \wedge \mathbf{E} (\mathbf{F} \text{Heat} \wedge \mathbf{G} \text{Error})))$

CTL* Model Checking: algorithm

Algorithm 27 CTL* model checking algorithm (basic idea)

Input: finite transition system TS with initial states I , and CTL* formula Φ

Output: $I \subseteq \text{Sat}(\Phi)$

```
for all  $i \leq |\Phi|$  do
  for all  $\Psi \in \text{Sub}(\Phi)$  with  $|\Psi| = i$  do
    switch( $\Psi$ ):
      true      :  $\text{Sat}(\Psi) := S$ ;
       $a$          :  $\text{Sat}(\Psi) := \{s \in S \mid a \in L(s)\}$ ;
       $a_1 \wedge a_2$  :  $\text{Sat}(\Psi) := \text{Sat}(a_1) \cap \text{Sat}(a_2)$ ;
       $\neg a$       :  $\text{Sat}(\Psi) := S \setminus \text{Sat}(a)$ ;
       $\exists \varphi$      : determine  $\text{Sat}_{LTL}(\neg \varphi)$  by means of an LTL model-checker;
                  :  $\text{Sat}(\Psi) := S \setminus \text{Sat}_{LTL}(\neg \varphi)$ 
    end switch
     $AP := AP \cup \{a_\Psi\}$ ; (* introduce fresh atomic proposition *)
    replace  $\Psi$  with  $a_\Psi$ 
    forall  $s \in \text{Sat}(\Psi)$  do  $L(s) := L(s) \cup \{a_\Psi\}$ ; od
  od
od
return  $I \subseteq \text{Sat}(\Phi)$ 
```

CTL: example and complexity*

Example: $\neg \text{EF}((\neg \text{Close} \wedge \text{Start} \wedge \text{E} (\text{F Heat} \wedge \text{G Error})))$

Level 1: The level 1 formula $\neg \text{Close}$ is added to $L(1)$ and $L(2)$. $\text{E} (\text{F Heat} \wedge \text{G Error})$ is pure LTL, but there is no state satisfying this formula.

Level 2: $\text{E} (\text{F Heat} \wedge \text{G Error})$ is replaced by a fresh atomic proposition a . LTL-model checking is then applied to the formula $\text{EF}((\neg \text{Close} \wedge \text{Start} \wedge a)$, that is unsatisfiable, so all states are labeled with $\neg \text{EF}((\neg \text{Close} \wedge \text{Start} \wedge \text{E} (\text{F Heat} \wedge \text{G Error})))$.

Theorem: There exists a CTL* model checking algorithm with complexity $O(|\mathcal{M}| 2^{|f|})$

Theorem: CTL* model checking is PSPACE-complete.