

# Dataflow programming languages: Simulink



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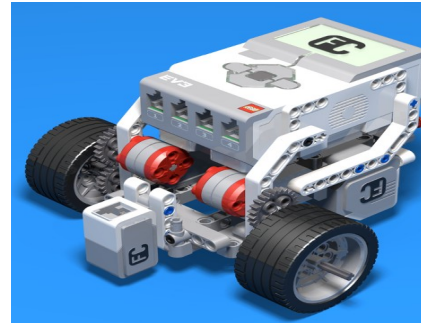
# Simulink

Data-flow programming within MatLab, very engineering-oriented

PRO: Compile/deploy to many systems

Sapienza students licenses

- Android devices
- Apple iPhone/iPad
- Raspberry Pi
- Arduino
- Beagleboard



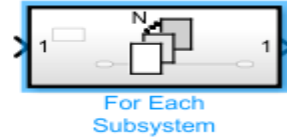
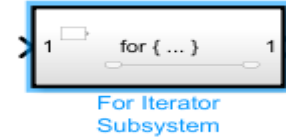
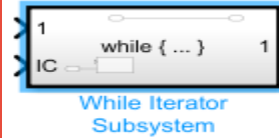
- Nao robot
- Xilinx FPGA boards
- Lego Mindstorms EV3
- Parrot mini drones



# Features

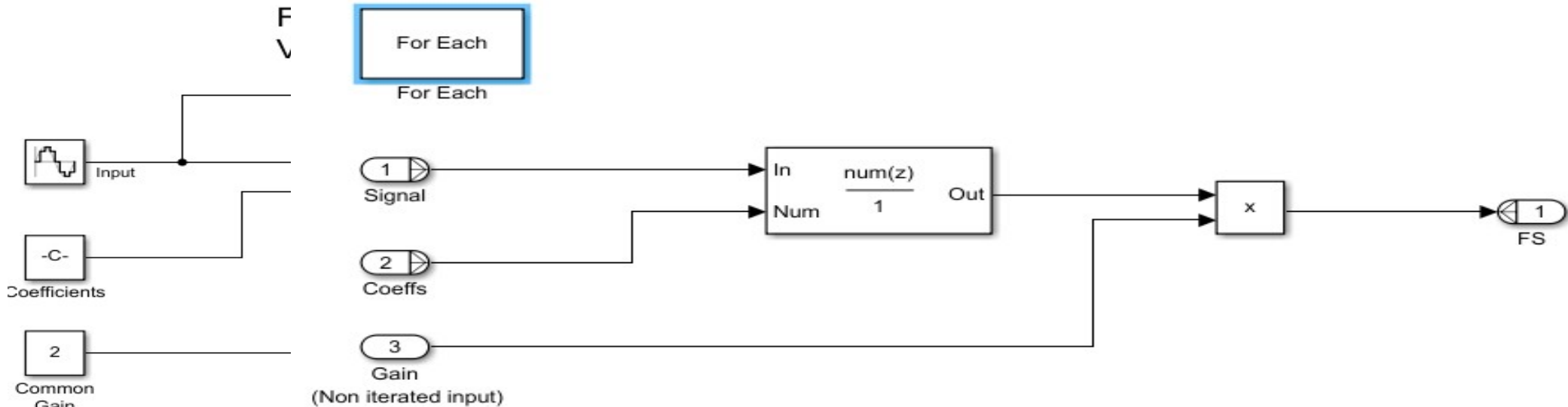
Typed wires?	YES	(but not visually)
Functions?	YES	(in Matlab or in Simulink)
Functional programming?	NO?	
Recursion?	YES	(but in Matlab only)
Loops?	YES	(for, foreach, while)
External languages?		
- Matlab, C, Fortran	YES	
- Python ecc...	YES	(through Matlab)
File I/O	YES	
Modularization?	YES	(subsystems)
Concurrency?	YES	(explicit partitioning)

# Subsystems: looping constructs



Subsystems are used for:

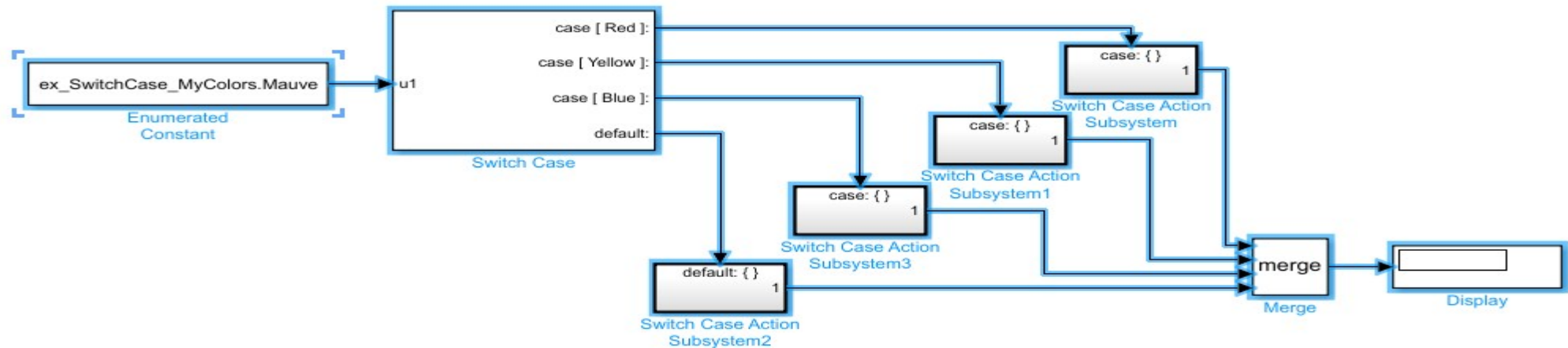
- Hierarchical model definition (modularization)
- Repeated execution (for/while/foreach)



# Conditionals: switch + merge

Conditional execution (if/case) is made by:

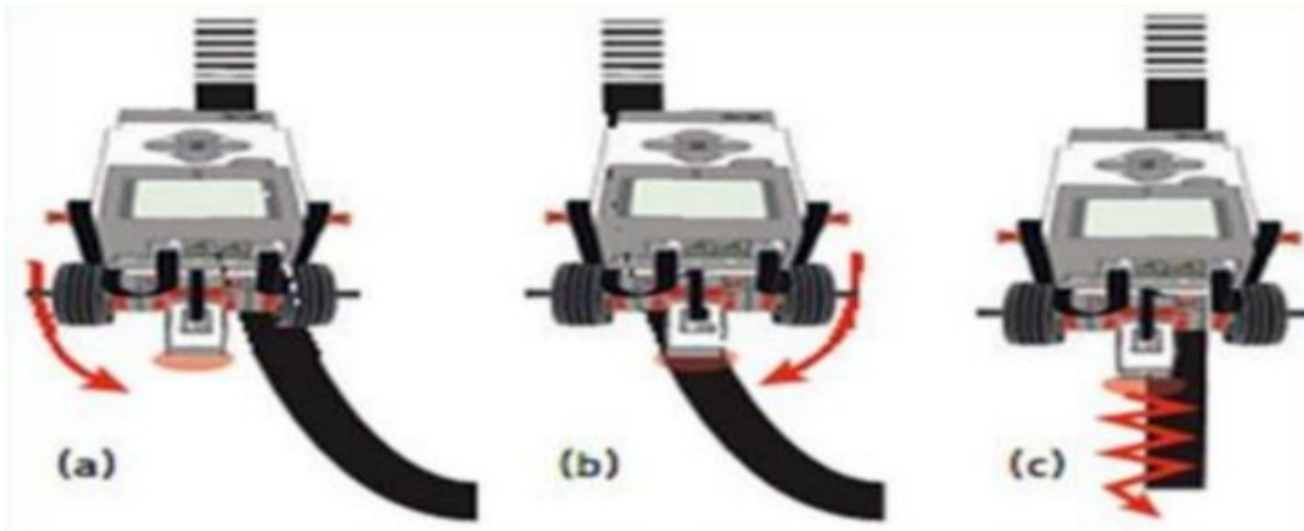
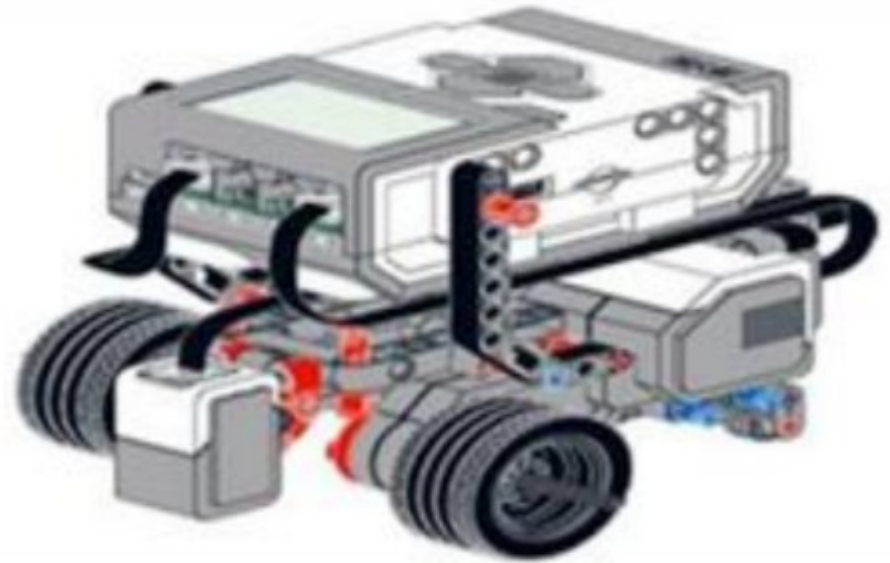
- if/case block with tested input and “enable” outputs
- a separate circuit/subsystem for each case (with “enable” port)
- a merge block collecting all alternate outputs



## Lego EV3 line follower

EV3 with light sensor facing down

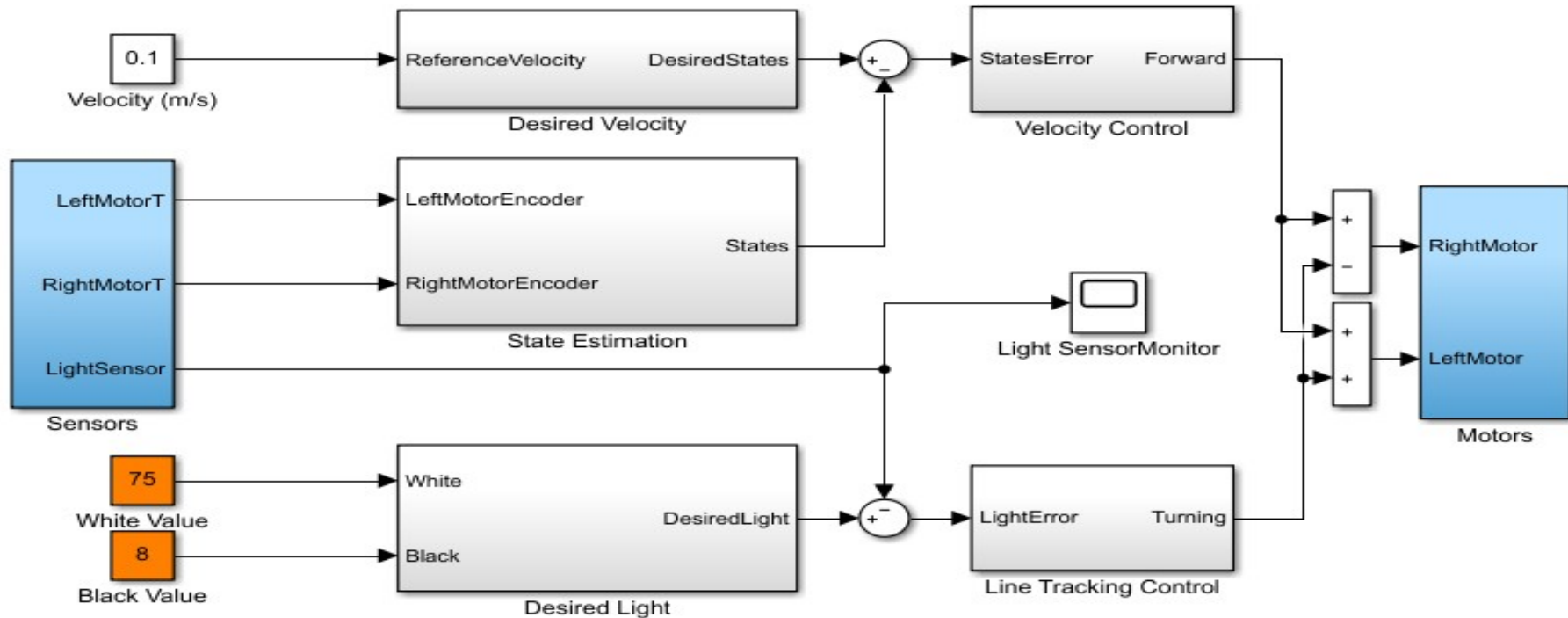
Follow the B/W border of the line



# Line follower: control system

## Line Tracking

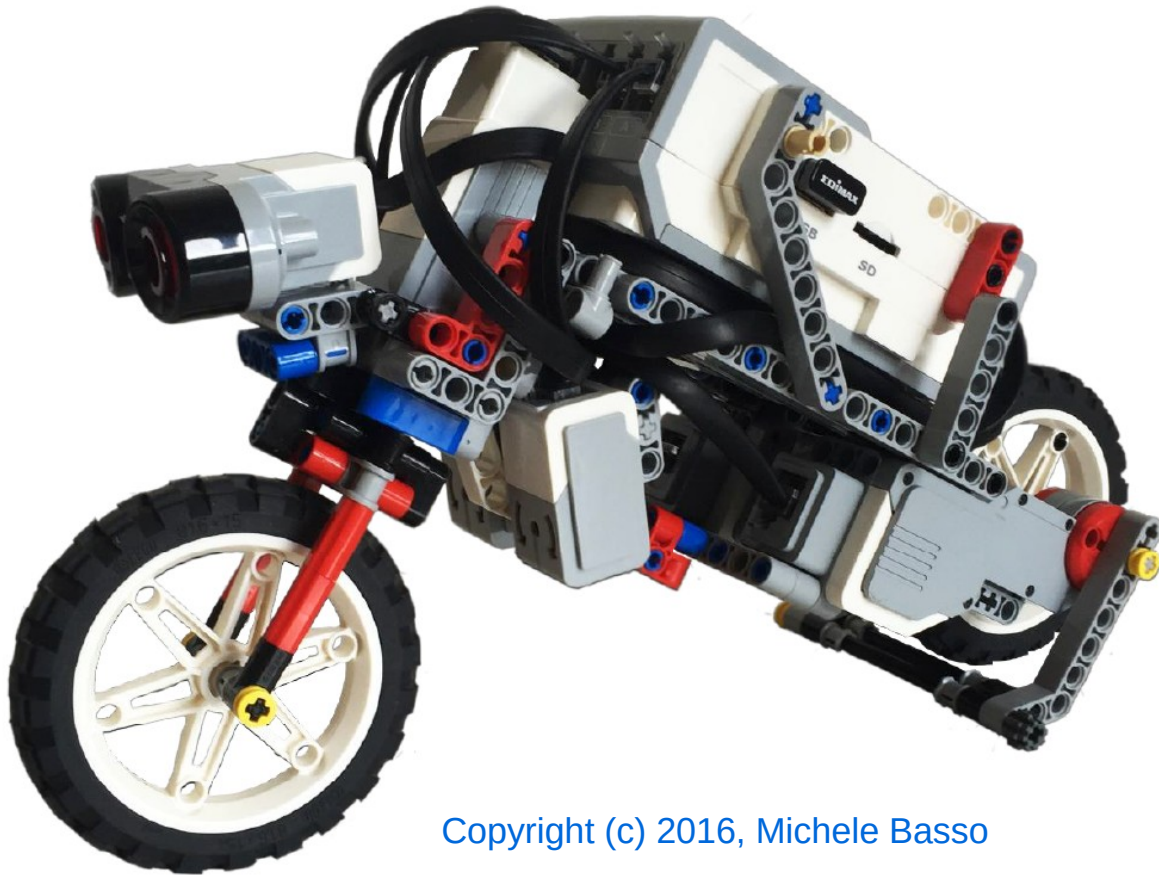
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# Line follower details

**SIMULINK ... loading**

# Lego Bike: keep a bicycle up by steering (@UNI-FI)



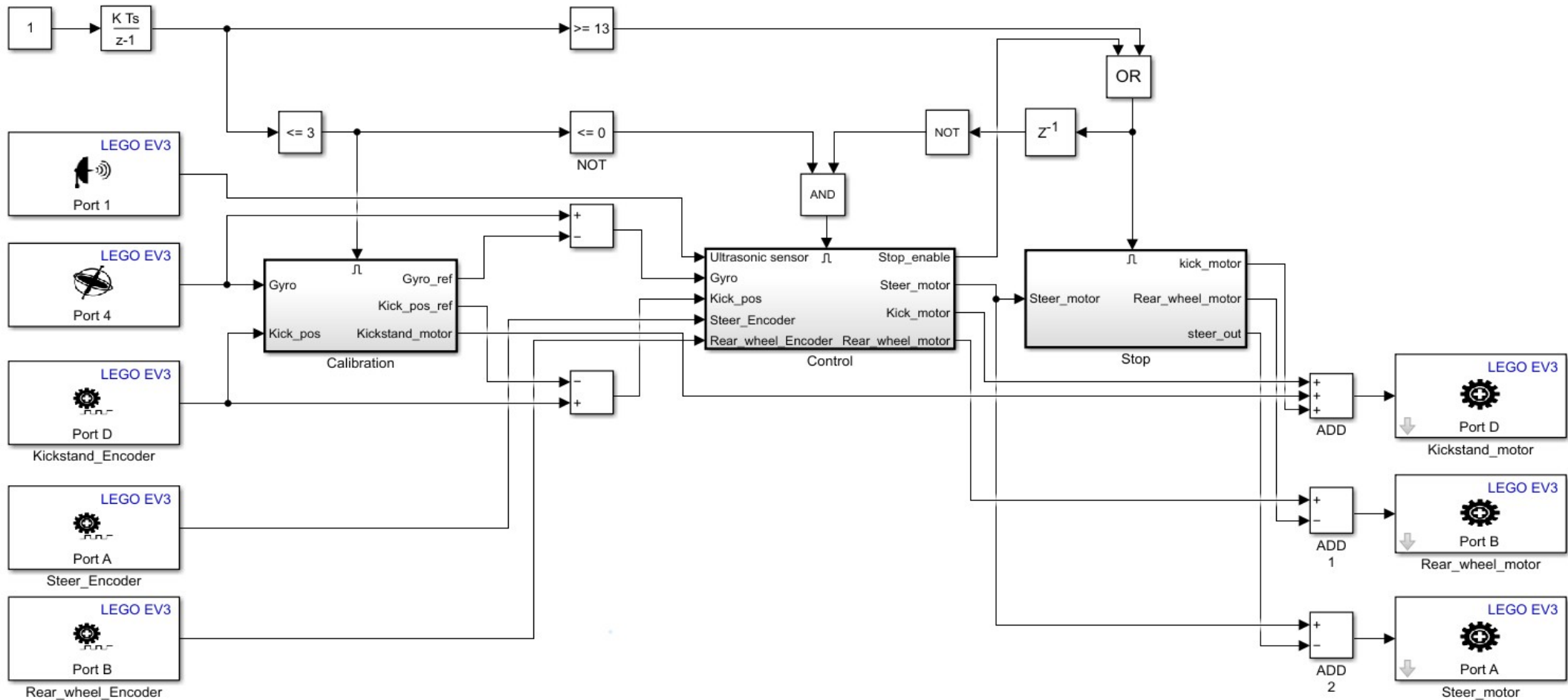
## Sensors:

- gyroscope
- ultrasound distance
- front wheel angle
- rear wheel rotation

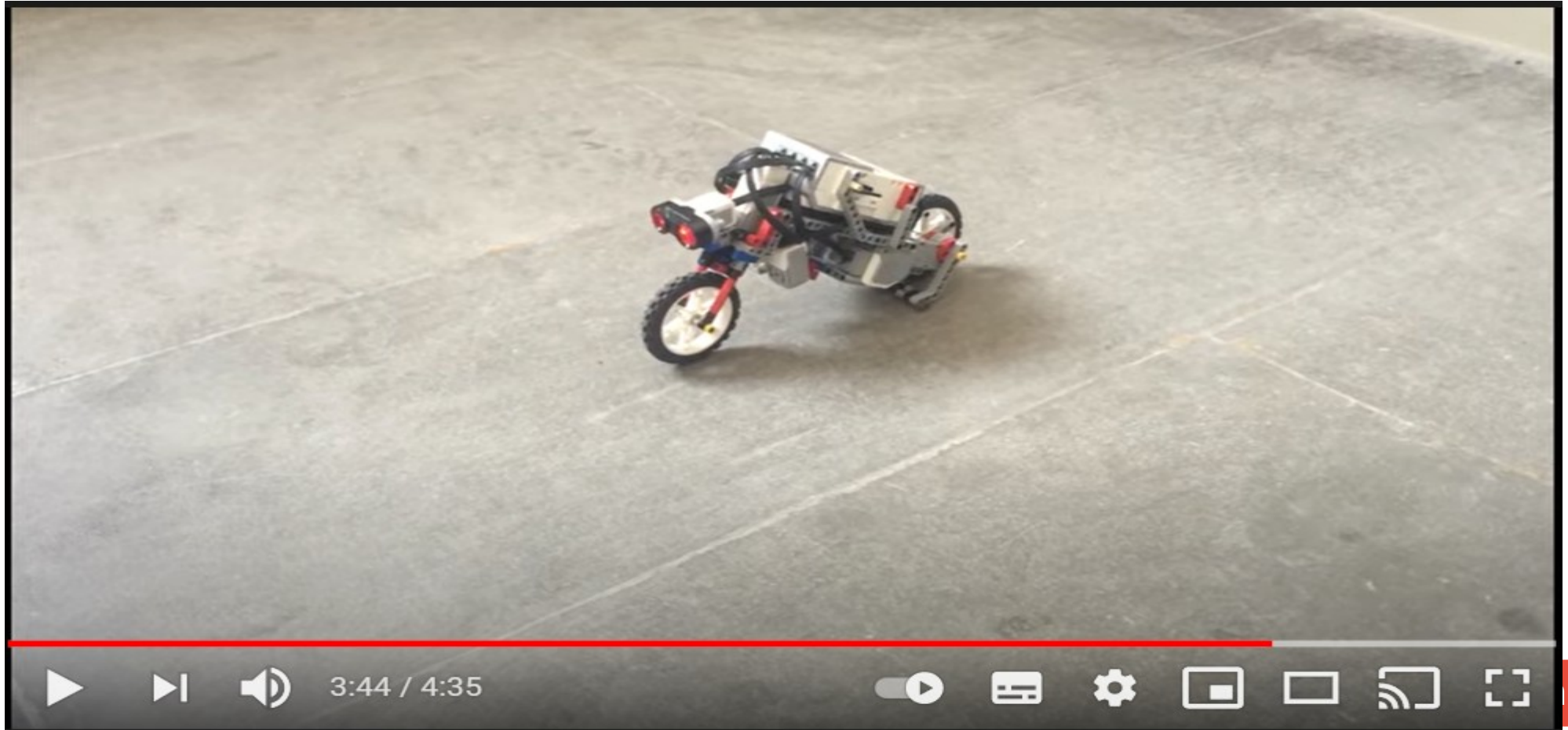
## Actuators

- front wheel steer angle
- rear wheel speed
- rear stand up/down

# Lego Bike: control system



# Lego Bike in action



# Simulink for teaching Computational Thinking?

## PRO

- algorithms as circuits
- enhance modularization with submodules
- good for data/signal analysis
- good for control systems
- a lot of packages and examples
- robotic simulation  
(ROS or Control toolbox)

## CON

- algorithms as circuits (!)
- could be overwhelmingly complex
- diagrams less readable than LabVIEW
- exec. constraints not shown in diagrams

**TLDR: good for electronic/technical schools**