

Intensive Computation 2020-2021  
17th March 2021

## HOMEWORK 2

### Linear Systems

1) Write a C program where you implement GENP (Gaussian Elimination without pivoting) and GE\*P (Gaussian Elimination with either Partial, Complete or Rook pivoting – choose one) to solve linear systems.

Run the two procedures on randomly generated linear systems  $Ax = b$  considering different sizes  $n$  approximately between 1000 and 10000.

For each matrix size, run a number of tests in order to obtain sufficient statistical confidence.

For each test and for each algorithm, consider the execution time and the error  $\epsilon = \|A\tilde{x} - b\|$ , where  $\tilde{x}$  is your computed solution.

Make two graphs using any plotting platform showing how errors and execution times change with the growth of the system size  $n$  for both methods.

Your program should look something like this:

```
runTests:
for n = 1000:1000:10000
    for ex = 1:noExperiments
        generate random A nxn and b nx1;
        run GEPP on Ax=b
        store execution time and error
        run GE*P on Ax=b
        store execution time and error
    end
end
end
```

2) Write a C program for the solving randomly generated linear systems using the Cholesky decomposition.

Test the algorithm over randomly generated linear systems  $Ax = b$  of size  $n$  approximately between 1000 and 10000. When you generate the linear systems, make sure  $A$  is **symmetric and strictly diagonally dominant, with positive entries in its principal diagonal**. This will ensure convergence. An example of symmetric, strictly diagonally dominant matrix with positive entries in its principal diagonal is:

```
A = 3 1 0 -1
    1 8 -4 -2
    0 -4 10 3
    -1 -2 3 8
```

Compare the results that you get in terms of computational time and solution with the output of the LAPACK function \*posv. Implement a similar scheme as runTests.

For comparing the solutions obtained by your Cholesky implementation and Lapack's, compute  $\epsilon = \|\tilde{x} - x_L\|$ , where  $\tilde{x}$  is your solution and  $x_L$  is the solution obtained by Lapack.

Plot your results.

## Installing LAPACK and compiling

Go to: <http://www.netlib.org/lapack/>

Click on [software](#) and download the library.

install with cmake and make (follow the instruction on the README). You will be needing a fortran compiler (gfortran).

To compile your project, project.c, use the following line:

```
gcc -O3 project.c -o project -lcblas -llapacke -llapack
```

LAPACK documentation: <http://www.netlib.org/lapack/explore-html/>

LAPACK documentation for the dposv function:

[http://www.netlib.org/lapack/explore-html/dc/de9/group\\_double\\_posolve\\_ga9ce56acce70eb6484a768eaa841f70d.html-ga9ce56acce70eb6484a768eaa841f70d](http://www.netlib.org/lapack/explore-html/dc/de9/group_double_posolve_ga9ce56acce70eb6484a768eaa841f70d.html-ga9ce56acce70eb6484a768eaa841f70d)

### OTHERWISE:

You might want to use the Intel MKL (Math Kernel Library).

You need to install the Intel oneAPI toolkit:

<https://software.intel.com/content/www/us/en/develop/tools/oneapi/base-toolkit/download.html>

And follow the installation instructions.

To compile your project, project.c, use the following lines:

```
>> source <oneapi_install_dir>/setvars.sh
```

```
>> gcc -O3 -DMKL_ILP64 project.c -o project -lmkl_intel_ilp64 -lmkl_core -lmkl_sequential -lm
```

Line advisor for linking:

<https://software.intel.com/content/www/us/en/develop/tools/oneapi/components/onemkl/link-line-advisor.html>

MKL documentation:

<https://software.intel.com/content/www/us/en/develop/documentation/onemkl-developer-reference-c/top.html>

MKL documentation for the \*posv function:

<https://software.intel.com/content/www/us/en/develop/documentation/onemkl-developer-reference-c/top/lapack-routines/lapack-linear-equation-routines/lapack-linear-equation-driver-routines/posv.html>

SEE ATTACHED FILES geLapack.c and geMKL.c for example including Lapack and MKL calls to the dgesv function for solving linear systems with the Gaussian Elimination.