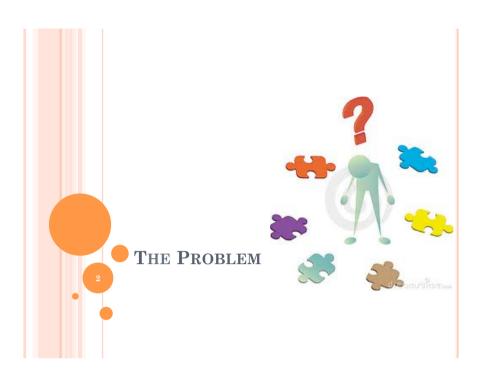
THE MINIMUM ENERGY BROADCAST PROBLEM I.E. THE MINIMUM SPANNING TREE PROBLEM

> Prof. Tiziana Calamoneri Network Algorithms A.y. 2014/15

# THE PROBLEM (1)

- A wireless *ad-hoc* network consists of a set S of (fixed) radio stations joint by wireless connections.
- We assume that stations are located on the Euclidean plane (only partially realistic hp).
- Nodes have omnidirectional antennas: each transmission is listened by all the neighborhood (natural broadcast)

**o** ...



## THE PROBLEM (2)

#### What does it means "sufficiently close"? ...

- Two stations communicate either directly (single-hop) if they are sufficiently close or through intermediate nodes (multi-hop).
- A transmission range is assigned to every station: a range assignment  $r : S \rightarrow R$  determines a directed communication graph G=(S,E), where edge  $(i, j) \in E$  iff dist $(i, j) \leq r(i)$  (dist(i, j)= euclidean distance between i and j).
- In other words,  $(i, j) \in E$  iff j belongs to the disk centered at i and having radius r(i).

#### THE PROBLEM (3)

- For reasons connected with energy saving, each station can dynamically modulate its own transmission power.
- In fact, the transmission radius of a station depends on the energy power supplied to the station.
- The general aim is to save energy as much as possible.

# THE PROBLEM (5)

• Stations of an ad hoc network cooperate in order to provide specific network connectivity properties by adapting their transmission ranges and, at the same time, they try to save energy.

o ...

#### THE PROBLEM (4)

• In particular, the power  $P_s$  required by a station s to transmit data to another station t must satisfy:

$$\frac{P_s}{dist(s,t)^{\alpha}} \ge$$

where  $\alpha \geq 1$  is the distance-power gradient

Usually  $2 \le \alpha \le 4$  (it depends on the envorinment) In the empty space  $\alpha = 2$ 

• Hence, in order to have a communication from *s* to *t*, the power  $P_s$  is proportional to  $dist(s,t)^{\alpha}$ 

# THE PROBLEM (6)

• ... According to the required property, different problems are proposed.

• For example:

- The transmission graph is required to be strongly connected. In such a case, the problem is NP-hard and there is a 2-approximate alg. in 2 dim. [Kirousis, Kranakis, Krizanc, Pelc '01]; there exists an r>1 s.t. the problem is not r-approximable
- The transmission graph is required to have diameter at most *h*. Not trivial approximate results are not known.

#### THE PROBLEM (7)

Given a source node *s*, the transmission graph is required to include a spanning tree rooted at *s*.

• A Broadcast Range Assignment (for short Broadcast) is a range assignment that yields a communication graph G containing a directed spanning tree rooted at a given source station s.

• A fundamental problem in the design of ad-hoc wireless networks is the Minimum-Energy Broadcast problem (for short *Min Broadcast*), that consists in finding a broadcast of minimal *overall energy*.

# THE PROBLEM (9)

#### Proof (cnt.d).

Note. *MinSetCover* is not approximable within  $c \log n$  for some constant c>0, where n=|S|.

Given an instance x of MinSetCover it is possible to construct an instance y of MinBroadcast s.t. there exists a solution for x of cardinality k iff there exists a solution for y of cost k+1.

So, if *MinBroadcast* is approximable withing a constant then even *MinSetCover* is. Contradiction.

# THE PROBLEM (8)

Th. Min Broadcast is not approximable within any constant factor.

Proof. Recall the *MinSetCover* problem:

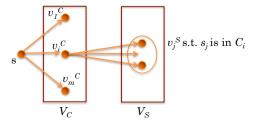
given a collection C of subsets of a finite set S, find a subset C' of C with min cardinality, s.t. each element in S belongs to at least one element of C'.

Example:

$$\begin{split} S = & \{1, 2, 3, 4, 5\} \qquad C = \{\{1, 2\}, \ \{1, 2, 3\}, \ \{3\}, \ \{3, 4, 5\}\} \\ C' = & \{\{1, 2, 3\}, \{3, 4, 5\}\} \end{split}$$

THE PROBLEM (10)

Proof (cnt.d). Reduction: x=(S,C) instance of MinSetCover with:  $S=\{s_1, s_2, ..., s_n\}$  and  $C=\{C_1, C_2, ..., C_m\}$ . We construct y=(G, w, s) of MinBroadcast. Nodes of  $G: \{s\} \cup \{V_C\} \cup \{V_S\}$ Edges of  $G:\{(s, v_i^C), 1 \le i \le m\} \cup \{(v_i^C, v_j^S), 1 \le i \le m, s.t. s_j \text{ in } C_i\}$ 



# THE PROBLEM (11)

#### Proof (cnt.d).

Finally, define w(e)=1 for any edge e.

Let C' be a solution for x.

A sol. for *y* assigns 1 to *s* and to all nodes of  $V_C$  in *C*.

The resulting transmission graph contains a spanning tree rooted at *s* because each element in *S* is contained in at least one element of *C*'. The cost of such a sol. is |C'|+1.

# The Problem (15)

#### Note

- We proved that *Min Broadcast* is not approximable within a constant factor, but we have dealt with the general problem.
- There are some special cases (e.g. the Euclidean bidimensional one) that are particularly interesting and that behave better!
- In the following, we restrict to the special case of Euclidean plane...

# THE PROBLEM (14)

#### Proof (cnt.d).

• • •

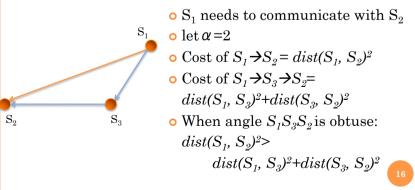
Conversely, assume that r is a feasible sol. for y, (wlog r(v) is either 0 or 1 if v is in  $V_C$ : other values would be meaningless) and r(v)=0 if v is in  $V_S$ .

We derive a sol. C' for x selecting all subsets  $C_i$  s.t.  $r(v_i^{C})=1$ .

It holds that |C'| = cost(r)-1.

# THE PROBLEM (16)

• Collaborating in order to minimize the overall energy is crucial:

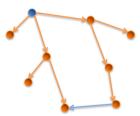


#### THE PROBLEM (17)

• In the Euclidean case, a range assignment r can be represented by the correspondent family  $D = {D_1, \ldots, D_{p}}$  of disks, and the overall energy is defined as:

 $\cos t(D) = \sum_{i=1}^{l} r_i^{\alpha}$  where  $r_i$  is the radius of  $D_i$ .

#### THE PROBLEM (19)



The set of connections used to perform a broadcast from *s*: • cannot generate a cycle, because

nodes do not need to be informed twice  $\rightarrow$  tree

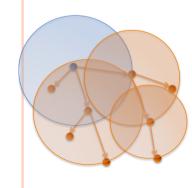
• minimizes the overall energy  $\rightarrow$  long arcs waste more energy than short ones.

# THE PROBLEM (18)

- Consider the complete and weighted graph  $G^{(\alpha)}$ where the weight of each arc e=(u,v) is  $dist(u,v)^{\alpha}$ .
- The broadcast problem is strictly related with the minimum spanning tree, in view of some important properties...

THE PROBLEM (20)

• Nevertheless, the Minimum Broadcast problem is not the same as the Min Spanning Tree problem:



• The energy wasted by each node u is

 $\max_{(u,v)\in T} \left\{ dist(u,v) \right\}^{\alpha}$  (i.e. not all the arcs appear with their contribution) •Leaves waste no energy

#### THE PROBLEM (21)

- The Minimum Broadcast problem is NP-hard in its general version and it is neither approximable within  $(1 \varepsilon) \Delta$  where  $\Delta$  is the maximum degree of T and  $\varepsilon$  is an arbitrary constant
- Nothing is known about the hardness of the geometric version.



#### THE PROBLEM (22)

- An approx algorithm is based on the computation of the MST:
  - compute the MST of the complete graph induced by *S*,
  - Assign a direction to arcs (from *s* to the leaves)
  - Assign to each node i a radius equal to the length of the longest arc outgoing from i
- Easy to implement  $\rightarrow$  deep analysis of the approx ratio.
  - [Clementi+al.'01] the first constant approx ratio (about 40)
  - [Ambüehl '05] the best (tight) known approx ratio (6)

MINIMUM SPANNING TREE (1)

- Obs. 1: If the weights are *positive*, then a MST is in fact a minimum-cost subgraph connecting all nodes
- Proof: A subgraph containing cycles necessarily has a higher total weight. QED
- Obs. 2: There may be several minimum spanning trees of the same weight having a minimum number of edges.
- In particular, if all the edge weights of a given graph are the same, then every spanning tree of that graph is minimum.

## MINIMUM SPANNING TREE (2)

- Obs. 3: If each edge has a distinct weight, then there is a unique MST.
- This is true in many realistic situations, where it's unlikely that any two connections have *exactly* the same cost
- Proof: Assume by contradiction that MST *A* is not unique. So, there is another MST with equal weight, say *B*.

# MINIMUM SPANNING TREE (4)

...

- Obs. 4: For any cycle *C* in the graph, if the weight of an edge *e* of *C* is larger than the weights of all other edges of *C*, then this edge cannot belong to an MST.
- **Proof:** Assuming the contrary, i.e. that *e* belongs to an MST  $T_1$ , then deleting *e* will break  $T_1$  into two subtrees with the two ends of *e* in different subtrees. The remainder of *C* reconnects the subtrees, hence there is an edge *f* of *C* with ends in different subtrees, i.e., it reconnects the subtrees into a tree  $T_2$  with weight less than that of  $T_1$ , because the weight of *f* is less than the weight of *e*.

#### MINIMUM SPANNING TREE (3)

#### (proof – cnt.d)

- Let  $e_1$  be an edge that is in A but not in B. As B is a MST,  $\{e_1\} \cup B$  must contain a cycle C and there is at least one edge  $e_2$  in B that is not in A and lies on C.
- If the weight of  $e_1$  is less than that of  $e_2$ :
- replace  $e_2$  with  $e_1$  in B yields the spanning tree  $\{e_1\} \ U \ B \setminus \{e_2\}$  which has a smaller weight compared to B. Contradiction, as we assumed B is a MST but it is not.
- If the weight of  $e_1$  is larger than that of  $e_2$ : a similar argument involving tree  $\{e_2\}$   $UA \setminus \{e_1\}$  also leads to a contradiction.
- We conclude that the assumption that there is a further MST was false. QED 24

#### MINIMUM SPANNING TREE (5)

- Obs. 5: If the edge of a graph with the minimum cost *e* is unique, then this edge is included in any MST.
- Proof: If *e* was not included in the MST, removing any of the (larger cost) edges in the cycle formed after adding *e* to the MST, would yield a spanning tree of smaller weight. QED

# MINIMUM SPANNING TREE (6)

- Obs. 6: For any cut C in the graph, if the weight of an edge e of C is strictly smaller than the weights of all other edges of C, then this edge belongs to all MSTs of the graph.
- Proof: If e was not included in the MST, adding e to the MST produces a cycle. Removing any of the (larger cost) edges of the cut in the cycle, would yield a spanning tree of smaller weight. QED
- By similar arguments, if more than one edge is of minimum weight across a cut, then each such edge is contained in a minimum spanning tree.

# MINIMUM SPANNING TREE (8)

- The three algorithms are all greedy algorithms and based on the same structure:
  - Given a set of arcs A containing some MST arcs, e is a safe arc w.r.t A if A Ue contains only MST arcs, too.
  - *A*=empty set

#### While A is not a MST

find a safe arc *e* w.r.t. *A* A=A U e

"difficult" issue

# MINIMUM SPANNING TREE (7)

Three classical algorithms: • Kruskal ['56] • Prim ['57] • Boruvka ['26]

#### MINIMUM SPANNING TREE (9)

• *A*=empty set while A is not a MST find a safe arc e w.r.t A  $A = A \cup e$ 

whenever:

• A is acyclic

- graph  $G_{A} = (V, A)$  is a forest whose each connected component is either a node or a tree
- Each safe arc connects different connected components of  $G_A$
- the while loop is run *n*-1 times

# KRUSKAL ALGORITHM (1)

• A=empty set While A is not a MST find a safe arc e w.r.t. A A=A U e

Implementation using:

• Data structure Union-Find

- ${\rm o}$  The set of the arcs of G is sorted w.r.t. their weight
- Time Complexity:  $O(m \log n)$

[Johnson '75, Cheriton & Tarjan '76]

# PRIM ALGORITHM (1)

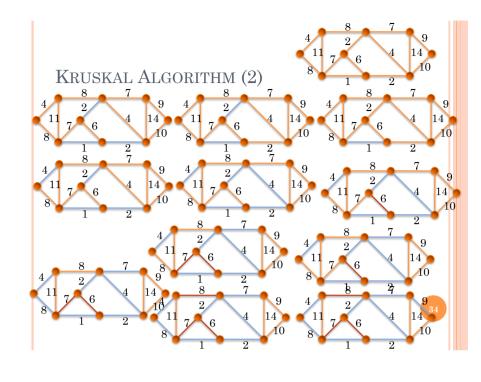
 A=empty set
 While A is not a MST find a safe arc e w.r.t. A
 A=A U e

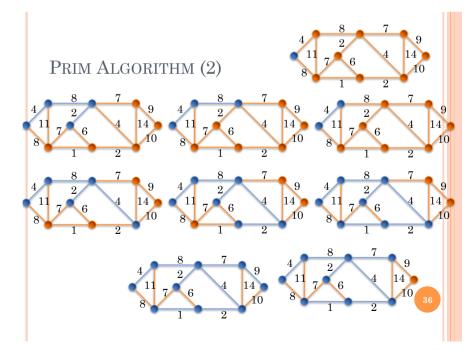
Implementation using:

- Nodes in a min-priority queue w.r.t. key(v)=min weight of an arc connecting v to a node of the main connected component; ∞ if it does not exist
- If the priority queue is a heap  $\rightarrow$  Complexity:  $O(m \log n)$
- If the priority queue is a Fibonacci

heap  $\rightarrow$  Complexity:  $O(m+n \log n)$ 

[Ahuja, Magnanti & Orlin '93]





main connected component with an isolated node, choose the one with minimum weight

Among those connecting the

Among those

connecting two

different connected

components in  $G_A$ ,

choose the one with minimum

weight

# BORUVKA ALGORITHM (1)

(purpose: an efficient electrical coverage of Moravia) Hipothesis: each arc has a

distinct weight

A=empty set
 While A is not a MST
 foreach connected component C<sub>i</sub> of A
 find a safe arc e<sub>i</sub> w.r.t. C<sub>i</sub>
 A=A U {e<sub>i</sub>}

 $\begin{array}{c} \text{Among those} \\ \text{connecting } C_i \text{ to} \\ \text{another} \\ \text{component, the} \\ \text{one with minimum} \\ \text{weight} \end{array}$ 

Trick: handle many arcs (exactly log of the # of connected components) during the same loop Impossible to introduce cycles, thanks to the hipothesis!<sup>37</sup> Complexity:  $O(m \log n)$ 

# 

# OTHER ALGORITHMS (1)

- [Friedman & Willard '94] Linear time algorithm, but it assumes the edges are already sorted w.r.t. their weight. Not used in practice, as the asimptotic notations hides a huge constant
- [Matsui '95] Linear time algorithm for planar graphs (possible lesson)

# OTHER ALGORITHMS (2)

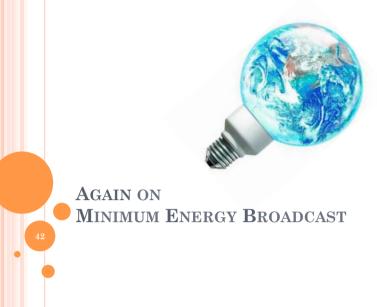
- [Frederickson '85, Eppstein '94] Given a graph and its MST, it is even interesting to find a new MST after that the original graph has been slightly modified. It can be performed in average time  $O(\log n)$
- Only *O*(*n*+*m*) time is necessary to verify whether a given spanning tree is minimum.

#### ANOTHER APPLICATION

- A telecommunications company wants to lay cable to a new neighborhood.
- It is constrained to bury the cable only along certain paths (e.g. along roads).
- Model as a (not geometrical) graph:
  - nodes: represent points
  - edges: represent those paths
  - (edge) weight: cost of adding cable on that path.
     Note 1. some of those paths might be more expensive, because they are longer, or require the cable to be buried deeper
     Note 2. there is no requirement for edge lengths to obey normal rules of geometry such as the triangle inequality.
  - A minimum spanning tree for that graph would be a subset of those paths that has no cycles but still connects to every house with the lowest total cost, thus would represent the least expensive path for laying the cable.

# HEURISTICS (1)

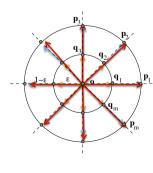
- In [Wieselthier, Nguyen, Ephremides, 00]: three heuristics all based on the greedy technique:
- SPT (spanning path tree): it runs Dijkstra algorithm to get the minimum path tree, then it directs the edges of the tree from the root to the leaves
- BAIP (Broadcast Average Incremental Power): it is a modification of the Dijkstra algorithm based on the nodes (i.e. a new node is added to the tree on the basis of its minimum average cost)
- MST (min spanning tree): it runs Prim algorithm to get a MST, then it directs the edges of the tree from the root to the leaves



#### HEURISTICS (2) Greedy is not always good

Greedy is not always good [Wan, Calinescu, Li, Frieder '02]:

• SPT: it runs Dijkstra algorithm to get the minimum path tree, then it directs the edges of the tree from the root to the leaves



#### $(\text{let} \alpha = 2)$

- SPT outputs a tree with total energy:
  - $\epsilon^{2}+n/2(1-\epsilon)^{2}$
- If the root transmits with radius 1 the energy is 1
- When  $\varepsilon \rightarrow 0$  SPT is far n/2 from the optimal solution.

#### HEURISTICS (3) Greedy is not always good

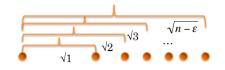
- BAIP (Broadcast Average Incremental Power): it is a modification of the Dijkstra algorithm based on the nodes: a new node is added to the tree on the basis of the min average cost=energy increasing/# of added nodes
- It has been designed to solve the problems of SPT



- BAIP will let the source to transmit at power  $\sqrt{n}$   $\varepsilon$  to reach all nodes in a single step.
- However, the opt. routing is a path consisting of all nodes from left to right. Its min power is:

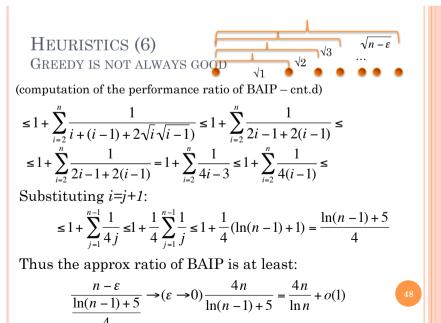
$$\sum_{i=1}^{n-1} (\sqrt{i} - \sqrt{i-1})^2 + (\sqrt{n-\varepsilon} - \sqrt{n-1})^2 < \sum_{i=1}^n (\sqrt{i} - \sqrt{i-1})^2 = \sum_{i=1}^n (\sqrt{i} - \sqrt{i-1})^2 \frac{(\sqrt{i} + \sqrt{i-1})^2}{(\sqrt{i} + \sqrt{i-1})^2} = \sum_{i=1}^n \frac{((\sqrt{i} - \sqrt{i-1})(\sqrt{i} + \sqrt{i-1}))^2}{(\sqrt{i} + \sqrt{i-1})^2} = \sum_{i=1}^n \frac{(i - (i-1))^2}{(\sqrt{i} + \sqrt{i-1})^2} = \sum_{i=1}^n \frac{1}{(\sqrt{i} + \sqrt{i-1})^2} = 1 + \sum_{i=2}^n \frac{1}{(\sqrt{i} + \sqrt{i-1})^2} \le 47$$

# HEURISTICS (4) GREEDY IS NOT ALWAYS GOOD



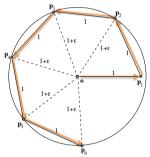
(let  $\alpha = 2$ ):

- The min transmission power of the source to reach k receiving nodes is  $\sqrt{k^2}=k$  and thus the average power efficiency is k/k=1
- On the other hand, the min transmission power of the source to reach all receiving nodes is
- $(\sqrt{n} \cdot \varepsilon)^2 = n \cdot \varepsilon$  and thus the average power efficiency is  $(n \cdot \varepsilon)/n = 1 \cdot \varepsilon / n \dots$



#### HEURISTICS (7) Greedy is not always good

MST: it runs Prim algorithm to get a MST, then it directs the edges of the tree from the root to the leaves



- Path op<sub>1</sub>...p<sub>6</sub> is the unique MST, and its total energy is 6.
  On the other hand, the opt.
- routing is the star centered at *o*, whose energy is (1+ε)<sup>α</sup>.
  The approx. ratio converges to
  - 6, as  $\varepsilon$  goes to 0.

# HEURISTICS (9)

• Any pair of edges do not cross each other

The blue edge is necessarily shorter than at least one of the two crossing edges



# HEURISTICS (8)

- We have just shown a lower bound on the approximation ratio of MST.
- This ratio is a constant and an upper bound is 12.
- The proof involves complicated geometric arguments, and therefore we only sketch some of them:

o ...

# HEURISTICS (10)

(properties of the geometric MST - cnt.d)

 $\circ$  The angles between any two edges incident to a common node is at least  $\pi/3$ 



The blue edge is necessarily shorter than at least one of the two orange edges

# HEURISTICS (11)

(properties of the geometric MST - cntd)

• The *lune* determined by each edge does not contain any other nodes.

The lune through points  $p_1$  and  $p_2$  is the intersection of the two open disks of radius  $dist(p_1,p_2)$  centered at  $p_1$  and  $p_2$ , respectively, hence an internal node would create a cycle

# HEURISTICS (13)

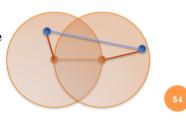
- Obs. The proof in [Wan, Calinescu, Li, Frieder '02] contains a small flaw that can be solved, arriving to an approximation ratio of 12,15 [Klasing, Navarra, Papadopoulos, Perennes '04]
- Indipendently, an approximation ratio of 20 has been stated in [Clementi, Crescenzi, Penna, Rossi, Vocca '01]
- Approx. ratio improved to 7,6 [Flammini, Klasing, Navarra, Perennes '04]
- Approx. ratio improved to 6,33 [Navarra '05]
- Optimal bound 6 [Ambüehl '05]

# HEURISTICS (12)

(properties of the geometric MST - cnt.d)

• Let  $p_1 p_2$  be any edge. Then the two endpoints of any other edge are either both outside the open disk  $D(p_1, dist(p_1, p_2))$  or both outside the open disk  $D(p_2, dist(p_1, p_2))$ 

The red edges are added before than the blue edge because they are shorter. The blue edge would create a cycle.



HEURISTICS (14)

• For realistic instances, experiments suggest that the tight approximation ratio is not 6 but 4 [Flammini, Navarra, Perennes '06] -> possible lesson