

# Can mobility improve WSN performance?

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Università degli Studi di Roma

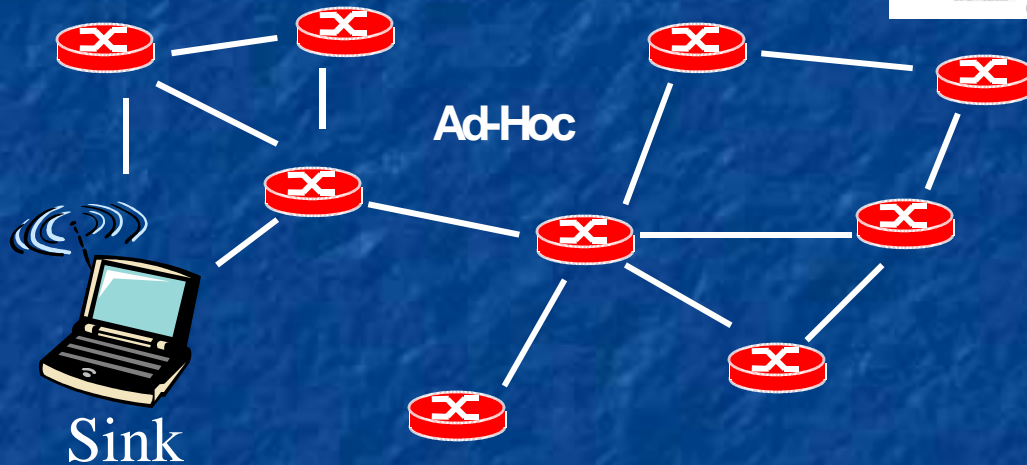


**Northeastern**

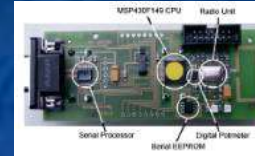
UNIVERSITY

# Wireless Sensor Networks

Traditional view



Sensor node



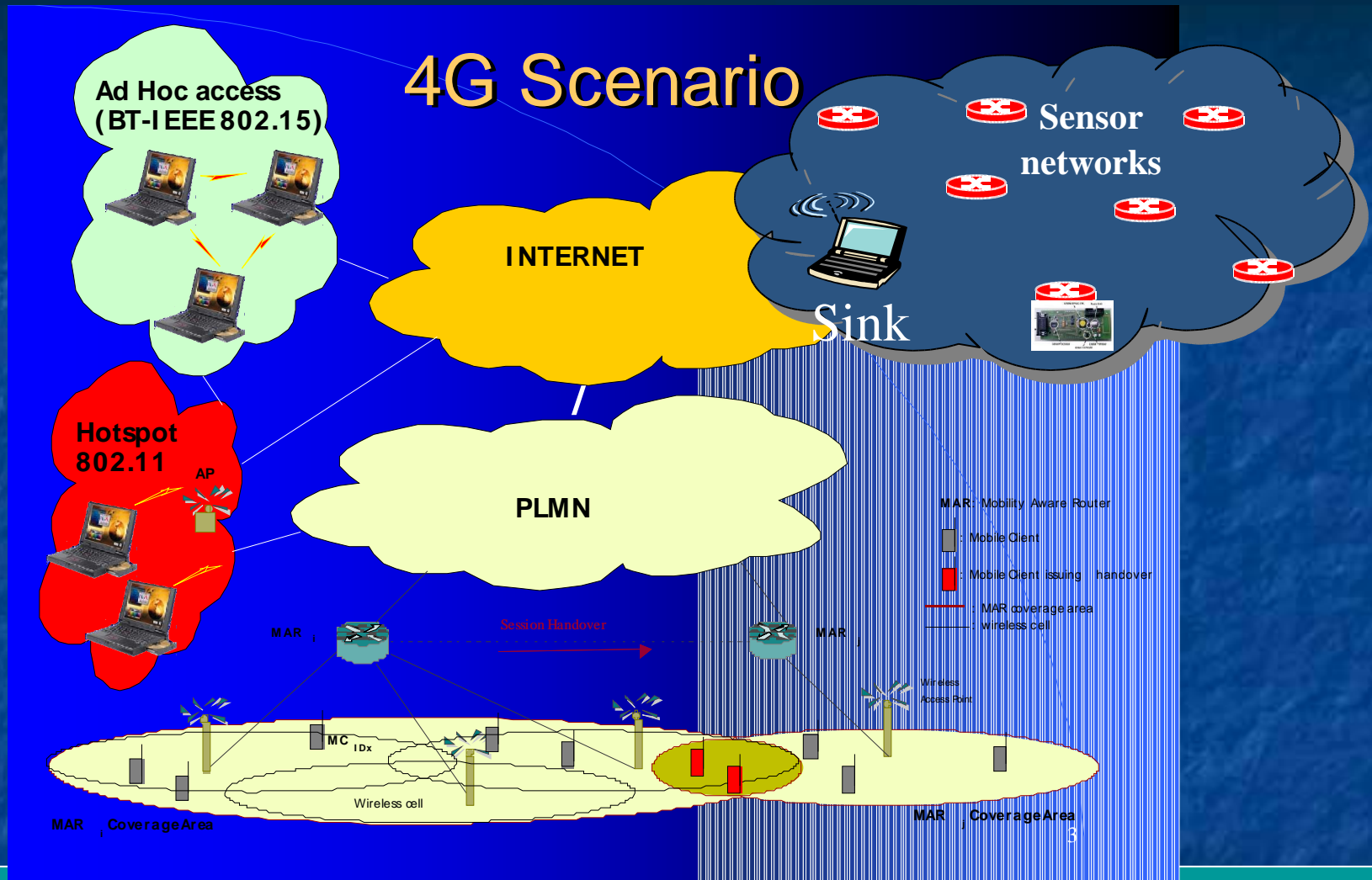
*Traditional applications*

- environmental monitoring
- precision agriculture
- structural integrity of buildings/bridges
- military applications

....

A sensor network is a network whose nodes have sensing, (actuating), (wireless) transmission capability. Nodes cooperate to perform monitoring of events of interest. Communication is via multi-hop paths to/from more resource-rich devices called sinks

# Wireless Sensor Networks



A sensor network is a network of nodes which monitor events of interest to provide ambient intelligence. Such intelligence can be exploited by existing networks to provide value added services.

# WSN: features and constraint

- Sensor nodes are very limited in terms of
  - energy, memory, computational power
- Are deployed in very large numbers in often hostile, inaccessible areas → batteries cannot be recharged/replaced
- Communication is from the sink to the sensor nodes (interest dissemination) and from the sensor nodes to the sink (convergecasting)
- Systems must be operational for long times (say years)
- Traffic maybe low
- Nodes and network elements are static (TRUE ??)



- Need to adopt simple, fully distributed, scalable, schemes
- Energy-efficiency really an issue for system implementation
  - key metric: network lifetime ← time till the system is fully operational)
  - key element: exploit the fact nodes transceiver can alternate between awake and asleep (low energy-consuming) modes

# WSN: Where we are today

A lot has been done already on the design of energy-efficient protocols for WSNs...

- Energy-efficient design of protocols at the PHY,MAC, routing layers
- Exploitation of data aggregation, awake-asleep scheduling
- Cross-layer optimizations to design an overall energy-efficient solution
- Homogenous networks usually assumed

## Current hot topics

- Need of large-scale real-life testing, and of development of tools to enable extensive testing
- Mobility of some of the network elements is an emerging issue still to dealt with
  - As associated to some specific scenarios
  - As able to improve performance (today's talk)
- Scalability issues should be accounted for

# Why mobility in sensor networks?

- To allow communication between different connected components of the network → allowing also sparse networks to operate
- To reduce energy consumption
- To better load balance energy consumption among the nodes → increasing lifetime
- To improve placement (sensors mobility) and coverage

# Different Architectures and mobility

Which network component is mobile?

## Sensor Nodes

Sensor nodes  
are mobile  
(usually for better  
placement)

Sensors are attached  
to mobile devices  
(e.g. car, buses)

## Mobile Agents

Communication  
to/from the sensor  
nodes only when the  
agent passes by  
→  
energy-latency trade-off

- Uncontrolled, unpredictable mobility
- Uncontrolled predictable mobility
- Controlled mobility

## Sink

Allows improvements  
in performance.  
Communication  
can be multi-hop.

# An example: Data Mules



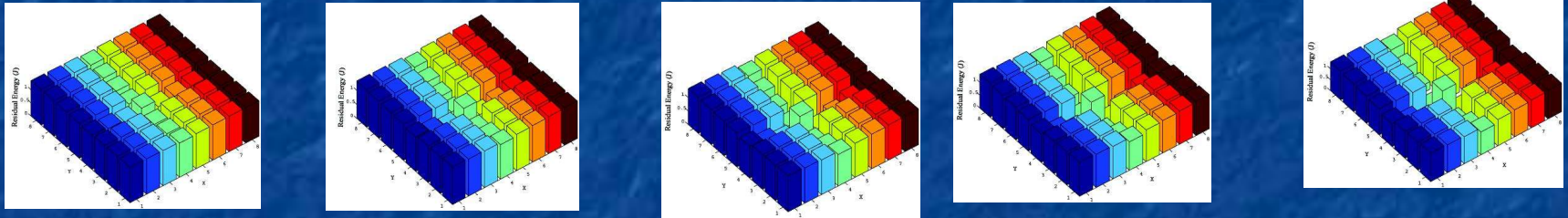
- Sensor nodes communicate data to MULEs when they pass by
- MULEs store the info they gather and delivery them to the sink when they pass by  
low complexity & energy vs. latency



# Our idea: controlled sink mobility

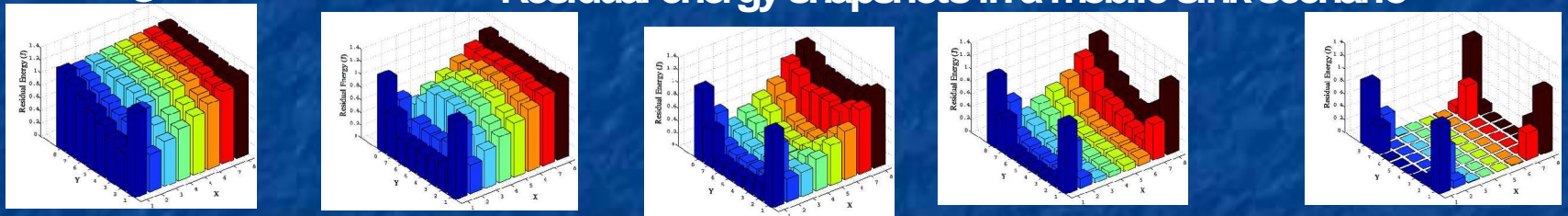
Idea: If the sink is static independently of the routing protocol adopted nodes close to the sink will fast deplete their energy and die  $\rightarrow$  sink disconnection  $\rightarrow$  the WSN can no longer operate

**Residual energy snapshots in a static sink scenario**



If the sink can move the energy consumption is more fairly balanced among nodes

**Residual energy snapshots in a mobile sink scenario**



If sink mobility can be controllable (e.g. the sink is a robot, an UV, or located over a moving object) then we can address how it should move to maximize lifetime (general multi-hop WSN scenario)

# Problem Formulation

- *Given  $n$  wireless sensor nodes deployed in an area, and a set of sink sites  $S$  determine the initial site, the route to be followed by the sink as well as the sojourn times  $t_k$  at each site  $k$  in  $S$  so that the network lifetime is maximized.*
- Each sensor node  $i$  transmits data periodically with a rate  $r_i$ , has a transmission range and energy model which depend on the sensor node prototype. All sensor nodes use the same routing protocol (e.g. shortest path-geographic).

# Problem Formulation

- We assume that each time the sink reaches a new site it informs the nodes which perform route maintenance accordingly
- When the sink decides to move it also informs the nodes
  - generated or in transit packets are buffered till nodes are informed of the new sink site
  - → longer traveled distances result in more time the packets may have to be buffered → longer latencies

# A MILP formulation

*Given a routing protocol, and a set of sink sites, how can we determine the sink route and sink sojourn times at the different sink sites to maximize the network lifetime?*

## Distinguished Features of the Model

- The model can be applied to a sensor network with any geometric shapes, e.g. squares or circles.
- The model is independent from the underlying sensor network topology, a grid or any arbitrary topology.
- The model can also work with any type of routing method, e.g., shortest path or geographic routing method.
- The model is not restricted with the transmission range or any physical parameters set up in the sensor nodes.
- The model accounts for the energy "costs" associated to changing the sink site.
- The model accounts for the extra latency induced during the sink movements
- The model is independent of the nodes density.
- Partially controllable mobility and multi-sink scenarios can be easily accounted for

$$\text{Max } \sum_{k \in S} t_k$$

$$\sum_{k \in S} c_{ik} t_k + \sum_{k \in S} f_{ik} y_k \leq e_0 \quad i \in N$$

$$t_{\text{MIN}} y_k \leq t_k \leq M y_k \quad k \in S$$

$$\sum_{k \in S} x_{0k} = 1$$

$$\sum_{k \in S} x_{k,q+1} = 1$$

$$\sum_{\substack{j \in S \cup \{0\} \\ (j,k) \in OUA}} x_{jk} = \sum_{\substack{j \in S \cup \{q+1\} \\ (k,j) \in AUD}} x_{kj} \quad k \in S$$

$$\sum_{\substack{j \in S \cup \{0\} \\ (j,k) \in OUA}} x_{jk} = y_k \quad k \in S$$

$$u_j - u_k + q x_{jk} \leq q - 1 \quad (j,k) \in A$$

$$t_k, u_k \geq 0 \quad y_k \in \{0,1\} \quad x_{jk} \in \{0,1\}$$

# A few notes on the model

- $d_{\max}$  to bound the packet latency
- $t_{\min}$  to control the effect of the sink mobility rate
- Routing-independent approach (the reasons why to use a given routing protocol can go beyond the lifetime only)
- Extensions:
  - Each site can be traversed  $h$  times instead of 1
  - The model can capture partially controllable mobility and a multi-sink scenario

# Distributed Schemes: GMRE

- *We say the adjacent sites of a site are the sites within euclidean distance  $d_{max}$  from it*
- When the sink moves to a given site it also determines 'sentinels' for the adjacent sites  $k^*$  (i.e. nodes in the tx range of  $k^*$ )
- Every  $t_{min}$  the sink decides whether to move or stay
  - It contact each of the sentinels inquiring them about the residual energy around the associated site
  - Gather info on the sentinels
  - It moves drawn by the residual energies of the adjacent sites
    - If the current site is still the one with most residual energy it stays
    - Otherwise it move to the adjacent site with more residual energy
    - Residual energy= minimum residual energy of the nodes around the site

# Distributed Schemes: RM

- Every  $t_{\min}$  the sink moves randomly to one of the adjacent sites
  - Captures random mobility as in DATA MULES
  - Used for sake of benchmarking

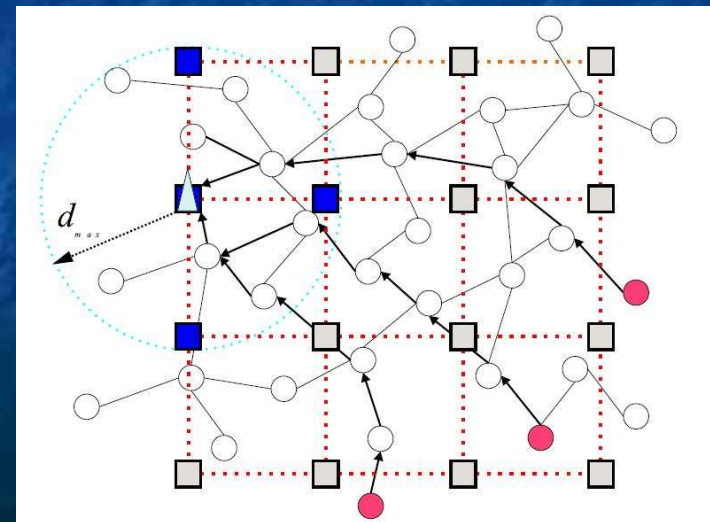
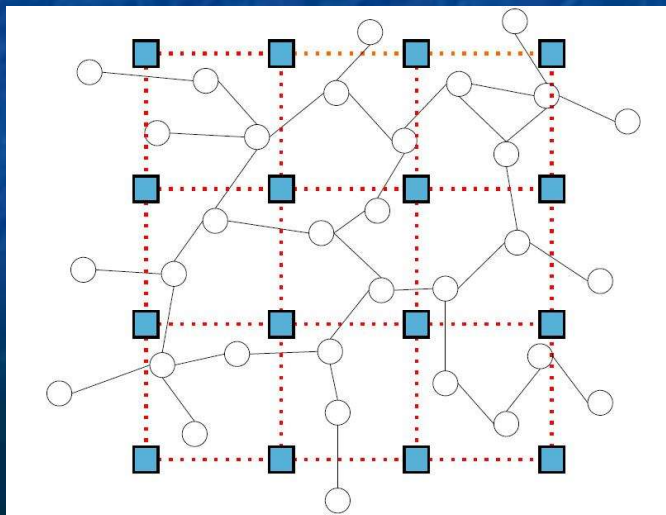
# Simulation scenarios

- Ns-2 based
- Compared the performance of
  - Optimum sink mobility (MILP model) → OPT
  - Static sink optimally placed → STATIC
  - Random Mobility → RM
  - Greedy Maximum Residual Energy heuristic → GMRE
- Metrics of interest:
  - Network lifetime
  - Residual energy over time
  - Latency
  - Overhead
  - Sojourn times at the different sites



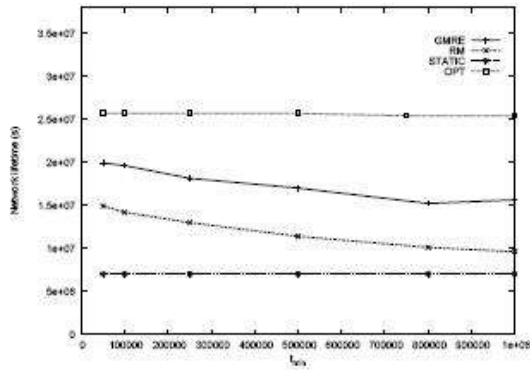
# First experiments: Basic Scenario

- Deployment area: 400mx400m square
- $n = 400$  nodes with 25m transmission range
- Sensor nodes initial energy 50J. Nodes equipped with TR1000 (14.8mW Tx, 12.5mW Rx)
- Data rate per node: 0.5bps, channel data rate: 250Kbps
- CSMA/CA MAC, “Shortest path like routing”
- Sink sites: 4x4,6x6,8x8 matrix
- $D_{max}=190m$

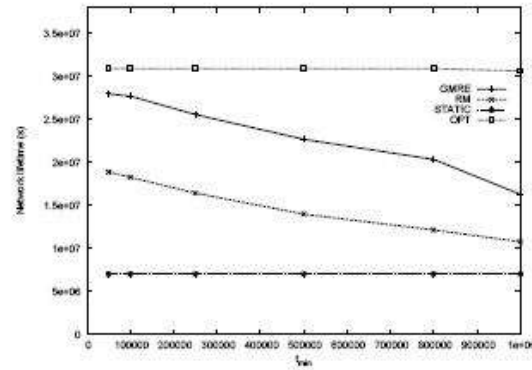


# Basic Scenario: Results

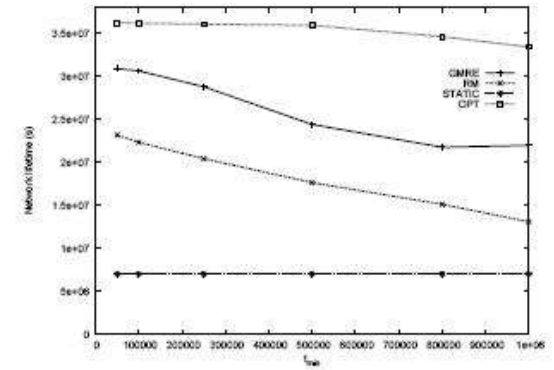
## Network Lifetime



(a)  $4 \times 4$  sink sites



(b)  $6 \times 6$  sink sites

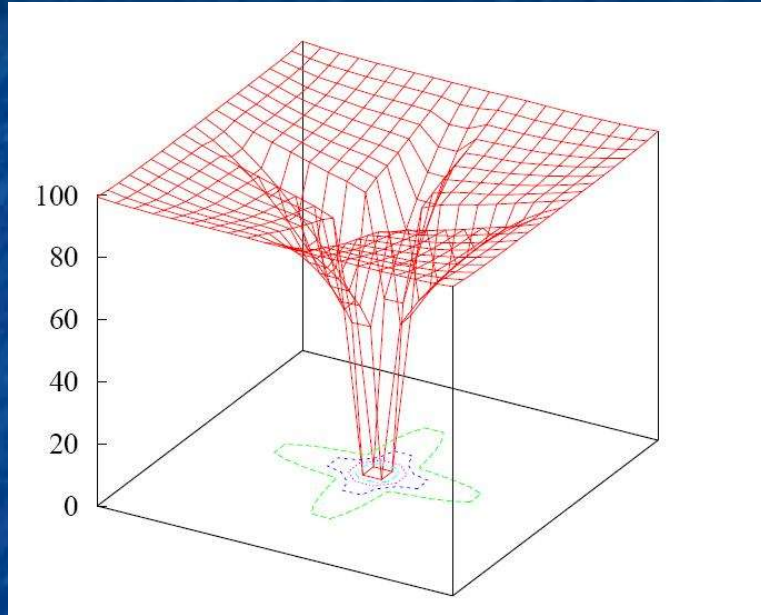


(c)  $8 \times 8$  sink sites

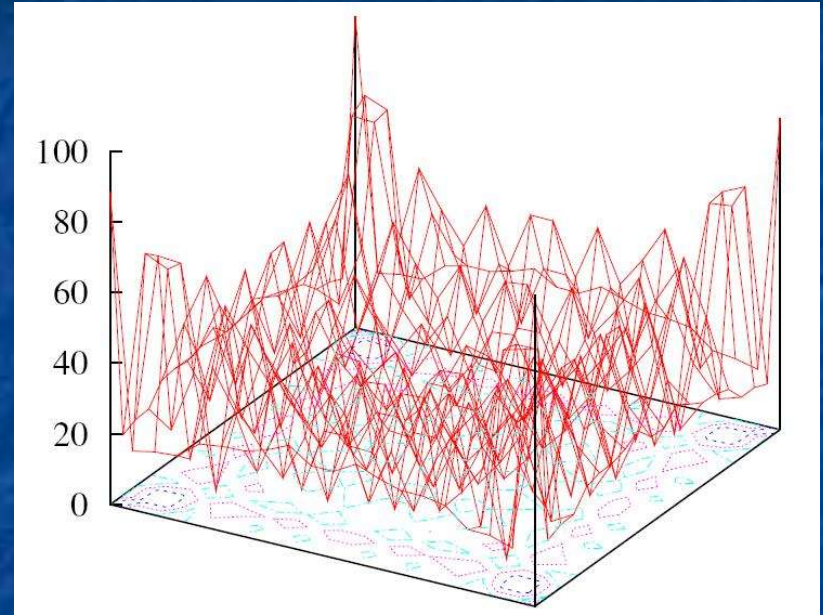
- GMRE:
  - 200-300% improvement over STATIC
  - 16-28% decrease wrt OPT lifetime
- RM:
  - 100-220% improvement over STATIC

*Small  $t_{min}$*

# Residual energies at lifetime



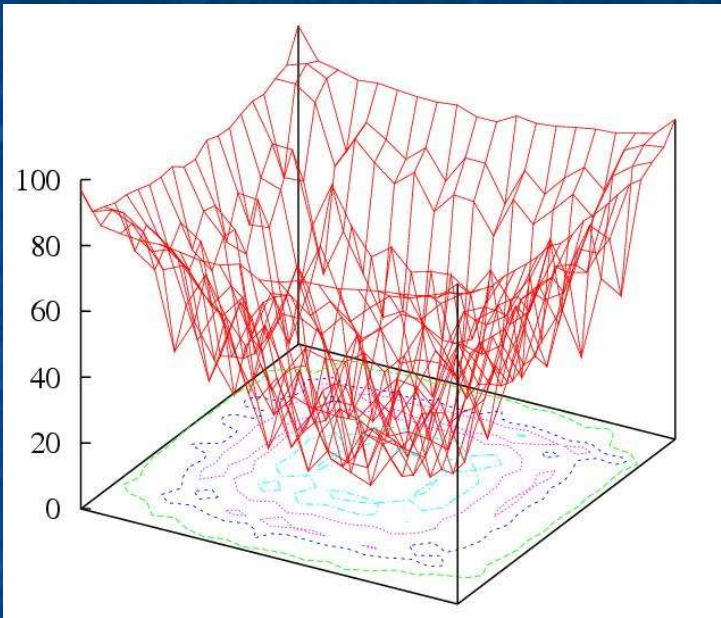
STATIC



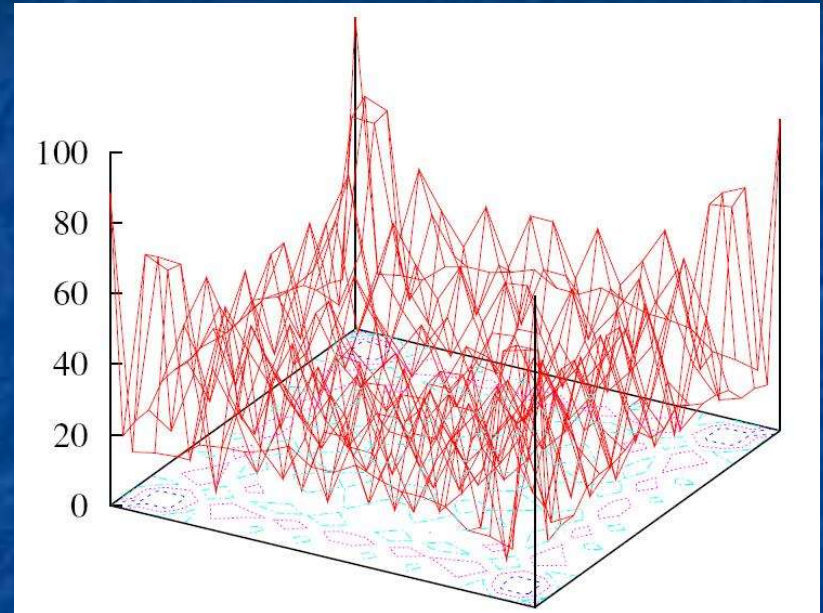
GMRE 8x8 sites

- **STATIC:** almost half of the nodes have  $>95\%$  of the initial energy left at lifetime!!
- The other schemes are better able to load balance energy consumption among network nodes: the better the higher the network lifetime

# Residual energies at lifetime



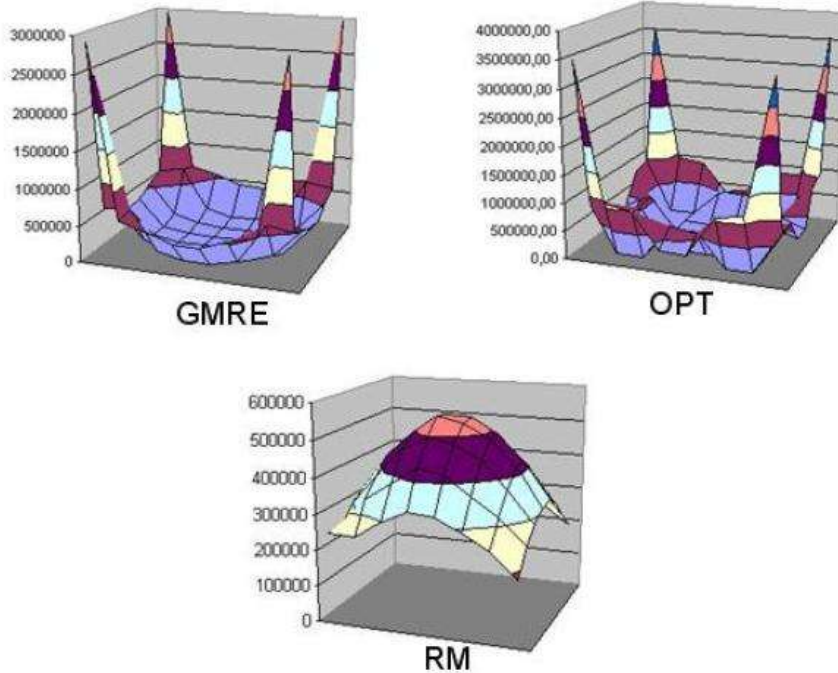
RM



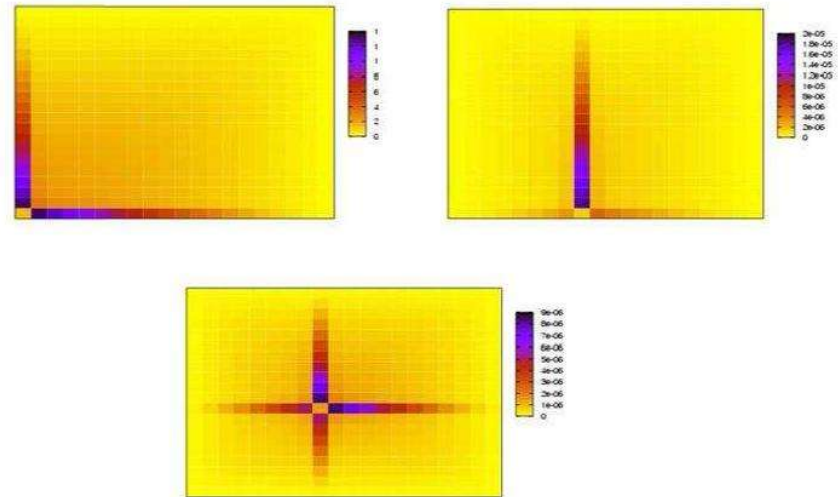
GMRE 8x8 sites

- The other schemes are better able to load balance energy consumption among network nodes: the better the higher the network lifetime

# Sojourn times



Sojourn times

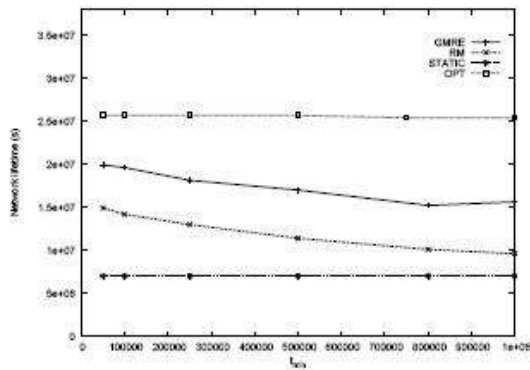


Energy consumption at the different Nodes when the sink stays at various Sink sites

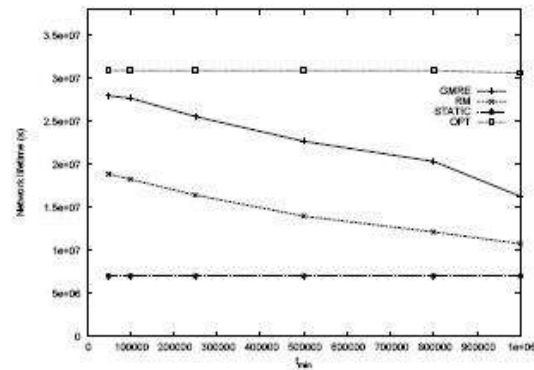
- RM does not account for residual energy
- OPT and GMRE spends most time at sites which impose High energy consumption on nodes otherwise not stressed
- OPT able to better fine tune sojourn times

# Basic Scenario: Results

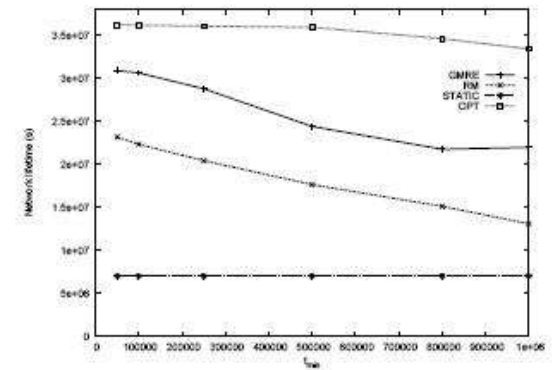
## Network Lifetime



(a) 4 × 4 sink sites



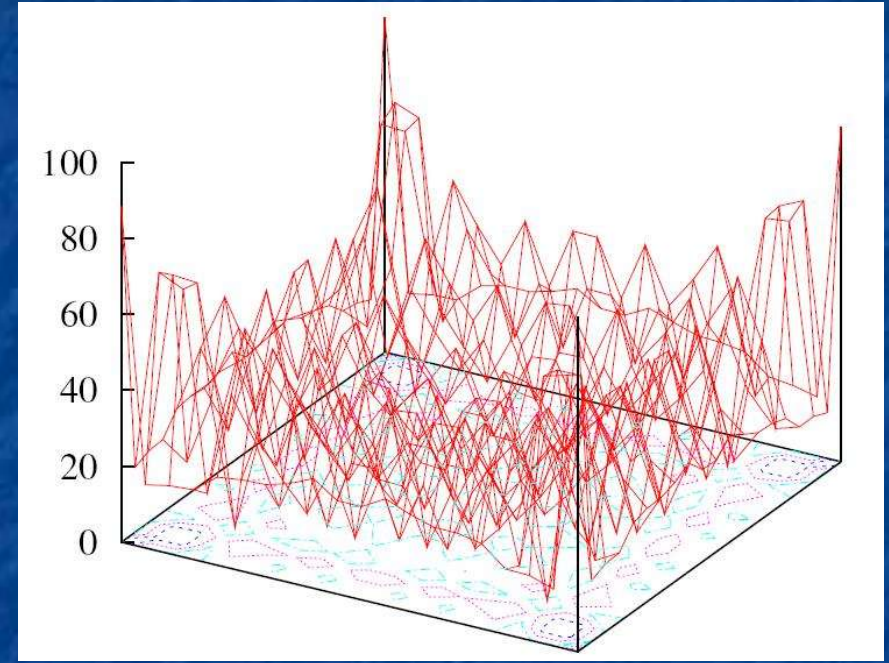
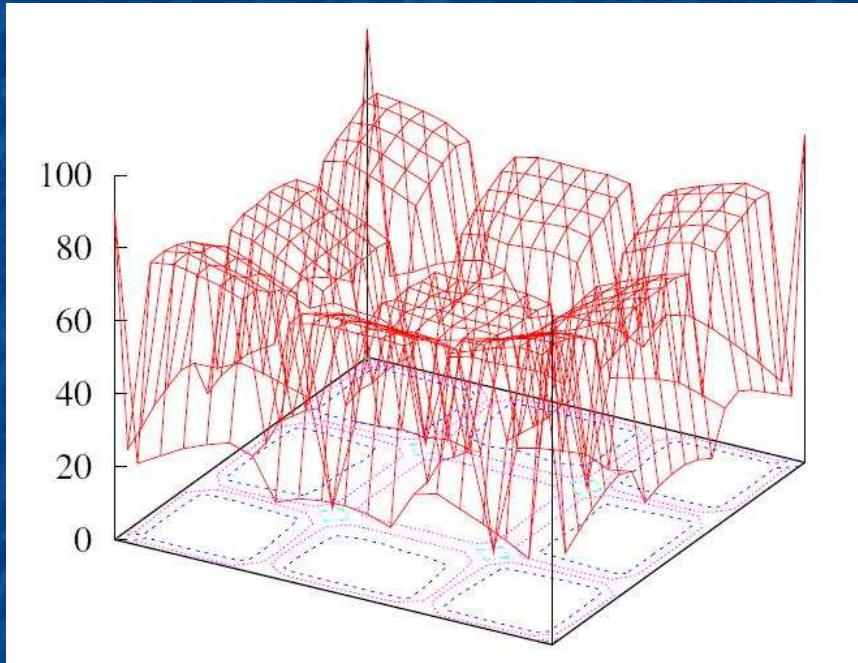
(b) 6 × 6 sink sites



(c) 8 × 8 sink sites

- Decreases with  $t_{\min}$  (low  $t_{\min}$  better tuning of the sojourn times, less price to pay in case of a bad move)
- Increases with number of sites (better ability to drain energy from all the different parts of the network)

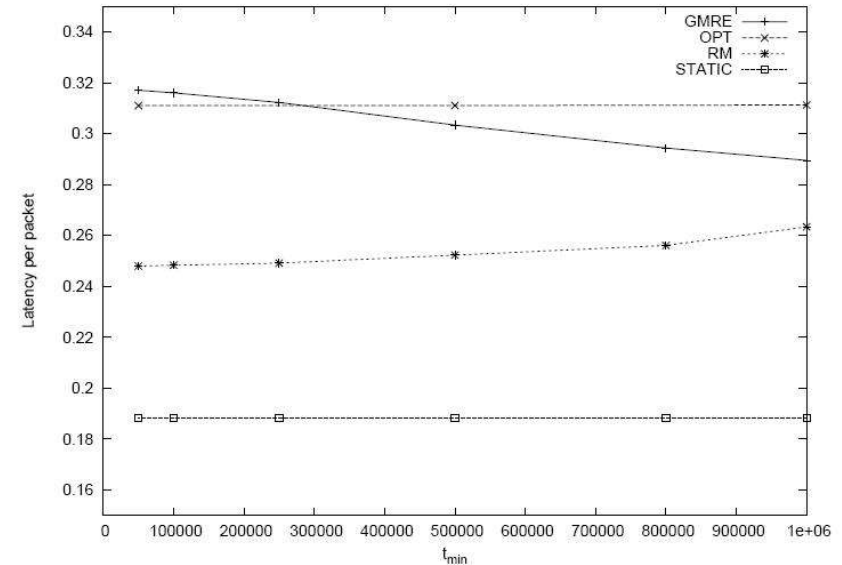
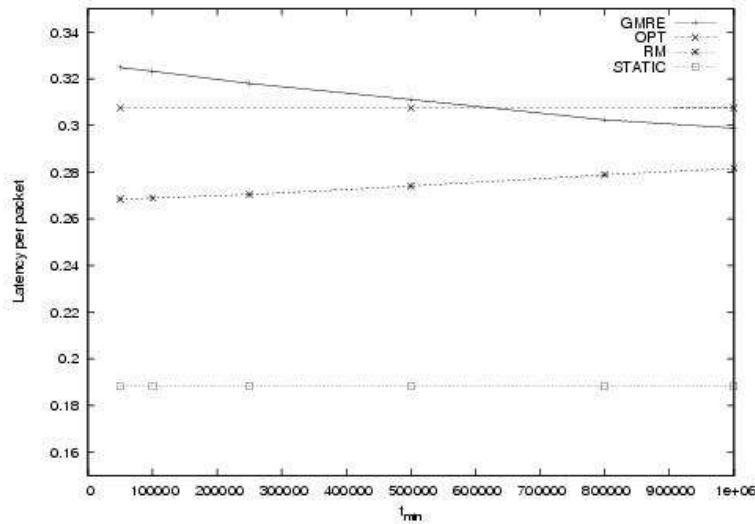
# Impact of changing the number of sink sites



- GMRE, 16 and 64 sink sites
- Increasing the number of sink sites improves the ability to drain energy from all the different parts of the network

# Packet Latency

## Packet Latency

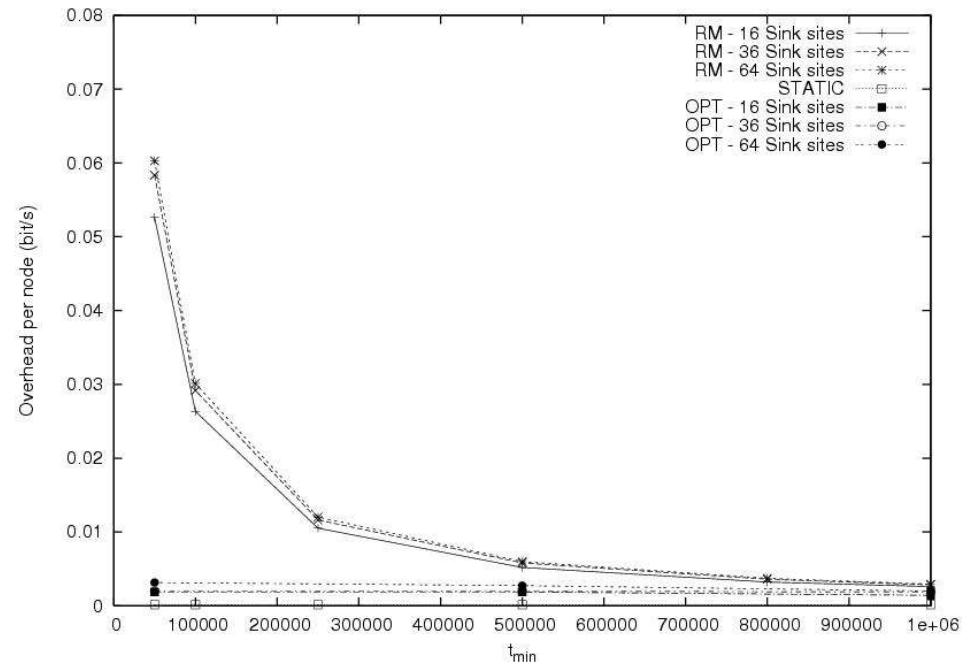
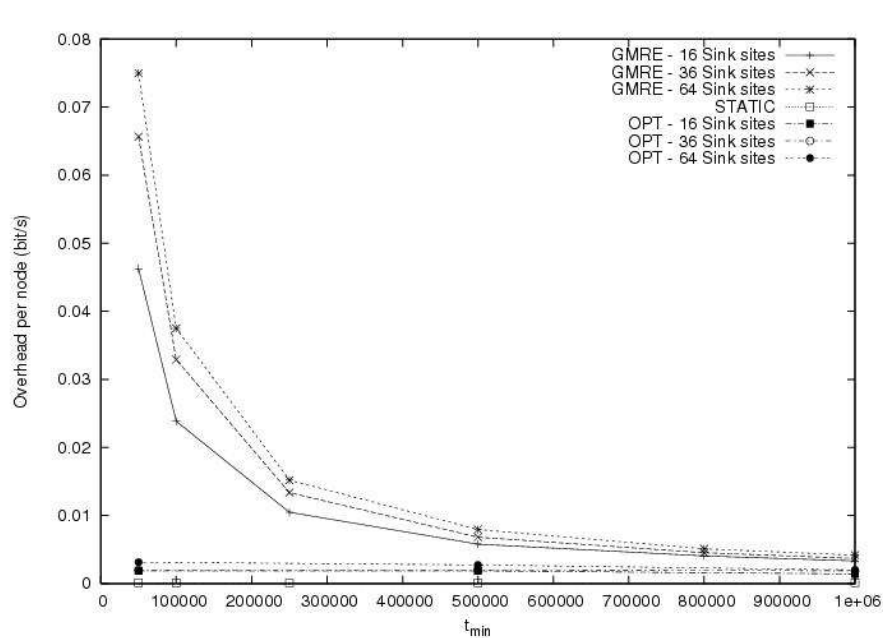


- Schemes which tend to stay also in external areas (for sake of energy conservation) results in higher latencies



# Overhead

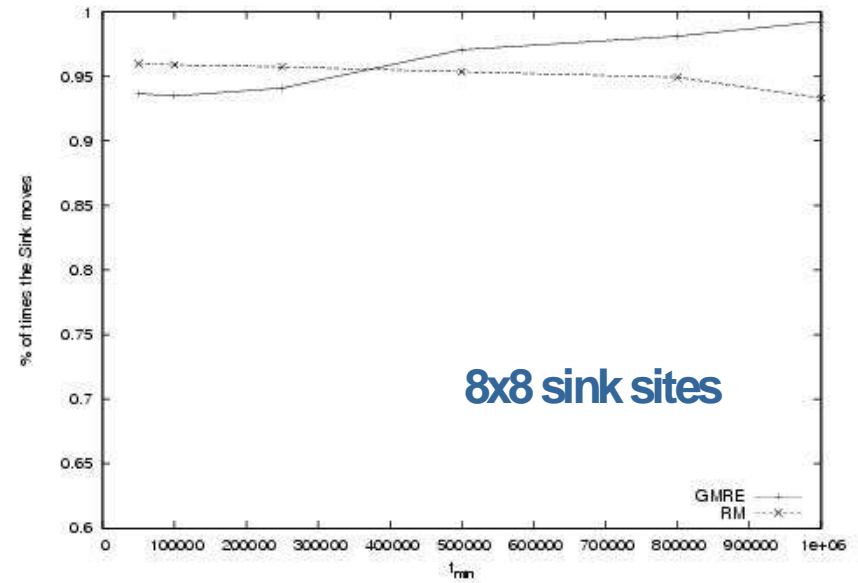
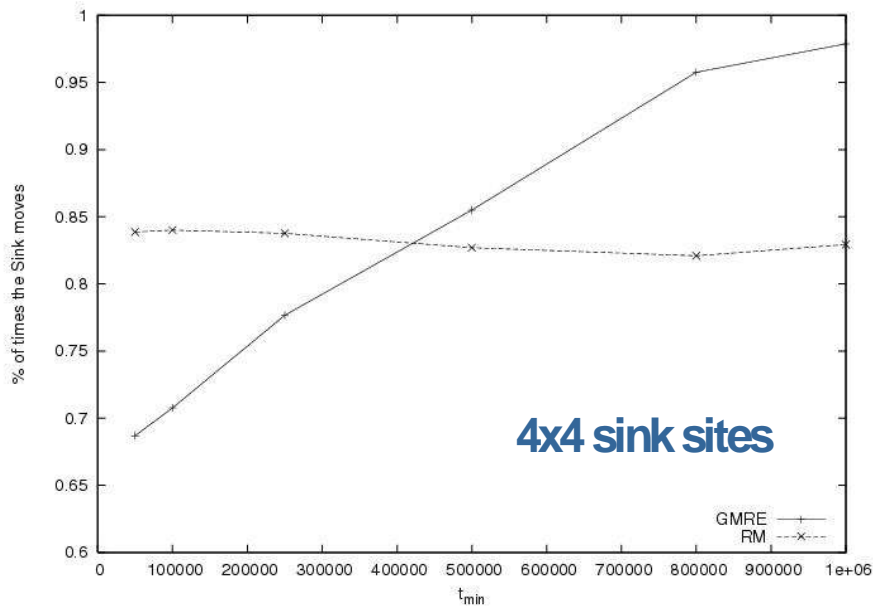
## Overhead (bps)



- OPT and STATIC result in basically no overhead
- GMRE and RM overhead decreases when the sink mobility rate decreases
- GMRE has higher costs (to inquiry sentinels and compute residual energies) → especially at high num. sites

# Percentage of times the sink moves

## Percentage of times the sink moves

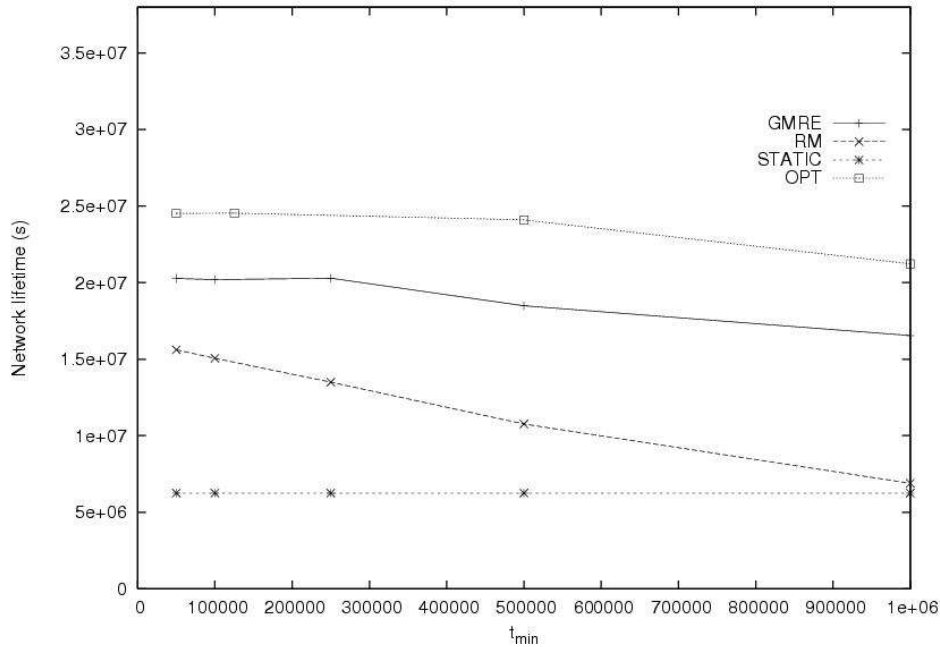


- Sink always almost moves
- The higher  $t_{min}$  the more RM stays at the external part of the area → the less it moves
- The higher  $t_{min}$  the more in GMRE is likely that one of the adjacent sites has more residual energy → the more the sink moves

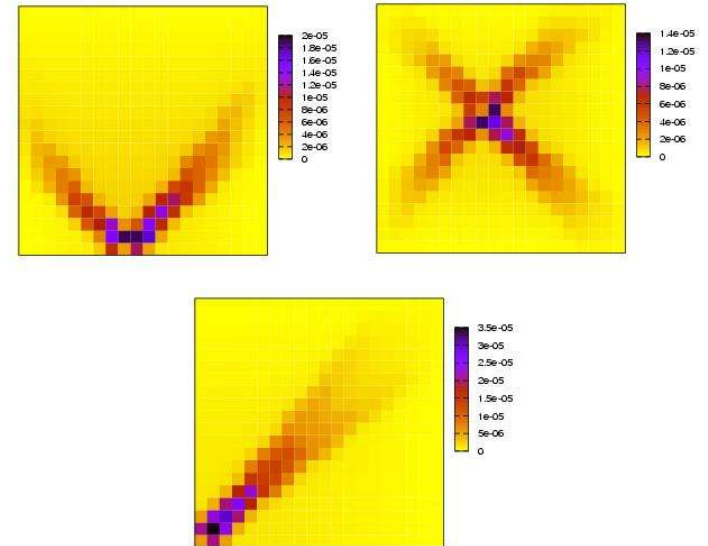
# Other Results

- We have tested the proposed schemes when
  - Changing the transmission range or routing ( $\rightarrow$  changes the sojourn times and sink route but does not change the relative behavior of the different schemes)
  - Varying  $d_{\max}$  (little effect in terms of lifetime)
  - Imposing limits on the area where the sink can stay
- Results show that the mobility pattern **DEPENDS** on the specific scenario but that the proposed heuristic well adapts to the different scenarios achieving performance close to the optimum.

# GeRaF Results



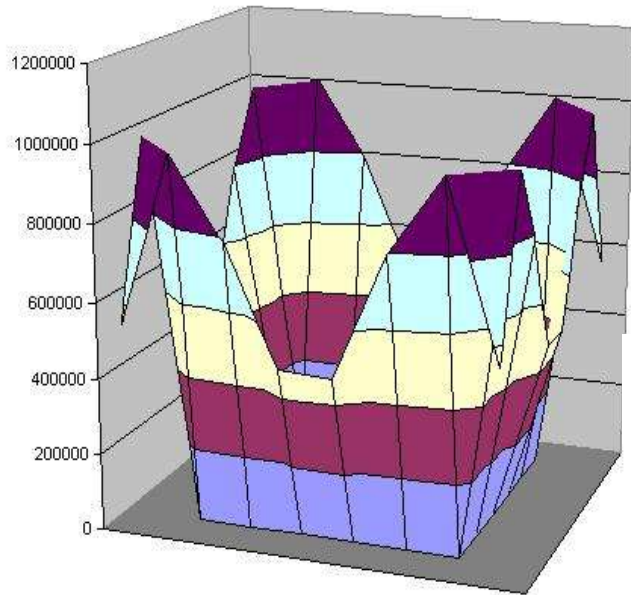
Network Lifetime



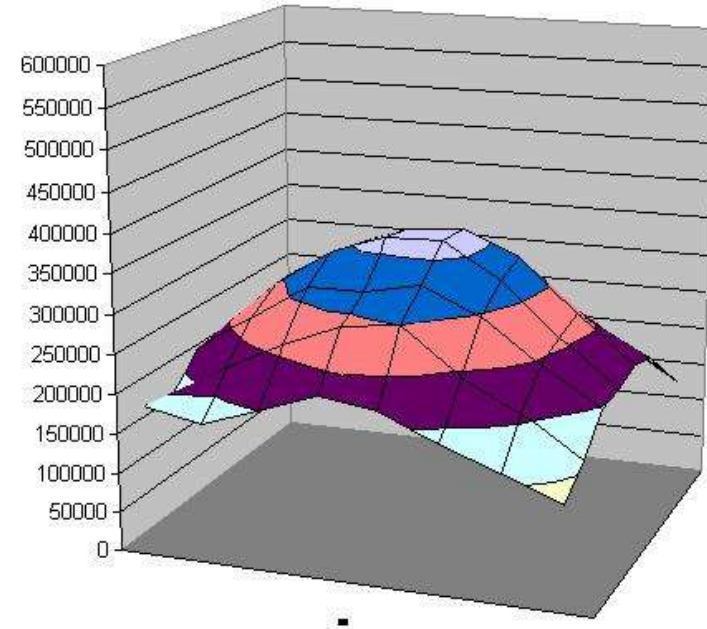
Energy costs

- OPT better than GMRE better than RM better than STATIC
- Changing routing changes energy cost at node  $i$  to forward data, changes sojourn times and sink route

# GeRaF Results – Sojourn Times

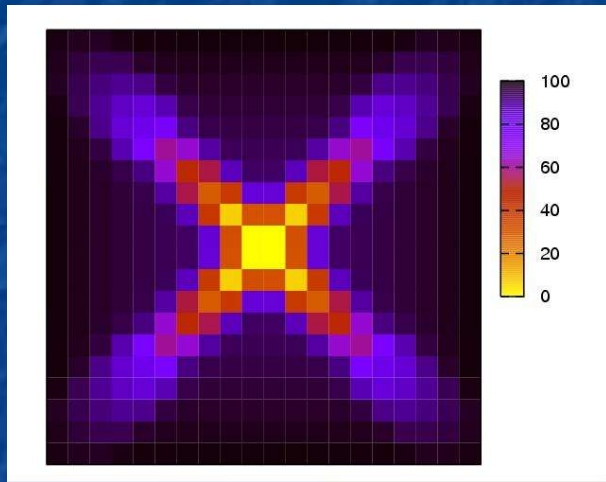


GMRE

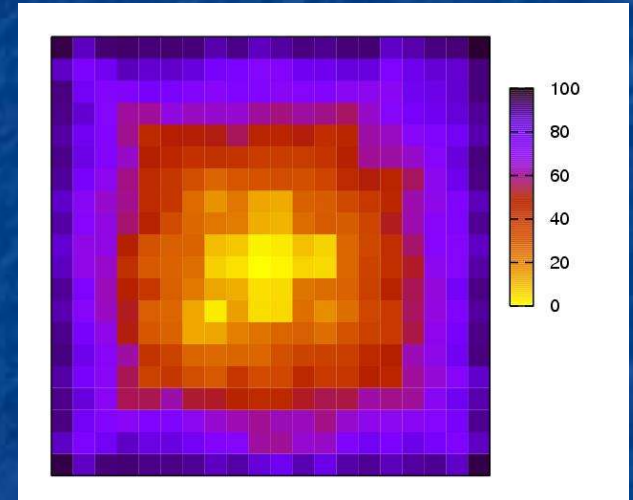


RM

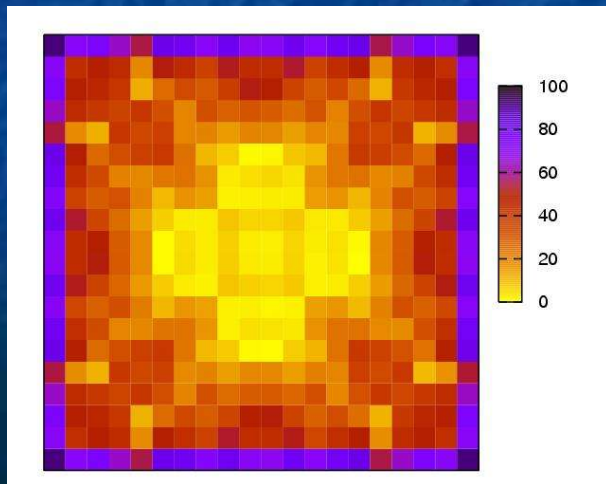
# GeRaF Results – Residual energy at network lifetime



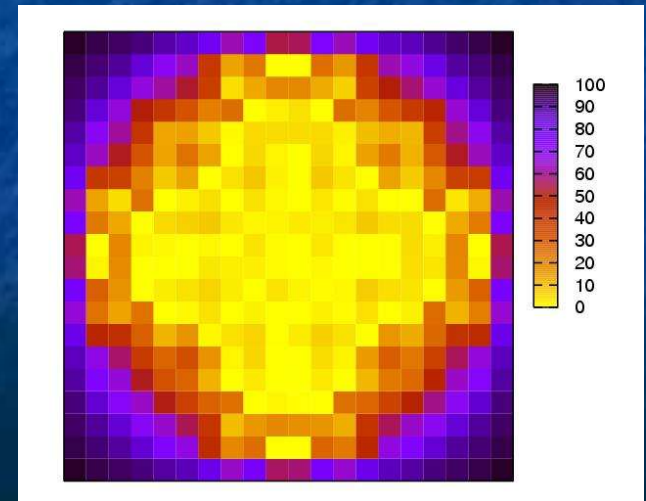
STATIC



RM

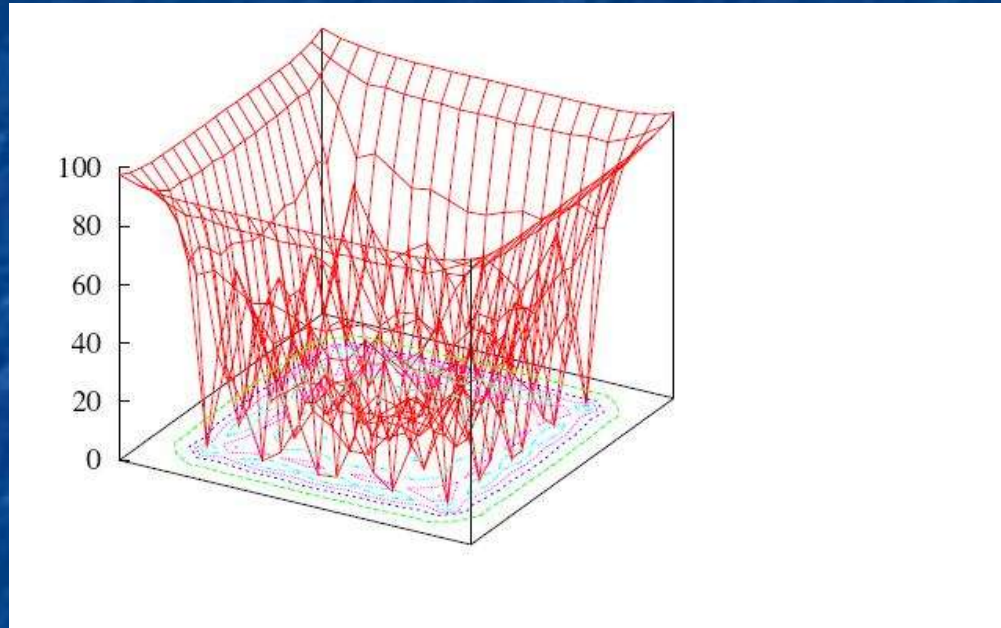


GMRE



OPT

# Limiting the sink sites



GMRE residual energy at lifetime: 50Ks

- OPT and GMRE very close for low  $t_{\min}$
- Both are able to very effectively drain energy from all the internal areas in the network (external areas only consume little energy as the sink cannot visit them)

# Limiting the sink sites

Sojourn times:  $t_{\min} = 50,000s$

