



SAPIENZA
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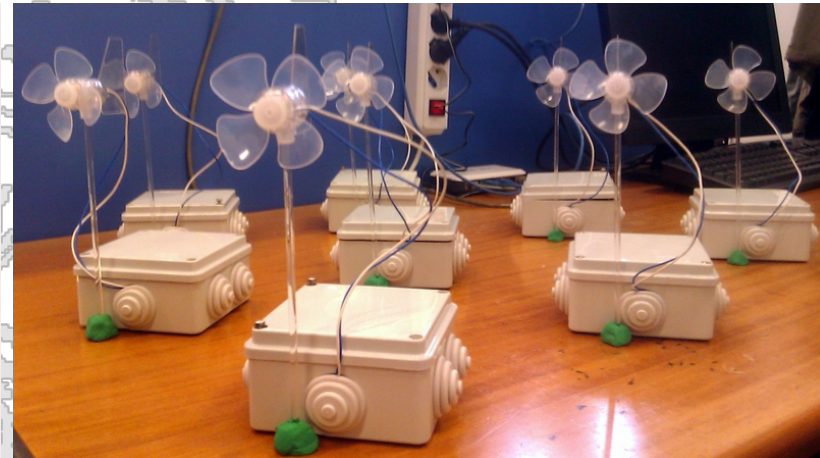
Protocols for EH-WSNs

Sistemi Wireless, a.a. 2013/2014

Un. of Rome "La Sapienza"

Chiara Petrioli[†]

[†] *Department of Computer Science – University of Rome "Sapienza" – Italy*

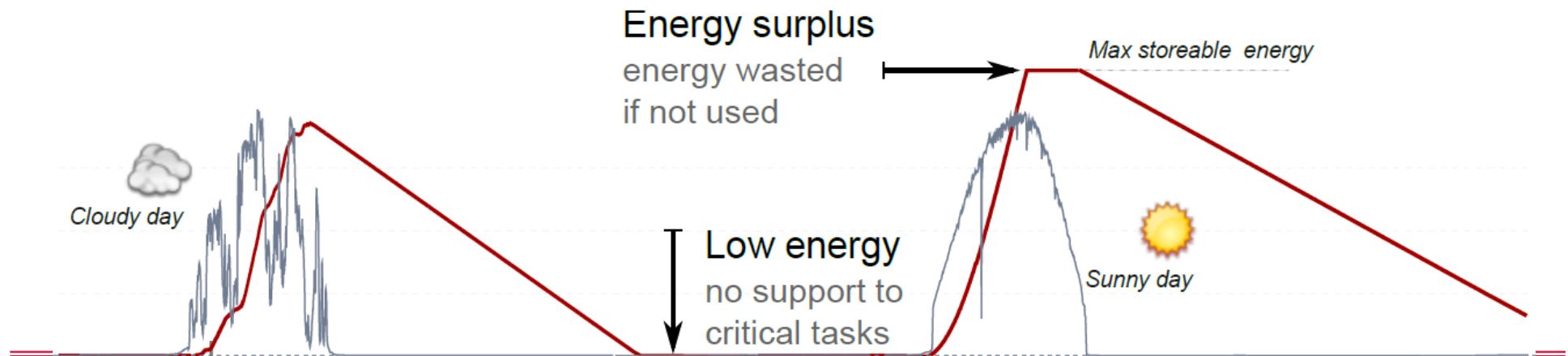


- Pose the basis for very long lasting operation
- Energy Neutral protocols have been proposed for several applications
- Changes also what a WSN can do



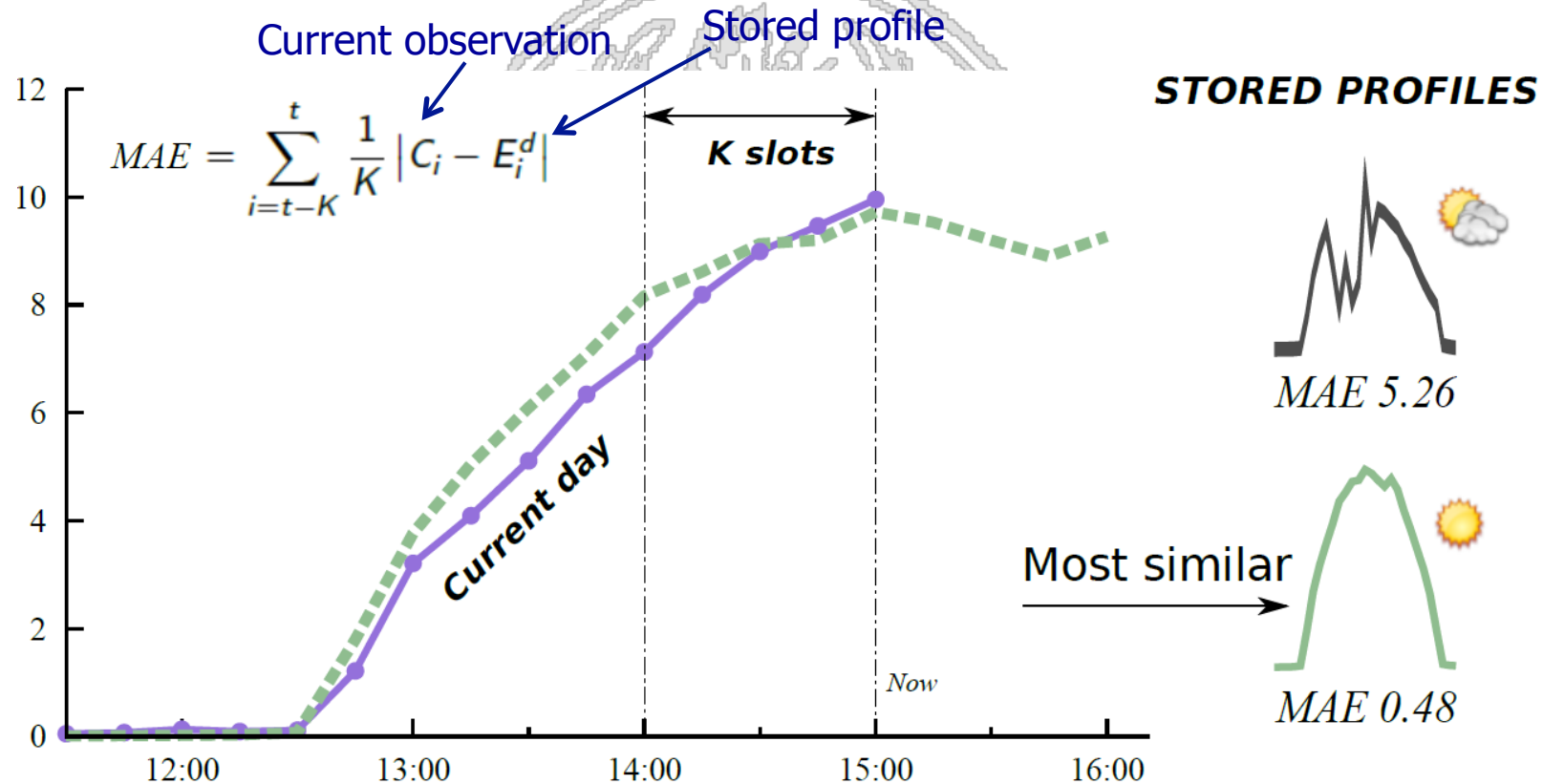
Why energy predictions?

- Energy predictions to mitigate uncertain energy availability
- Plan energy usage in advance: **proactive** vs reactive energy allocation
- Exploit available energy at best:
 - I. Minimizing the likelihood of running out of energy and missing high priority tasks
 - II. Minimizing the waste of energy (energy buffers are limited in size and time)
 - III. Enable operations which were not considered feasible






- Keep track of energy profiles observed during D typical days
- Store traces representative of different weather conditions (sunny, windy, ...)
- Predict future energy intake by looking at the most similar stored profile






$$\hat{E}_{t+1} = \alpha \cdot C_t + (1 - \alpha) \cdot E_{t+1}^d \quad (2)$$

where:

\hat{E}_{t+1} is the predicted energy intake in timeslot $t + 1$ of the current day;

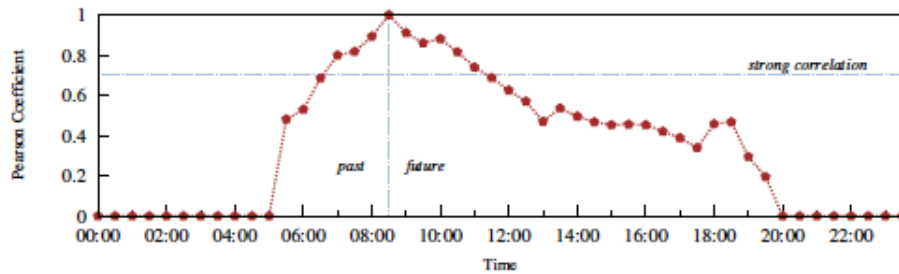
E_{t+1}^d is the energy harvested during timeslot $t + 1$ on the stored day d ;

C_t is the energy harvested during timeslot t on the current day C ;

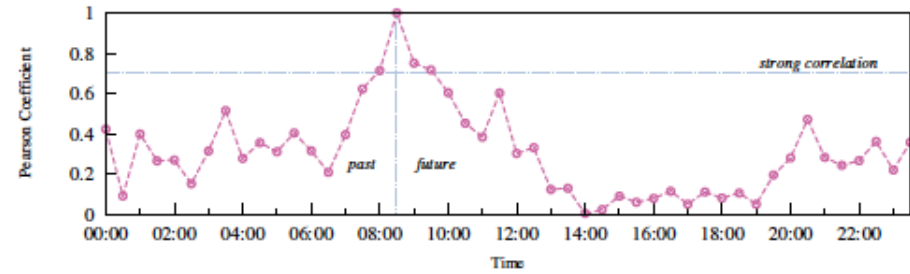
α is a weighting factor, $0 \leq \alpha \leq 1$.

The weighting parameter, α , allows to combine the value reported in the stored profile with the current energy observation, i.e., the energy observed in the last slot, C_t .





(a)



(b)

Figure 2. Pearson autocorrelation coefficient for (a) solar ORNL Dataset and (b) wind Bologna Dataset.

$$\gamma_i = \begin{cases} \alpha \cdot \left(1 - \frac{i-1}{G}\right), & \text{if } i \leq G \\ 0 & \text{if } i > G \end{cases} \quad \forall i, 1 \leq i \leq F$$

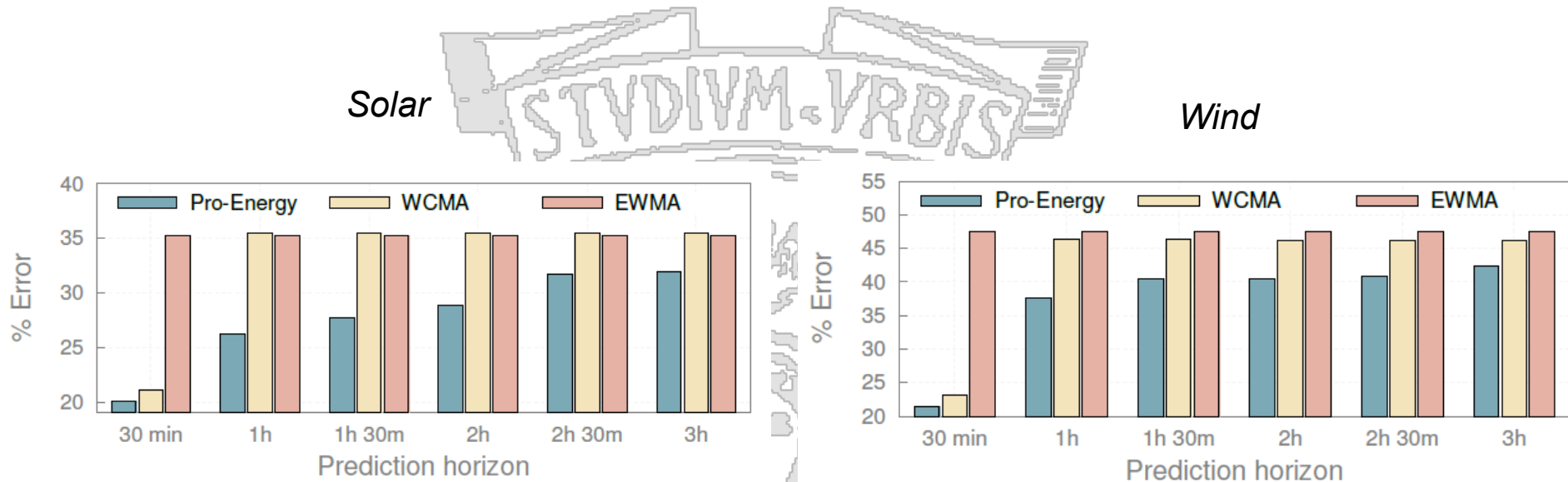
where:

- α is the weighting factor defined in Equation (2);
- i is the i^{th} timeslot in the future, with respect to the current slot, t ;
- G is the number of timeslots in the future which show a correlation above a given threshold with timeslot t ;
- F is the number of future timeslots for which Pro-Energy is delivering energy predictions.



Medium term energy
prediction
estimation

$$\hat{E}_{t+i} = \gamma_i \cdot C_t + (1 - \gamma_i) \cdot E_{t+i}^d$$



Solar: Pro-Energy performs up to **75%** better than EWMA and **60%** better than WCMA

Wind: Pro-Energy performs up to **55%** better than EWMA and **10%** better than WCMA

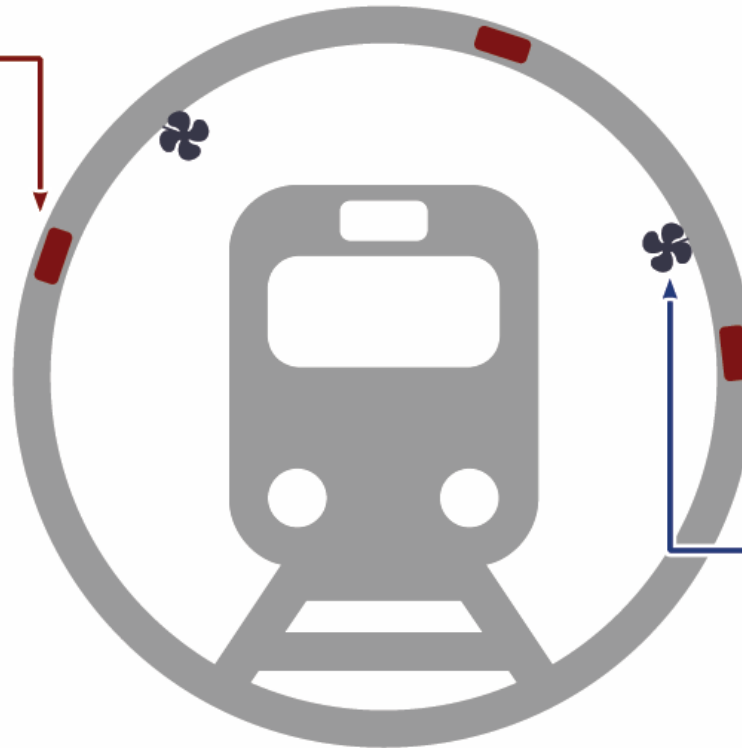


Vibrating Wire Strain Gauges

Monitor concrete and steel deformations to evaluate stability of the underground tunnel



SISGEO OVK4200VC00
Dedicated interface board for TelosB mote
Energy consumption: 720 mJ

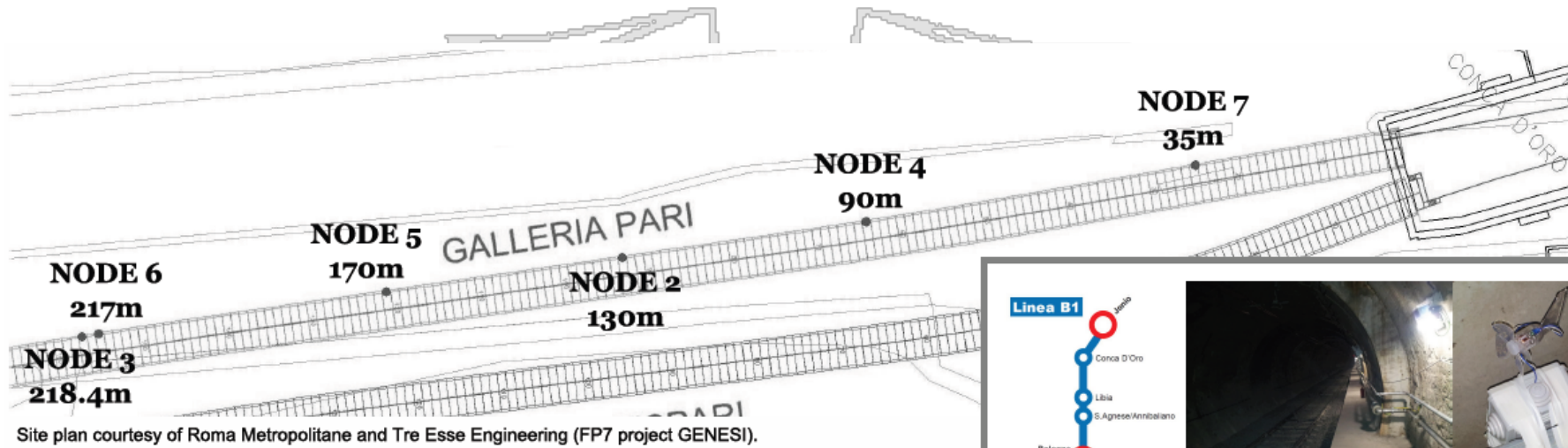


Micro wind turbines

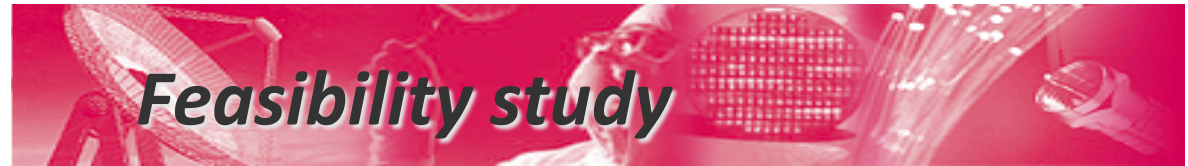
Energy harvesting from wind generated by trains

Why air-flow energy harvesting?

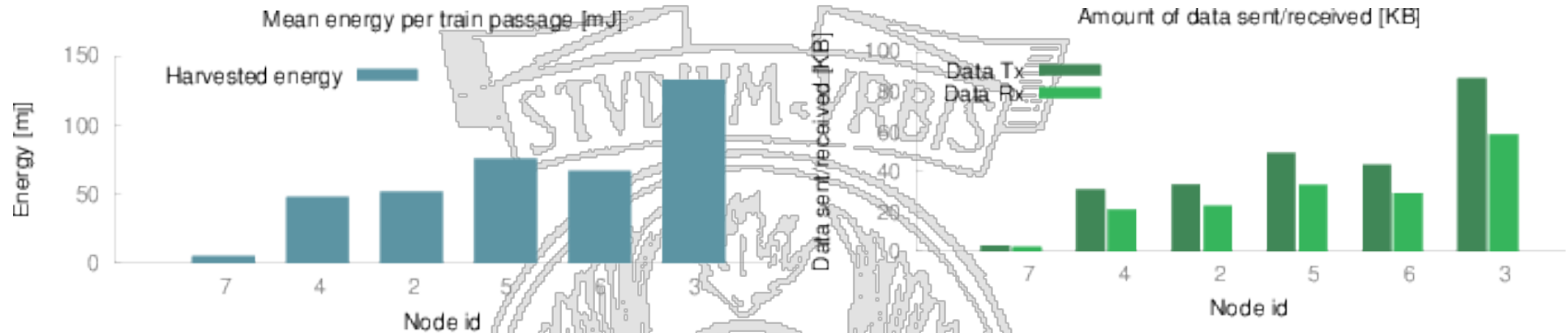
- SHM sensors are power-hungry
- required lifetime of decades or more
- battery-powered WSNs last only a few years



220 meter of instrumented tunnel
6 energy-harvesting nodes
33 days of data collection

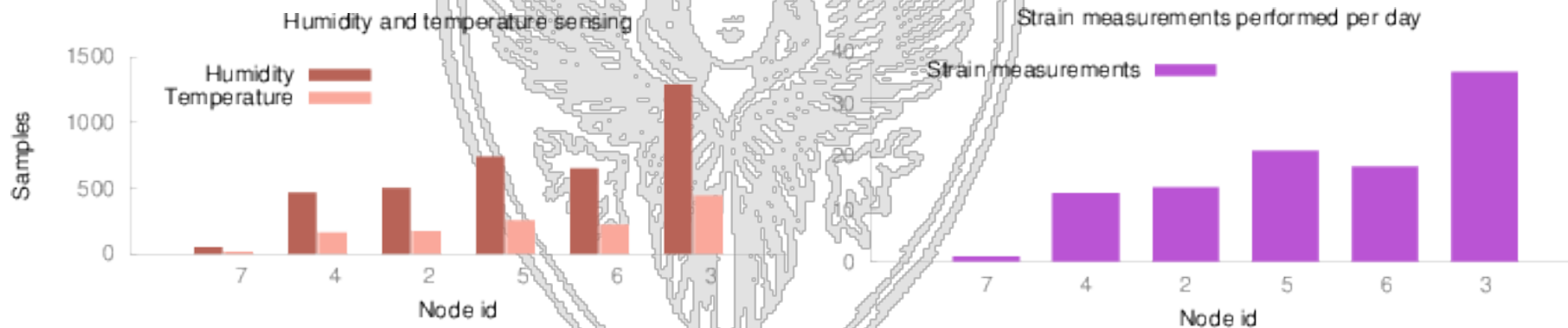


Feasibility study



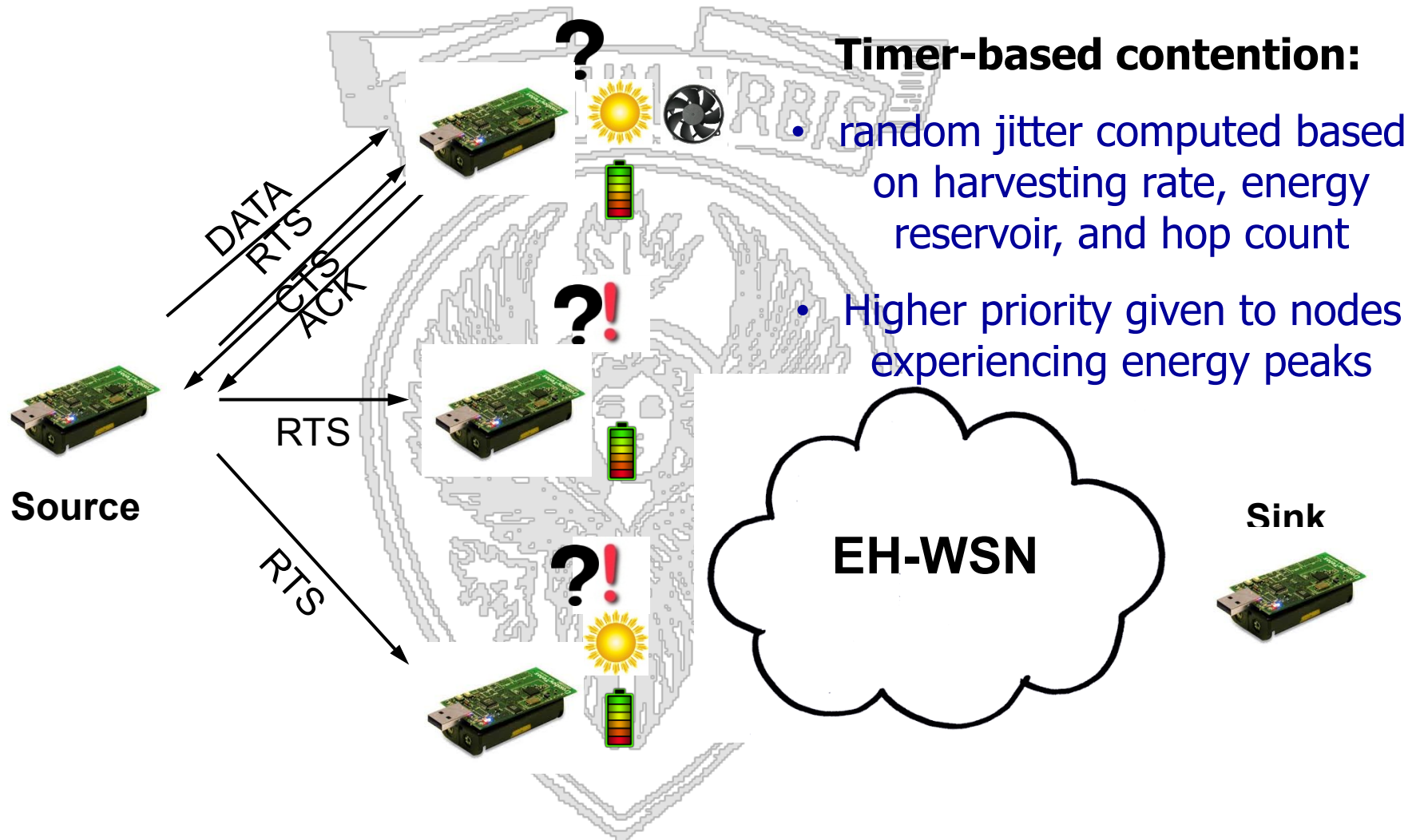
Up to 133 mJ harvested per train passage

Transmit/receive tens of KB



Collect hundreds of humidity and temperature samples

Up to 36 strain measurements per day

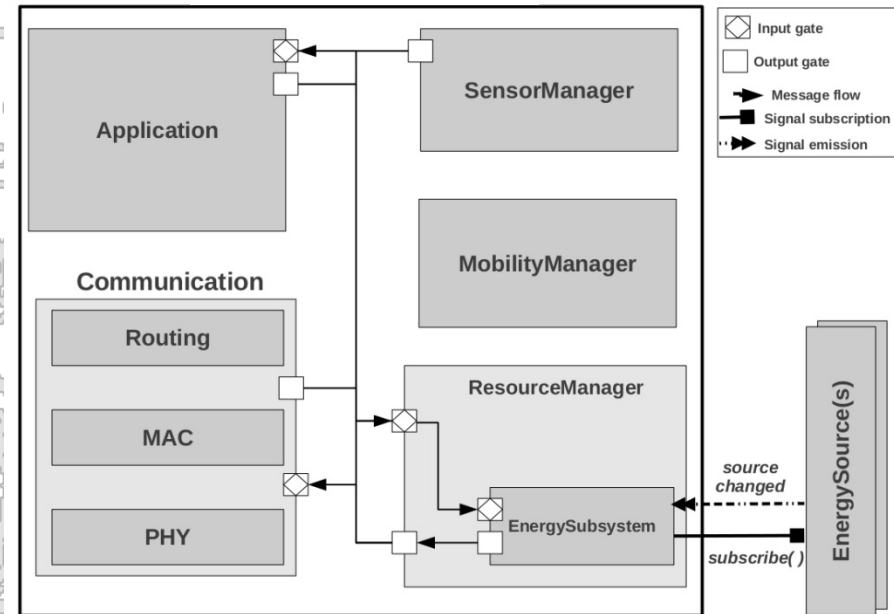




GreenCastalia features

- Support for multi-source harvesting
- Support for multi-storage devices
- Support for energy predictions
- Easily customizable
- Based on Castalia / OMNET++

Sensor node



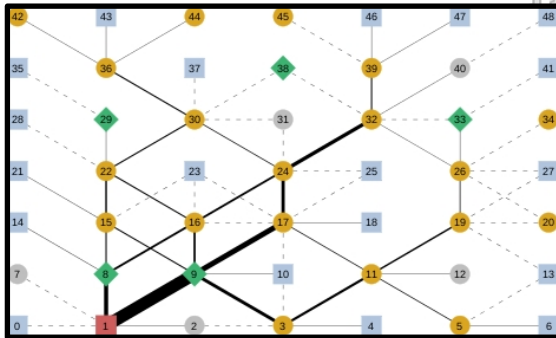
TraceEnergySource module: allows to feed the simulator with timestamped power traces collected through real-life deployments, or with energy availability traces obtained by data repositories or meteorological stations



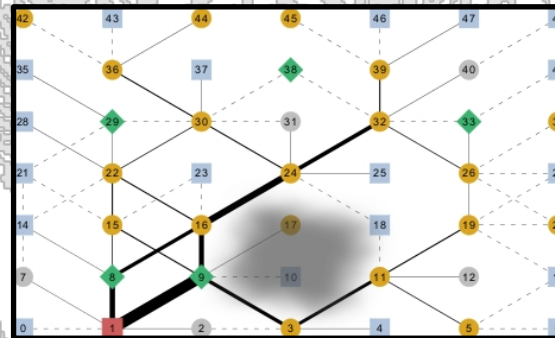
Simulation settings

- 120x120 meters field (7x7 grid deployment)
- Nodes with heterogeneous energy harvesting capabilities:
 - solar, wind both, none

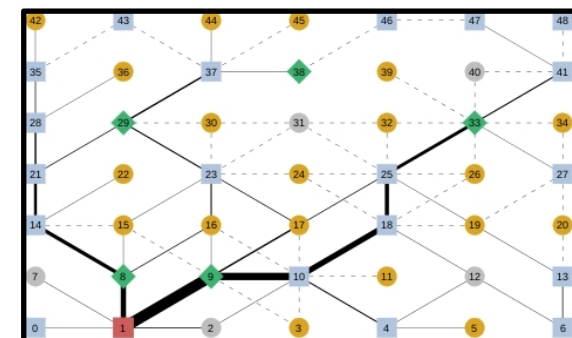
11am



5pm with shadow zone



8pm



Self-adaptive behaviour: nodes experiencing energy peaks are selected with higher priority as next hop relays

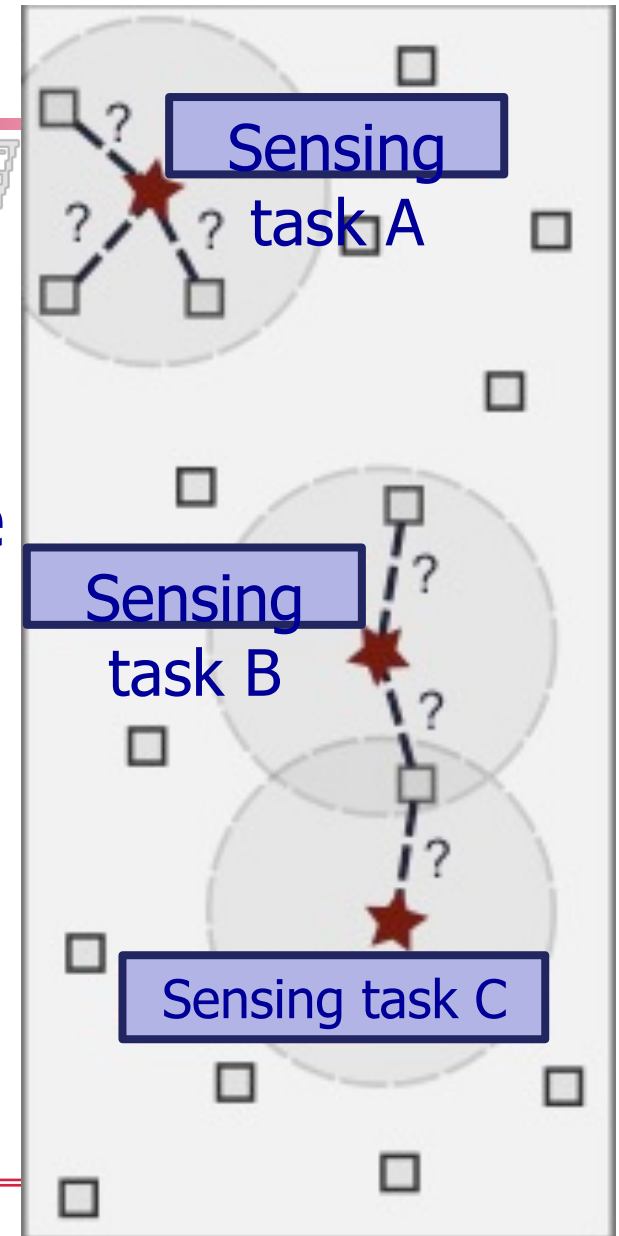


Task allocation



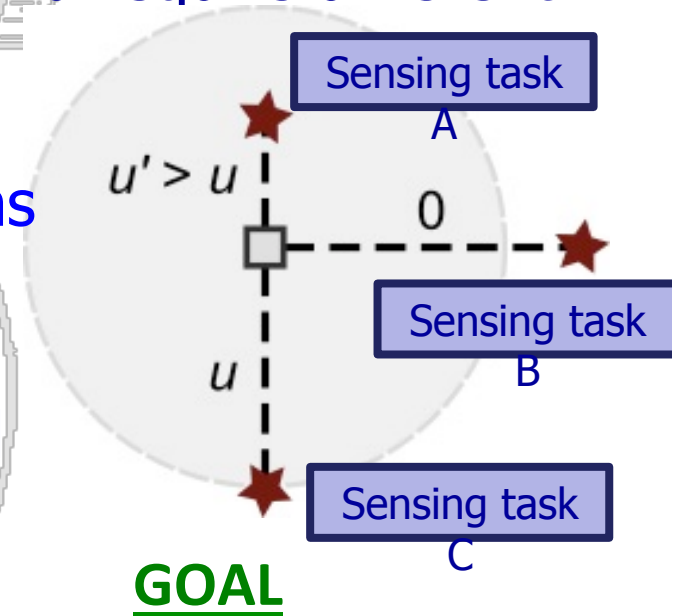
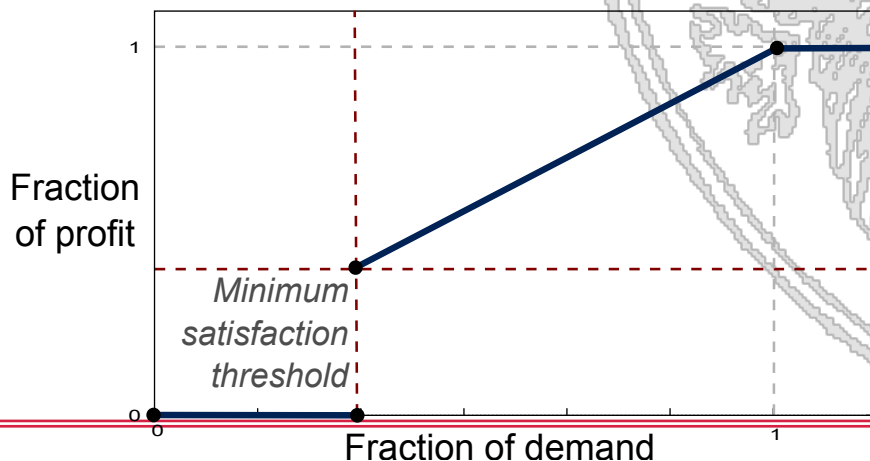
- Sensing tasks (missions) arrive in the network dynamically over time at different locations
- Multiple missions active at the same time, competing for the sensing resources of the network

Decide which sensor(s) should be assigned to each mission





- Missions have different priority (profit) and require different amount of resources (demand)
- **Assignments are not all equal..**
 - Nodes contribute to different missions with different **utility (quality of information)**
 - Achieved profit depends on allocated demand



Maximize the profit obtained by the network for missions execution within a given **target lifetime**

- Distributed heuristic for task allocation in WSN with **energy harvesting**
- Nodes make independent decisions about task execution
- Decision based on:

**Partial
profit**



1. Profit of the mission
2. Potential contribution to the mission

**Tune
eagerness**



3. Target network lifetime

**Classify
missions**



4. Current energy level of the node (fuel cell + supercap)
5. Energetic cost of the mission
6. Future energy availability

A new mission arrives
energy availability



check energy requirements and

Fuel cell/battery required not enough energy in the supercapacitor to execute the mission; use energy from the fuel-cell

Capacitor sustainable mission energy cost sustained by supercapacitor

Recoverable mission energy cost sustained by supercapacitor AND energy cost recovered through harvesting before the next mission arrives

Free mission energy cost expected to be fully sustained by energy harvesting

More
willing to
accept



A new mission arrives
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More willing to accept



REQUIRE ENERGY PREDICTIONS



Always for free missions

- Expected partial profit of a mission

$$\bar{p} = \frac{E[u]}{E[d]} \times \frac{E[p]}{P},$$

P maximum achievable profit: E[u], E[d], E[p] expected utility, demand and profit of a given mission

- Partial profit achievable by a node participating to a mission

$$p^* = \frac{e_{ij}}{d_j} \times \frac{p_j}{P} \times w_i$$

w weight which depends on mission classification. Bid if $p^* \geq$ expected partial profit

Task-Allocation

EN-MASSE-In summary



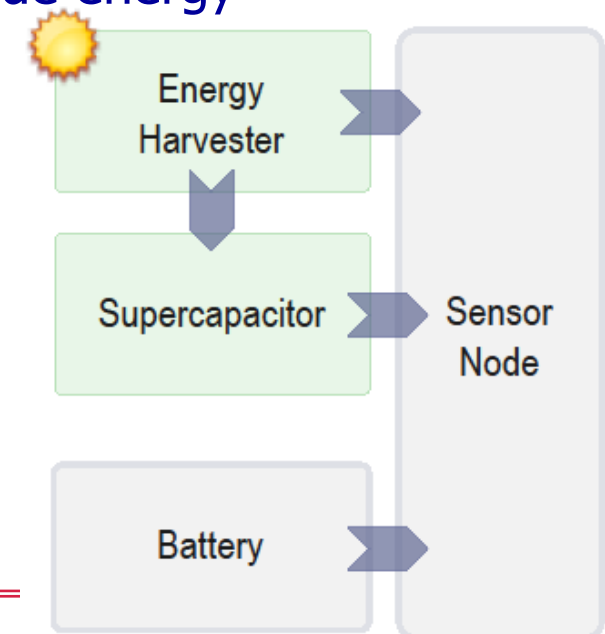
A **decentralized** harvesting-aware heuristic

Key features:

- Uses short and long term energy predictions for pro-active energy allocation
- Takes into account missions arrival statistics to make sustainable allocation decisions
- Considers the impact of executing a mission on node energy

Higher priority to less-impacting missions

1. **Free:** fully sustained by harvesting
2. **Recoverable:** sustained by supercapacitor and recovered before next mission
3. **Capacitor-sustainable:** sustained by supercapacitor
4. **Battery-required:** sustained by battery



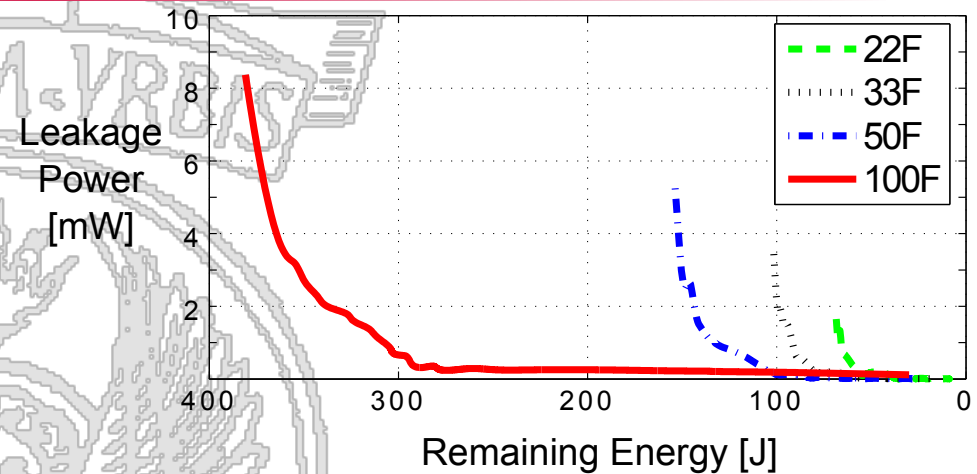


Modeling real harvesting systems



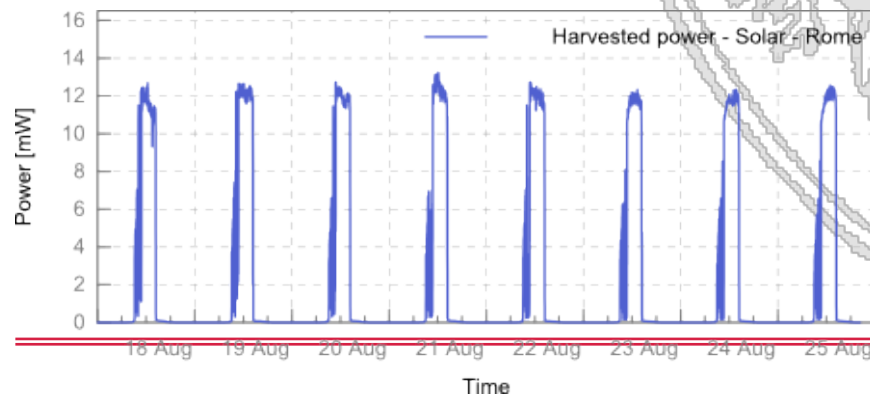
Non-ideal supercapacitors

1. Finite size
2. Charging\discharging efficiency < 1
3. Leakage\self-discharge

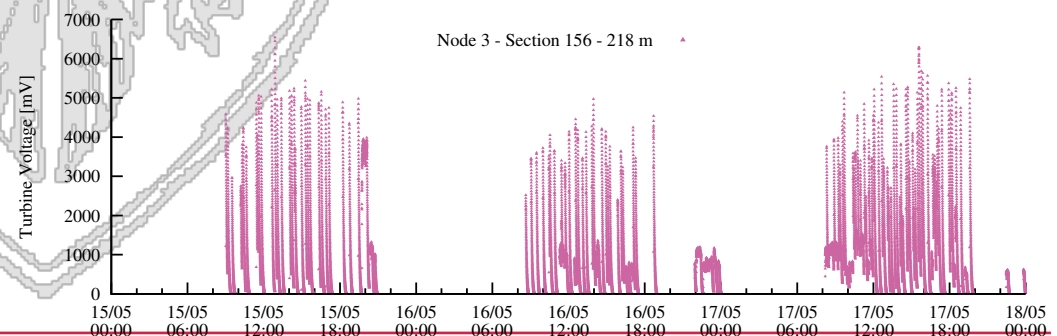


Real-life energy traces

Photovoltaic cells



Wind micro-turbines

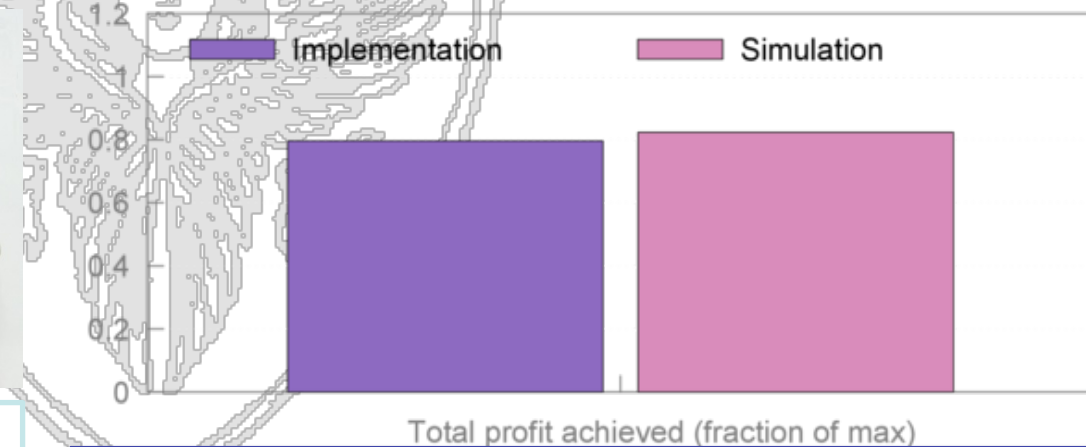
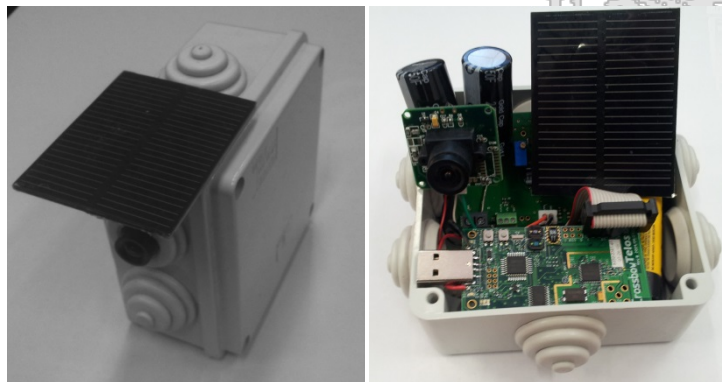


Performance evaluation



Profit: up to 60% higher than SoA

Stable profit: 70-80% of maximum



In-field testbed validation

Gap between simulations and testbed:
less than 3% of maximum profit



- Scritto su tutti gli argomenti del corso
- Orale su tutti gli argomenti del corso
- Scritto di "sbarramento"+Progetto (da concordare con il docente; dovrete avere visto delle proposte ma dovete averlo assegnato)
- Scritto/orale su parte del programma+ Tesina (potete sostituire articoli da leggere su un argomento che preferite non approfondire per approfondire leggendo paragonabile numero di articoli un argomento collegato che vi interessa).
 - Esempio di tesine su reti di sensori:
 - ✓ Adaptive Sampling e outlier detection
 - ✓ Low power MAC in reti di sensori
 - ✓ Energy harvesting aware routing
 - ✓ Wireless transfer enabled communication
 - ✓ Protocols under standardization for WSNs (Wireless Heart, ROLL etc)-confronto