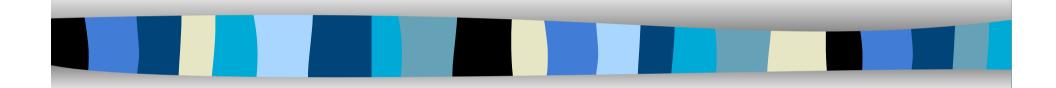
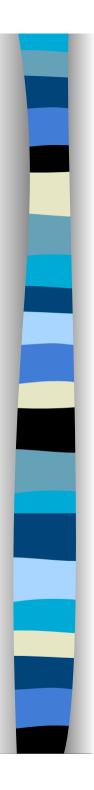
Formal Methods in software development



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Temporal logic

Let us want to express the following properties

 $\forall x ((file(x) \land requested(x)) \Rightarrow \exists y (y \ge a \land print(x,y)) \\ \forall y (y \ge a \Rightarrow works(x))$

The constant *a* as well as the variable *y*, of type "time"

If a file is requested to be printed, *eventually* it will be printed

After an amount *a* of time, *x* will begin to work 28/03/18



Temporal logic

One could use typed variables and first order logic making a distinction between temporal and dominion references

Or one can use modal operators

 $\forall x ((file(x) \land requested(x)) \Rightarrow F print(x))$

Gworks(x))

F means *eventuallyG* means *always*



Some hypotheses on temporal structure

Discrete/ Continuous

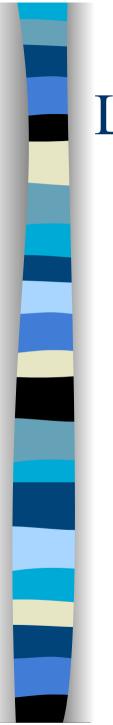
Linear / Branching

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Linear time temporal logic: LTL (syntax)

- $\varphi ::= T \mid \perp \mid p \mid (\neg \varphi) \mid (\varphi \land \varphi) \mid (\varphi \lor \varphi) \mid (\varphi \rightarrow \varphi) \mid (X\varphi) \mid (F\varphi) \mid (G\varphi) \mid (X\varphi) \mid (\varphi \cup \varphi) \mid (\varphi \cup \varphi) \mid (\varphi \cup \varphi)$
- F "eventually"
- G "always"
- X "next step"
- U "until"
- W "until possibly"



LTL: syntax

Warning: Operators not connectives

They bind more tightly than connectives



Exercises

Draw parse trees for the LTL formulas: (a) $Fp \wedge Gq \rightarrow p W r$ (b) $F(p \rightarrow Gr) \vee \neg q U p$ (c) p W (q W r)(d) $GFp \rightarrow F(q \vee s)$

LTL: satisfiability

Suppose $\mathcal{M} = (S, \rightarrow, L)$ is a model, $s \in S$, and ϕ an LTL formula. We write $\mathcal{M}, s \vDash \phi$ if, for every execution path π of \mathcal{M} starting at s, we have $\pi \vDash \phi$.

We write $\mathcal{M} \models \phi$ if, for every execution path π of \mathcal{M} we have $\pi \models \phi$.



LTL: semantics

We are dealing with a path intended as an infinite series of states

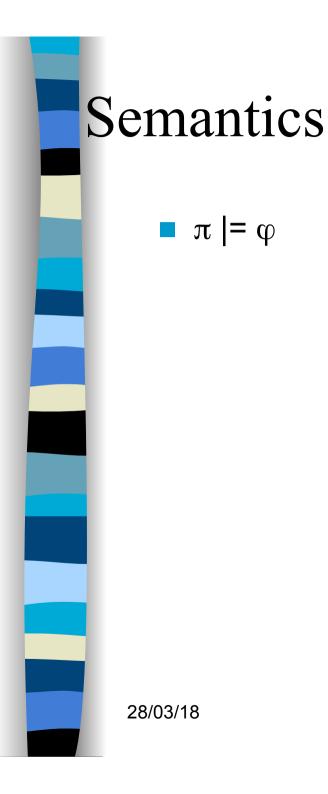
 \mathcal{M} , *s* |= φ if the path starting from *s* satisfys φ

States or paths? States are starting points of paths

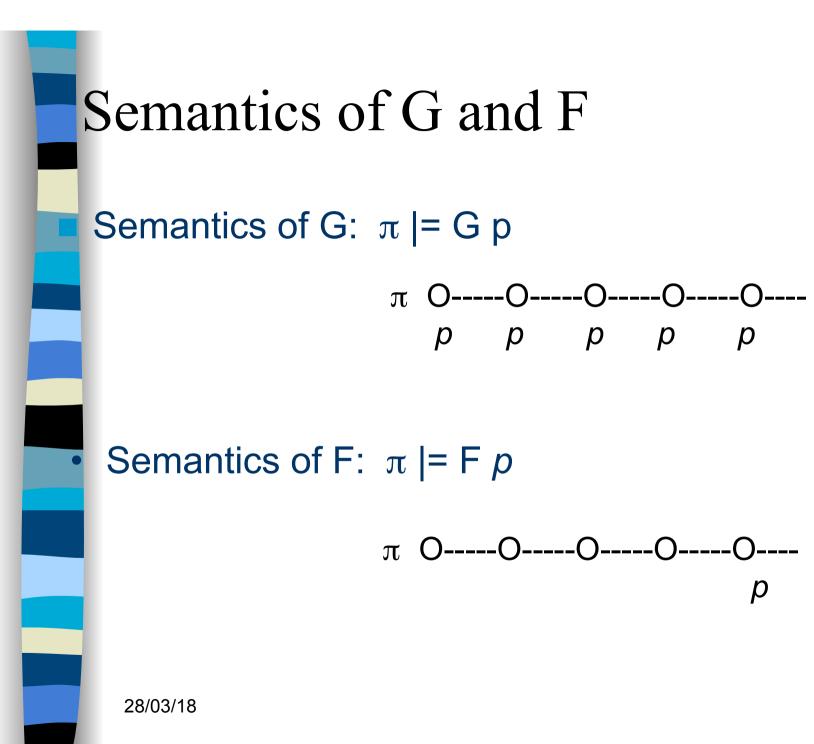
suffixes of paths are still paths

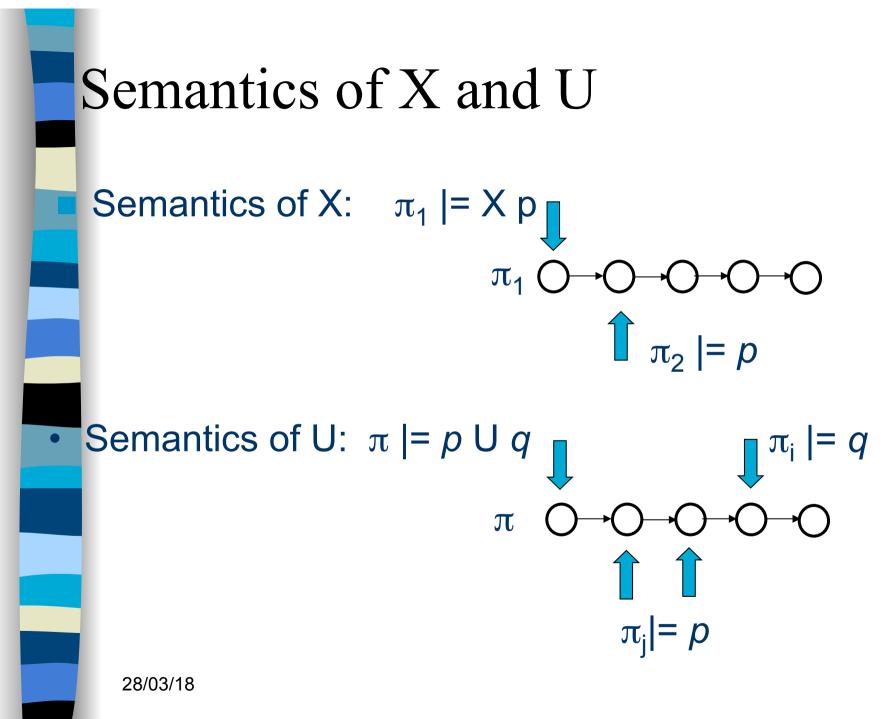
LTL: semantics (satisfaction)

- 1. $\pi \models \top$
- 2. $\pi \not\models \bot$
- 3. $\pi \vDash p$ iff $p \in L(s_1)$
- 4. $\pi \vDash \neg \phi$ iff $\pi \nvDash \phi$
- 5. $\pi \vDash \phi_1 \land \phi_2$ iff $\pi \vDash \phi_1$ and $\pi \vDash \phi_2$
- 6. $\pi \vDash \phi_1 \lor \phi_2$ iff $\pi \vDash \phi_1$ or $\pi \vDash \phi_2$
- 7. $\pi \vDash \phi_1 \rightarrow \phi_2$ iff $\pi \vDash \phi_2$ whenever $\pi \vDash \phi_1$
- 8. $\pi \models \mathbf{X} \phi$ iff $\pi^2 \models \phi$
- 9. $\pi \models \mathbf{G} \phi$ iff, for all $i \ge 1, \pi^i \models \phi$
- 10. $\pi \models \mathbf{F} \phi$ iff there is some $i \ge 1$ such that $\pi^i \models \phi$
- 11. $\pi \models \phi \cup \psi$ iff there is some $i \ge 1$ such that $\pi^i \models \psi$ and for all $j = 1, \ldots, i 1$ we have $\pi^j \models \phi$
- 12. $\pi \vDash \phi \otimes \psi$ iff either there is some $i \ge 1$ such that $\pi^i \vDash \psi$ and for all $j = 1, \ldots, i-1$ we have $\pi^j \vDash \phi$; or for all $k \ge 1$ we have $\pi^k \vDash \phi$



π Ο-----Ο----Ο----Ο φ,φ' φ ...





Semantics

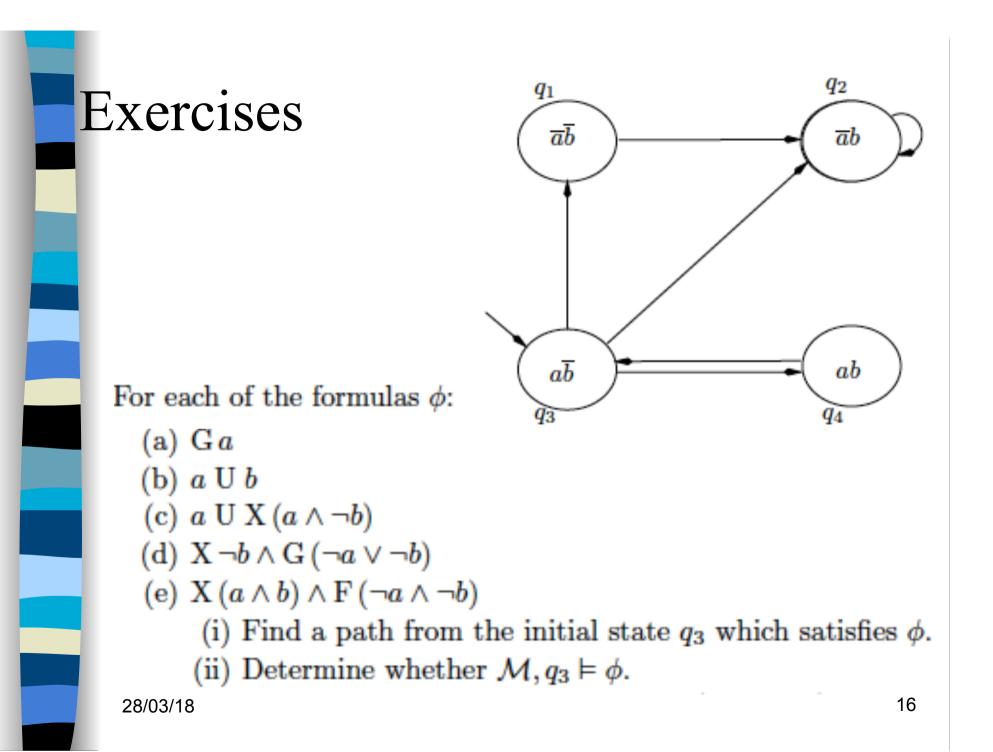
p V ¬*q* true: is true in the first state of the trace *X*¬*q* true, because *q* is false in the second state *XXq* false, because *q* is false in the *third* state *Gp* true, because *p* is true in all states *Gq* false, because *q* is not true in all states

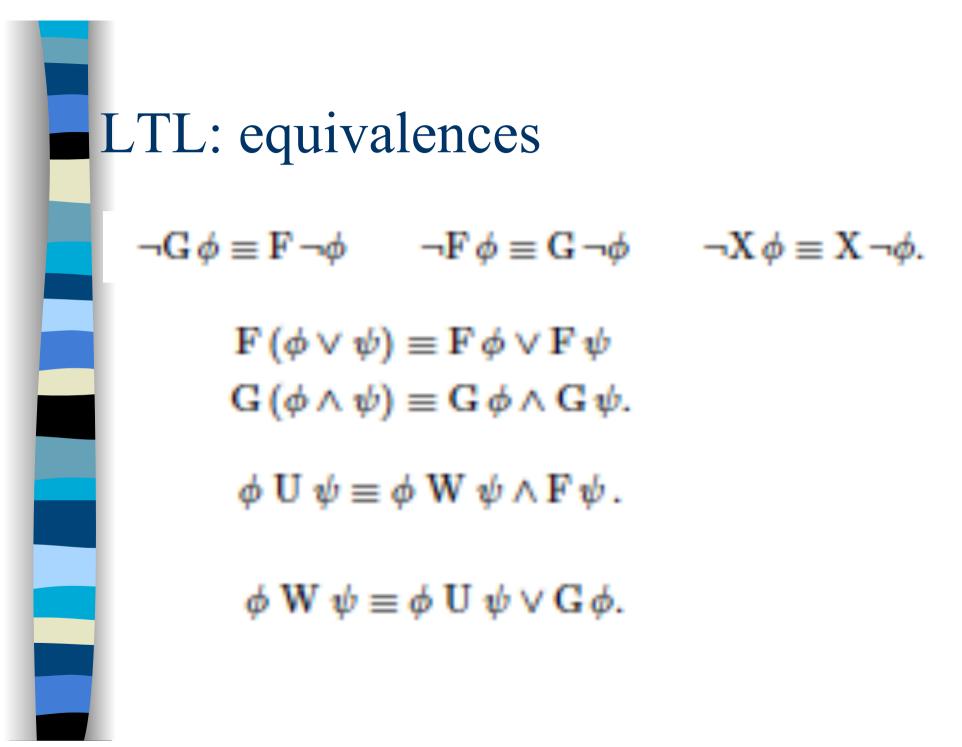
(it is true only in some states)

Semantics

pq p¬q pq pq ...

- GFq true: for all states of the sequence, there is some future point where q is true
- *pU¬q* true: *p* is true until ¬*q* becomes true;
 (in the first state *p* is true, then ¬*q* becomes true)
- *qUXXq* true: in the first state *q* is true, in the second state *XXq* is true (because *q* is true two states later)
- G(pUXXq) not straightforward to check: all states have to be checked for qUXXq in turn, check XXq in all states





LTL: what does hold (exercises)

$$G (\varphi \rightarrow \psi) \rightarrow (G \varphi \rightarrow G \psi)$$

$$G \varphi \rightarrow \varphi$$

$$\varphi \rightarrow F \varphi$$

$$G \varphi \rightarrow X \varphi$$

$$X \varphi \rightarrow F \varphi$$

$$G \varphi \rightarrow F \varphi$$

$$G \varphi \rightarrow F \varphi$$

$$X(\varphi \land \psi) \cong X \varphi \land X \psi$$



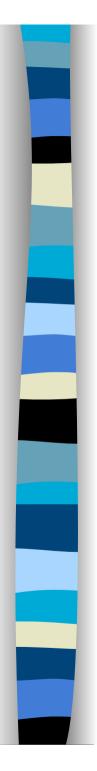
LTL: reductions

(transitivity on paths)

 $G \, \phi \twoheadrightarrow G G \phi$

while

 $GG \phi \rightarrow G\phi$ is always valid



LTL

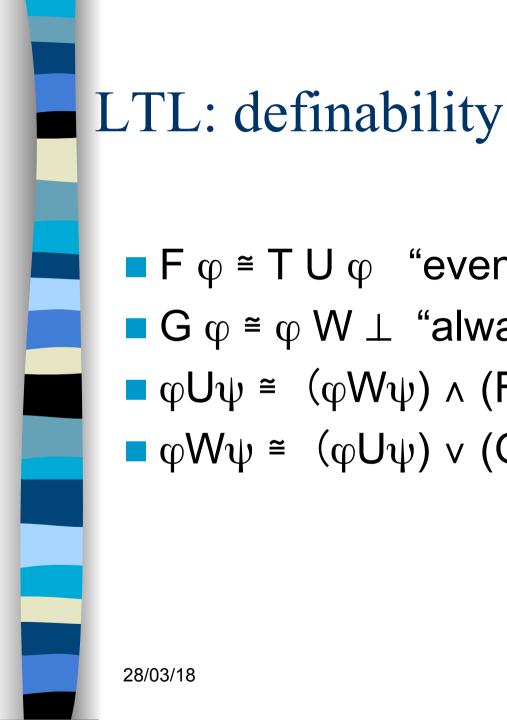
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An internal induction rule w.r.t. time

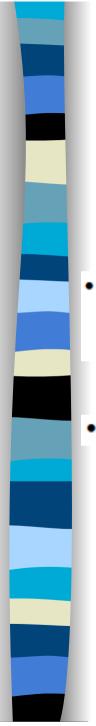
 $\phi \rightarrow X \phi \quad G(\phi \rightarrow X \phi)$

 $(\phi \rightarrow G\phi)$

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■ F $\phi \cong$ T U ϕ "eventually" ■ $G \phi \cong \phi W \perp$ "always" • $\varphi W \psi \cong (\varphi U \psi) \vee (G \varphi)$ "until possibly"



LTL

"next" operator

- X is completely orthogonal to the other connectives. That is to say, its presence doesn't help in defining any of the other ones in terms of each other. Moreover, X cannot be derived from any combination of the others.
- Each of the sets {U, X}, {R, X}, {W, X} is adequate.

Exercises

- 2. Consider the sentence $\phi \stackrel{\text{def}}{=} \forall x \exists y \exists z (P(x, y) \land P(z, y) \land (P(x, z) \rightarrow P(z, x))).$ Which of the following models satisfies ϕ ?
 - (a) The model \mathcal{M} consists of the set of natural numbers with $P^{\mathcal{M}} \stackrel{\text{def}}{=} \{(m, n) \mid m < n\}$.
 - (b) The model \mathcal{M}' consists of the set of natural numbers with $P^{\mathcal{M}'} \stackrel{\text{def}}{=} \{(m, 2 * m) \mid m \text{ natural number}\}.$
 - (c) The model \mathcal{M}'' consists of the set of natural numbers with $P^{\mathcal{M}''} \stackrel{\text{def}}{=} \{(m, n) \mid m < n + 1\}.$
- 3. Let P be a predicate with two arguments. Find a model which satisfies the sentence $\forall x \neg P(x, x)$; also find one which doesn't.