ADVANCED ARCHITECTURES INTENSIVE COMPUTATION

PARALLEL ARCHITECTURES: INTRODUCTION AND CLASSIFICATION

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What we will see in this and the next lessons

- Motivation to parallel architectures
- Classification of parallel architectures: Flynn's Taxonomy and other classifications
- SIMD class. Vector processors. Manycore architectures: GPU (and CUDA)
- MIMD class
- Interconnection topologies and interconnection networks
- Performance metrics and measurement

Textbooks

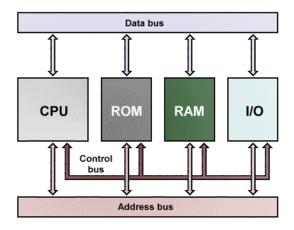
- Advanced Computer Architecture and Parallel Processing
 - H. El-Rewini, M. Abd-El-Barr, John Wiley and Sons, 2005
- Parallel computing for real-time signal processing and control (Ch. 2 Parallel Architectures)
 - M. O. Tokhi, M. A. Hossain, M. H. Shaheed, Springer, 2003
- Multicore and GPU Programming An Integrated Approach
 - G. Barlas Morgan Kaufmann, 2014
- Parallel Computer Architecture: A Hardware/Software Approach
 - D.E. Culler, J. P. Singh, A. Gupta Morgan Kaufmann, 1998

INTRODUCTION

Parallel Computer Architecture: A Hardware/Software Approach

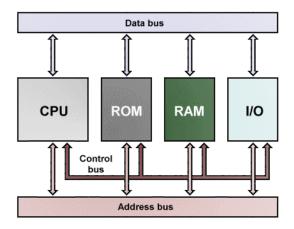
D.E. Culler, J. P. Singh, A. Gupta - Morgan Kaufmann, 1998

- The leading character of the growth in performance and capability of computer systems is parallelism
- Starting from the knowledge of the conventional computer architecture, we are interested in
 - Acquiring an understanding and appreciation of a computer system
 - Learning to harness parallelism to sustain performance improvements



In fact, the design of *parallel algorithms* and the study *of* strategies for problem decomposition are sustained by:

- A deep knowledge of the computer architecture
- A careful use of parallelism
- The performance analysis



- Parallel computer architecture forms an important thread in the evolution of computer architecture
- It has its roots in the beginnings of computing, and exploits advancement over what the base technology can provide
- Parallel computer designs have demonstrated a rich diversity
 of structure, usually motivated by specific higher level parallel
 programming models
- The speed with which computers can process information has been increasing exponentially over the time

Role of a computer architect:

To design and engineer the various levels of a computer system to maximize performance and programmability within limits of technology and cost

Parallelism:

- Provides an interesting perspective from which to understand computer architecture
- Provides alternative to faster clock for performance
- Applies at all levels of system design
- Is increasingly central in information processing

- ▶ A parallel computer is a collection of processing elements that cooperate to solve large problems fast
- ▶ This simple definition raises *many questions*

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Resource Allocation

- how large is the collection?
- how powerful are the elements?
- how big is memory?

- ▶ A parallel computer is a collection of processing elements that cooperate to solve large problems fast
- ▶ This simple definition raises *many questions*
- Data access, Communication and Synchronization
 - how do the elements cooperate and communicate?
 - how are data transmitted between processors?
 - what are the abstractions and primitives for cooperation?

- ▶ A *parallel computer* is a collection of processing elements that cooperate to solve large problems fast
- ▶ This simple definition raises *many questions*
- Performance and Scalability
 - how does it all translate into performance?
 - how does it scale?

- To understand parallel architectures, it is important to examine:
 - the principles of computer design at the processor level
 - the design issues present for each of the system components
 - memory systems
 - processors
 - networks
 - the relationships between these components
 - the division of responsibilities between hardware and software

 Parallel machines have been built at various scales since the earliest days of computing, but the approach is more viable today than ever before

- In fact
 - Whatever the performance of a single processor at a given time
 higher performance can be achieved by utilizing many processors
 - But now the basic processor building block is better suited to the job
- How much additional performance is gained and at what additional cost depends on a number of factors

CLASSIFICATION

Advanced Computer Architecture and Parallel Processing

H. El-Rewini, M. Abd-El-Barr, John Wiley and Sons, 2005

Parallel Architectures

- Parallel processors are computer systems consisting of
 - multiple processing units
 - connected via some interconnection network
 - plus the software needed to make the processing units work together
- There are two major factors used to categorize such systems:
 - the processing units themselves
 - the interconnection network that ties them together

Parallel Architectures

- A vast number parallel architecture types have been devised
- Various types of parallel architecture have overlapping characteristics to different extents
- It is not easy to develop a simple classification system for parallel architectures

Parallel Architectures

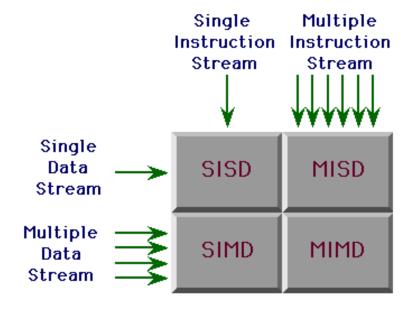
- Parallel architecture can be distinguished under the following broad categories:
 - Flynn's classification
 - Classification based on memory arrangement
 - Classification based on interconnections among PEs and memory modules
 - Classification based on characteristic nature of PEs

Flynn's classification

- Flynn's classification is based on the notion of a stream of information
- There are two types of information flow into a processor:
 - instruction stream defined as the sequence of instructions performed by the processing unit
 - data stream defined as the data traffic exchanged between the memory and the processing unit
- Either of the instruction or data streams can be single or multiple

Flynn's classification

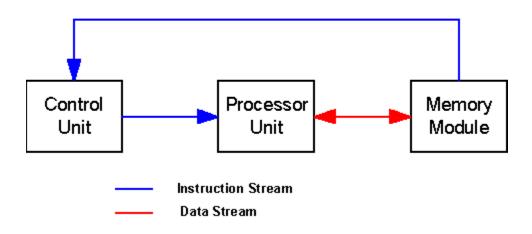
- Four distinct categories:
 - Single-Instruction Single-Data streams (SISD)
 - Single-Instruction Multiple-Data streams (SIMD)
 - Multiple-Instruction Single-Data streams (MISD)
 - Multiple-Instruction Multiple-Data streams (MIMD)



Single Instruction, Single Data Stream - SISD

- Single sequential processor executes a
 - Single instruction stream to operate on
 - Data stored in single memory

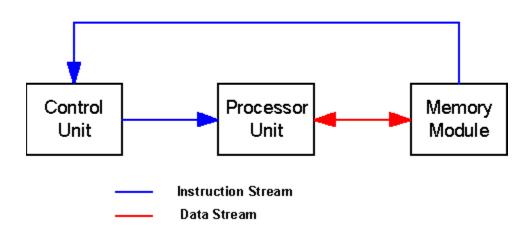
SISD Computer



Single Instruction, Single Data Stream - SISD

- During program execution the PE
 - fetches instructions and data from the main memory
 - processes the data according to the instructions
 - sends the results to the main memory after processing has been completed

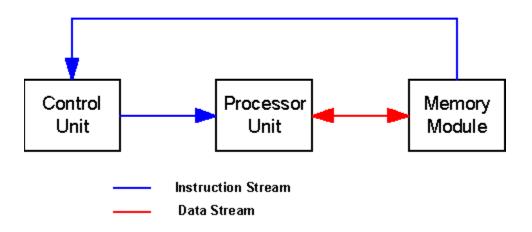
SISD Computer



Single Instruction, Single Data Stream - SISD

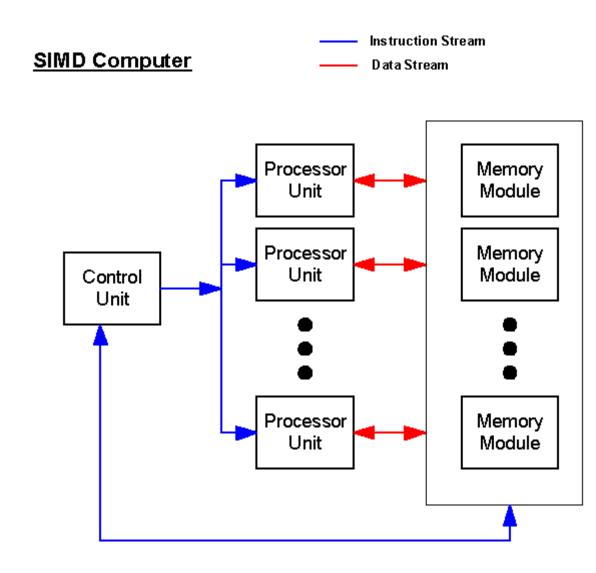
- The conventional single-processor Von Neumann computers falls under this category
- Today's conventional uniprocessors actually have several operations in flight at any one time
- In fact, the majority of contemporary CPUs is multicore and not only a single core CPU can be considered a SISD machine

SISD Computer



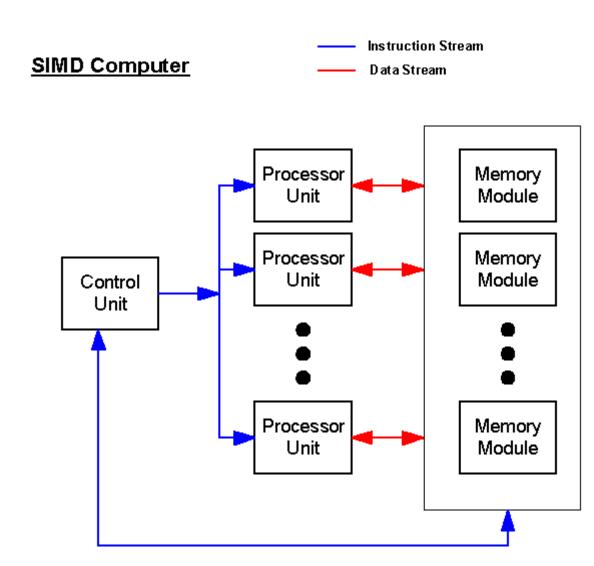
Single Instruction, Multiple Data Stream - SIMD

- A single instruction stream provides
 parallelism by
 operating on multiple data streams
 concurrently
- A single machine
 instruction controls
 the simultaneous
 execution of a
 number of processing
 elements on a
 lockstep basis



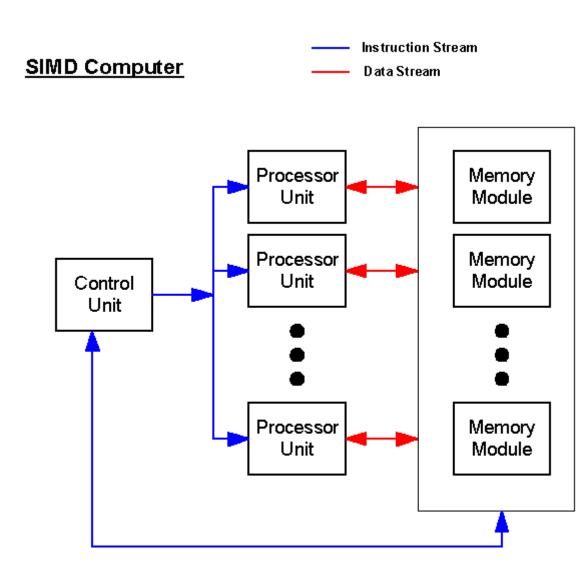
Single Instruction, Multiple Data Stream - SIMD

- Each processing element has an associated data memory
- Each instruction is executed on a different set of data by the different processors/cores



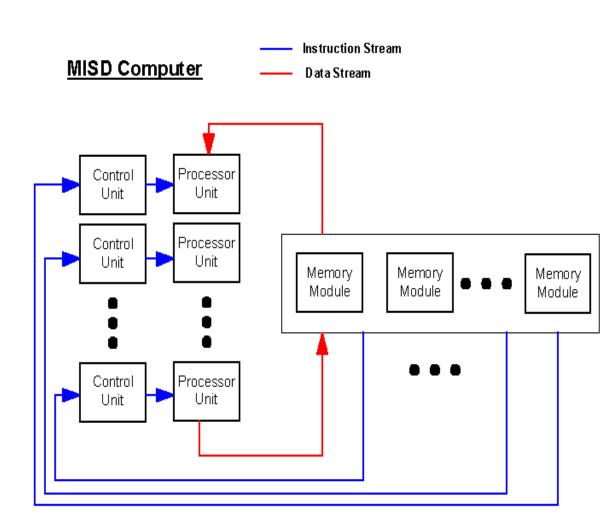
Single Instruction, Multiple Data Stream - SIMD

- Vector processors
 were the first SIMD
 machines
- GPUs follow this design at the level of Streaming Multiprocessor (SM)
- Applications:
 - Image processing
 - Matrix manipulations
 - Sorting



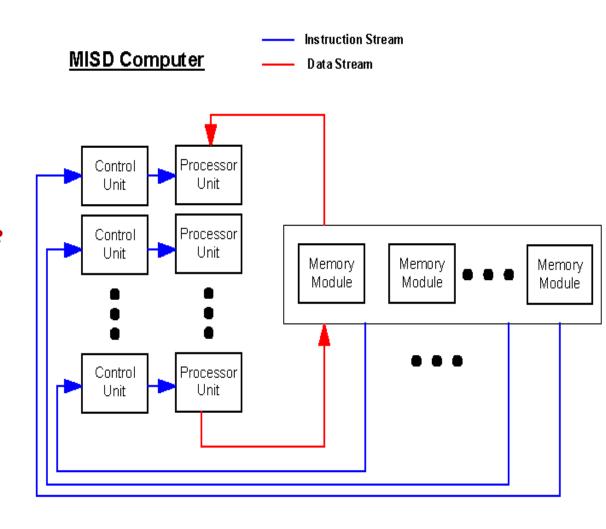
Multiple Instruction, Single Data Stream - MISD

- This is a controversial category
- A sequence of data is transmitted to a set of processors, each of which executes a different instruction sequence
- This structure is not commercially implemented



Multiple Instruction, Single Data Stream - MISD

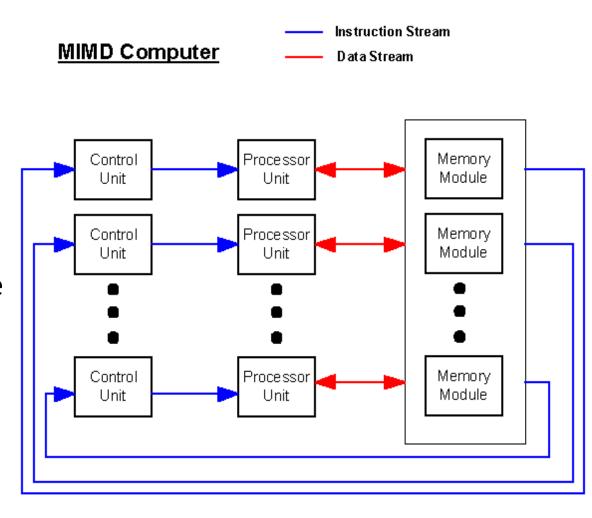
- MISD computers can be useful in applications of a specialized nature:
 - robot vision
 - when fault tolerance
 is required (military
 or aerospace
 application) data can
 be processed by
 multiple machines
 and decisions can be
 made on a majority
 principle



Multiple Instruction, Multiple Data Stream- MIMD

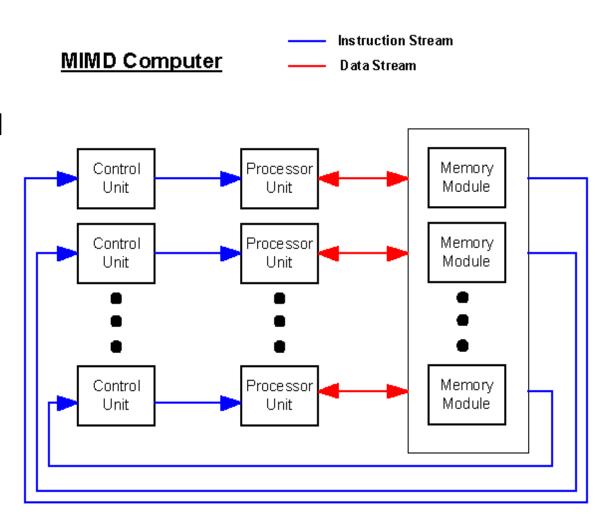
A set of processors
 simultaneously
 execute different
 instruction sequences
 on different data sets

 This architecture is the most common and widely used form of parallel architectures



Multiple Instruction, Multiple Data Stream- MIMD

- In the MIMD
 organization, the
 processors are general
 purpose
- Each processor can process all instructions necessary
- Further classified by method of processor communication



Flynn's classification

Advantages of Flynn

- Universally accepted
- Compact Notation
- Easy to classify a system

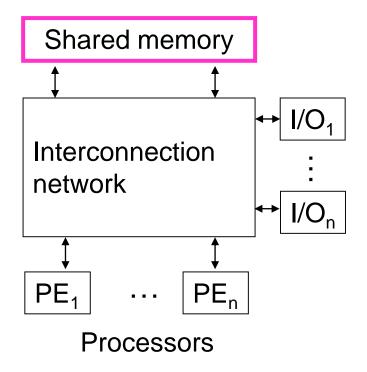
Disadvantages of Flynn

- Very coarse-grain differentiation among machine systems
- Comparison of different systems is limited
- Interconnections, I/O and memory not considered in the scheme

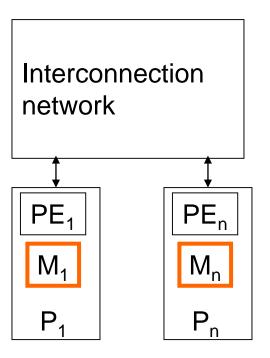
Classification based on memory arrangement

- Parallel architectures can be classified into two major categories in terms of memory arrangement:
 - Shared memory
 - Distributed memory or message passing
- This classification constitutes a subdivision of MIMD parallel architecture and are also known as:
 - Shared memory architecture → tightly coupled architecture
 - Distributed memory architecture → loosely coupled architecture
- A third choice is somewhere in between: groups of processors share a memory block while the different groups, also referred to as nodes, have distinct memory blocks

Classification based on memory arrangement



Shared memory *multiprocessors*



Distributed memory *multicomputers*

- A shared-memory multiprocessor is an architecture consisting of a (modest) number of processors, all of which have direct (hardware) access to all the main memory in the system
- The memory unit can comprise one or more memory modules
- All the processors:
 - have equal access to the memory modules,
 - can access data that any of the other processors has created
- The memory modules
 - store data
 - are seen as a single address space by all the processors
 - allow communication among the processors via

- The key to this form of multiprocessor architecture is the interconnection network that directly connects all the processors to the memories
- Communication is established through memory access instructions
- There is no direct processor-to-processor communication involved in the programming process
- Processors communicate by reading and writing data in locations into the shared memory
- The executable programming codes are stored in the memory for each processor to execute
- The data related to each program is also stored in this memory

- Each processor may have registers, buffers, caches, and local memory banks as additional memory resources
- A number of basic issues in the design of shared memory systems have to be taken into consideration: access control, synchronization, protection, and security
- Access to the memory modules can easily be controlled through appropriate programming mechanisms
- However, this architecture suffers from a bottleneck problem when a number of processors try to access the global memory at the same time
- This limits the scalability of the system but nonblocking networks as crossbars can be used to improve scalability

- Depending on the interconnection network, a shared memory system leads to systems that can be classified as:
 - uniform memory access (UMA) architecture
 - non-uniform memory access (NUMA) architecture
- In the UMA system
 - a shared memory is accessible by all processors through an interconnection network in the same way a single processor accesses its memory
 - the memory access time to the different parts of the memory are almost the same
- UMA architectures are also called symmetric multiprocessors

- An UMA architecture comprises two or more processors with identical characteristics
- The processors:
 - share the same main memory and I/O facilities
 - are interconnected by networks as some form of bus-based, crossbars, or multiport memories
- Processors perform the same functions under control of an operating system, which provides interaction between processors and their programs at the job, task, file and data element levels

- In the case of NUMA architectures, memory is physically distributed but logically shared
- Each processor has part of the shared memory attached, but the memory has a single address space, therefore, any processor could access any memory location directly
- The memory access time of processors differs depending on which region of the main memory is accessed
- A subclass of NUMA system is cache coherent NUMA (cc-NUMA) where cache coherence is maintained among the caches of various processors
- The main advantage of a cc-NUMA system is that it can deliver effective performance at higher levels of parallelism

- Anyway, cache coherence mechanisms are required in all cache-based multiprocessor systems, whether they are of the UMA or the ccNUMA kind
- This is because copies of the same cache line could potentially reside in several CPU caches
- Cache coherence ensures that any change in the data of one cache is reflected by some change to all other caches that may have a copy of the same global data location
- Cache coherence protocols ensure a consistent view of memory under all circumstances
- The interconnection network that provides cache coherence may employ any one of several techniques

An example is the **MESI protocol**, whose name is from the four possible states a cache line can assume:

- M modified: The cache line has been modified in this cache, and it resides in no other cache than this one. Only upon eviction will memory reflect the current state.
- **E exclusive**: The cache line has been read from memory but not (yet) modified. However, it resides in no other cache.
- S shared: The cache line has been read from memory but not (yet) modified. There may be other copies in other caches of the machine.
- I invalid: The cache line does not reflect any sensible data. Under normal circumstances this happens if the cache line was in the shared state and another processor has requested exclusive ownership.

Message Passing Multicomputer

- In a distributed memory architecture each unit is a complete computer building block including the processor, memory and I/O system
- Units are referred to as nodes, and there is no sharing of memory between them
- Nodes are typically able to store messages in buffers (temporary memory locations where messages wait until they can be sent or received), and perform send/receive operations at the same time as processing
- Hence, communication among the processors is established in the form of I/O operations through message signals and interconnection networks

Message Passing Multicomputer

Example

- If a processor needs data from another processor
- It sends a signal to that processor through an interconnection network demanding the required data
- The remote processor then responds accordingly
- Notice that, the further the physical distance to the remote processor, the longer it will take to access the remote data
- The processing units of a message passing system may be connected in a variety of ways ranging from architecturespecific interconnection structures to geographically dispersed networks
- The message passing approach is, in principle, scalable to large proportions

Message Passing Multicomputer

- The speed performance of distributed memory architecture largely depends upon how the processors are connected to each other
- It is impractical to connect each processor to the remaining processors through independent cables, it can work for a very low number of processors
- Message passing multiprocessors employ a variety of static networks in local communication
 - A common solution is to use specialized bus networks to connect all the processors in the system in order that each processor can communicate with any other processor attached to the system
 - hypercube networks have received special attention for many years
 - two-dimensional and three-dimensional mesh networks have been used as well

Classification based on characteristic of PEs

- Parallel architectures are also classified in terms of the nature of the PEs comprising them
- An architecture may consist of either only one type of PE or various types of Pes
- The different types of processors that are commonly used to form parallel architectures are:
 - CISC Processors
 - RISC Processors
 - Vector Processors and DSP (Digital Signal Processor)
 - Homogeneous and Heterogeneous Parallel Architectures

Classification based on characteristic of PEs

- Homogeneous computing systems employ a single type of processing component to perform all computation
- The majority of supercomputers are of this type
- Systems comprising two or more types of computer cores or nodes are distinguished from homogeneous computing systems that have only one type, and are designated as heterogeneous systems
- Accelerators, for example GPUs, can be attached to a system node via the I/O bus and can be accessed by any of the conventional processor cores of the system within the same node