## Parallelism and Performance

**Intensive Computation** 

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## References

Computer Architecture - A Quantitative Approach Hennessy Patterson *Chapter 1 - Fundamentals of Quantitative Design and Analysis* 

Section 1.8 - Measuring, Reporting, and Summarizing Performance

Section 1.9 - Quantitative Principles of Computer Design

- When we say one computer is faster than another we can mean different things:
  - The computer user is interested in reducing response time the time between the start and the completion of an event - also referred to as execution time
  - The operator of a warehouse-scale computer may be interested in increasing *throughput* - the total amount of work done in a given time

- In comparing design alternatives, we often want to relate the performance of two different computers: X and Y
- When we say X is faster than Y we mean that the response time or execution time is lower on X than on Y for the given task
- In particular, X is n times faster than Y will mean:

 $\frac{\text{Execution time } Y}{\text{Execution time } X} = n$ 

Execution time is the reciprocal of performance

• Since *execution time is the reciprocal of performance*, the following relationship holds:

$$n = \frac{\text{Execution time } Y}{\text{Execution time } X} = \frac{\text{Performance } X}{\text{Performance } Y}$$

The phrase the throughput of X is 1.3 times higher than Y signifies that the number of tasks completed per unit time on computer X is 1.3 times the number completed on Y

- Unfortunately, time is not always the metric quoted in comparing the performance of computers
- But (for Hennessy and Patterson) the only consistent and reliable measure of performance is the execution time of real programs
- All proposed alternatives to time as the metric or to real programs as the items measured have eventually led to misleading claims or even mistakes in computer design

- Even execution time can be defined in different ways depending on what we count
- The most straightforward definition of time is called *wall-clock time*, *response time*, or *elapsed time*  which is the *latency to complete a task*, including *disk*  accesses, memory accesses, input/output activities, operating system overhead...

- With multiprogramming, the processor works on another program while waiting for I/O and may not necessarily minimize the elapsed time of one program
- Hence, we need a term to consider this activity
- CPU time recognizes this distinction and means the time the processor is computing, *not* including the time waiting for I/O or running other programs
- Clearly, the response time seen by the user is the elapsed time of the program, *not* the CPU time

- Benchmarks can be used to measure performance
- The best choice of benchmarks is real applications
- Attempts at running programs much simpler than a real application have led to performance pitfalls
- Examples include:
  - Kernels, which are small, key pieces of real applications
  - Toy programs, which are 100-line programs (such as quicksort)
  - Synthetic benchmarks, which are fake programs invented to try to match the profile and behavior of real applications (as Dhrystone)
- All three are discredited today (compiler writer and architect can conspire to make the computer appear faster than on real applications)

# Taking advantage of parallelism

- In the design and analysis of computers, we need
  - Principles and guidelines
  - Observations about design
  - Equations to evaluate alternatives
- Taking advantage of parallelism is one of the most important methods for improving performance
  - Parallelism at the system level scalability
  - Parallelism at the level of an individual processor parallelism among instructions
  - Parallelism at the level of digital design memories and ALUs

# Taking advantage of parallelism

- Fundamental observations come from properties of programs
- The most important program property that we regularly exploit is the *principle of locality*
  - Temporal locality states that recently accessed items are likely to be accessed in the near future
  - Spatial locality says that items whose addresses are near one another tend to be referenced close together in time

# Taking advantage of parallelism

- An important and pervasive principle of computer design is to focus on the *common case*:
  - In making a design trade-off, *favor the frequent case* over the infrequent case
- This principle applies when determining how to spend resources, since the impact of the *improvement is higher* if the occurrence is *frequent*
- In applying this simple principle, we have to decide what the frequent case is and how much performance can be improved by making that case faster

- The performance gain obtained by improving some portion of a computer can be calculated using Amdahl's law
- Amdahl's law:
  - states that the *performance improvement is limited* by the *fraction of the time* the faster mode can be used
  - defines the speedup that can be gained by using a particular feature

#### speeedup

 $= \frac{Performance for the entire task using the enhancement when possible}{Performance for the entire task without using the enhancement}$ 

= Execution time for entire taskwithout using the enhancement Execution time for entire taskusing the enhancement when possible

- Amdahl's law gives us a quick way to find the speedup from some enhancement, which depends on two factors:
  - The *fraction of the computation time* in the original computer that can be converted to take advantage of the enhancement, that is

**Fraction**<sub>enhanced</sub> = time with enhancement / *total* time

#### Example:

- A program that takes 60 seconds in total
- 20 seconds of the execution time can use an enhancement
- The fraction is: 20/60
- This value is always less than or equal to 1

- Amdahl's law gives us a quick way to find the speedup from some enhancement, which depends on two factors:
  - 2) The improvement gained by the enhanced execution mode, that is, how much faster the task would run if the enhanced mode were used for the entire program:

**Speedup<sub>enhanced</sub>** = *original* mode time / *enhanced* mode time

#### Example:

- A portion of the program in the original mode is 5 seconds
- In the enhanced mode takes 2 seconds
- The improvement is 5/2
- This value is always greater than 1

 The execution time using the original computer with the enhanced mode will be the time spent using the unenhanced portion of the computer plus the time spent using the enhancement:

$$Execution time_{new} = Execution time_{old} \times \left( (1 - Fraction_{enhanced}) + \frac{Fraction_{enhanced}}{Speedup_{enhanced}} \right)$$

The overall speedup is the ratio of the execution times:

$$Speedup_{overall} = \frac{Executiontime_{old}}{Executiontime_{new}} = \frac{1}{(1 - Fraction_{enhanced}) + \frac{Fraction_{enhanced}}{Speedup_{enhanced}}}$$

- We want to enhance the processor used for Web serving
- The new processor is 10 times faster on computation in the Web serving application than the original processor
- Assume that the original processor is busy with computation 40% of the time and is waiting for I/O 60% of the time
- What is the overall speedup gained by incorporating the enhancement?

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$$Fraction_{enhanced} = 0.4 \qquad Speedup_{enhanced} = 10$$

$$Speedup_{overall} = \frac{1}{(1 - Fraction_{enhanced}) + \frac{Fraction_{enhanced}}{Speedup_{enhanced}}} = \frac{1}{(1 - 0.4) + \frac{0.4}{10}} = \frac{1}{0.64} = 1.6$$

- Amdahl's law can serve as a guide to:
  - how much an enhancement will improve performance
  - how to distribute resources to improve cost-performance
- The goal is to spend resources proportional to where time is spent
- Amdahl's law is useful
  - for comparing the overall system performance of two alternatives
  - to compare two processor design alternatives

- A common transformation in graphics processors is square root
- Implementations of floating-point square root (FPSQR) vary significantly in performance among processors for graphics
- Suppose
  - FPSQR is responsible for 20% of the execution time of a critical graphics benchmark and
  - FP instructions are responsible for half of the execution time for the application

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#### Example

- Two proposals:
  - To enhance the FPSQR hardware and speed up this operation by a factor of 10
  - To try to make all FP instructions in the graphics processor run faster by a factor of 1.6
- Compare these two design alternatives

We can compare these two alternatives by comparing the speedups

Speedup<sub>FPSQR</sub> = 
$$\frac{1}{(1-0.2) + \frac{0.2}{10}} = \frac{1}{0.82} = 1.22$$

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Speedup<sub>FPSQR</sub> = 
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Speedup<sub>FP</sub> =  $\frac{1}{(1-0.5)} + \frac{0.5}{1.6} = \frac{1}{0.8125} = 1.23$ 

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 Improving the performance of the FP operations overall is slightly better because of the higher frequency

- All computers are constructed using a clock running at a constant rate
- Discrete time events are called *ticks, clock ticks, clock periods, clocks, cycles, or clock cycles*
- Computer designers refer to the time of a clock period by its duration (e.g., 1 ns) or by its rate (e.g., 1 GHz)
- CPU time for a program can then be expressed two ways:
  - CPU time = CPU clock cycles for a program × Clock cycle time
     Or
    - CPU time = CPU clock cycles for a program / Clock rate

- We can also count the number of instructions executed the *instruction path length* or *instruction count (IC)*
- If we know the number of clock cycles and the instruction count, we can calculate the average number of clock cycles per instruction (CPI):

#### **CPI = CPU clock cycles for a program / IC**

- From this formula we obtain
  - CPU clock cycles for a program = CPI x IC

- This allows us to use CPI in the execution time formula and obtain the performance equation:
  - CPU time = IC × CPI × Clock cycle time
- In fact (using the units of measurement) we have:

$$IC \times CPI \times Clock cycle time = \frac{Instructions}{Program} \times \frac{Clock cycles}{Instructions} \times \frac{Seconds}{Clock cycles} = \frac{Seconds}{Program} = CPU time$$

 Observe that processor performance is equally dependent upon clock cycle (or rate), clock cycles per instruction, and instruction count

 It is useful to calculate the number of total processor clock cycles as

$$\mathsf{CPUclock\,cycles} = \sum_{i=1}^{n} \mathsf{IC}_{i} \times \mathsf{CPI}_{i}$$

- where
  - $IC_i$  is the number of times instruction *i* is executed in a program
  - $CPI_i$  is the average number of clocks per instruction for instr. *i*

This expression can be used to express CPU time as

$$CPU time = \left(\sum_{i=1}^{n} IC_{i} \times CPI_{i}\right) \times Clock cycle time$$

and the overall CPI as

$$CPI = \frac{\sum_{i=1}^{n} IC_i \times CPI_i}{Instruction count} = \sum_{i=1}^{n} \frac{IC_i}{Instruction count} \times CPI_i$$

- Suppose we have made the following measurements in the previous example :
  - Frequency of FP operations = 25%
  - Average CPI of FP operations = 4.0
  - Average CPI of other instructions = 1.33
  - Frequency of FPSQR = 2%
  - CPI of FPSQR = 20
- Assume that the two design alternatives are:
  - To decrease the CPI of FPSQR to 2 or
  - To decrease the average CPI of all FP operations to 2.5
- Compare these two design alternatives using the processor performance equation

- Observe that only the CPI changes
- The clock rate and instruction count remain identical
- We start by finding the original CPI with no enhancement:

$$CPI_{original} = \sum_{i=1}^{n} CPI_i \times \frac{IC_i}{Instruction count} = (4 \times 25\%) + (1.33 \times 75\%) = 2.0$$

 We can compute the CPI for the enhanced FPSR by subtracting the cycles saved from the original CPI:

$$\mathsf{CPI}_{\mathsf{new\,FPSR}} = \mathsf{CPI}_{\mathsf{original}} - 2\% \times (\mathsf{CPI}_{\mathsf{old\,FPSR}} - \mathsf{CPI}_{\mathsf{new\,FPSR\,only}}) =$$

$$=2-2\% \times (20-2)=1.64$$

 We can compute the CPI for the enhancement of all FP instructions (the same way or) by summing the FP and non-FP CPIs:

$$CPI_{newFP} = (2.5 \times 25\%) + (1.33 \times 75\%) = 1.625$$

 Since the CPI of the overall FP enhancement is slightly lower, its performance will be marginally better

#### The speedup for the FPSR enhancement is

Speedup<sub>FPSR</sub> = 
$$\frac{\text{CPU time}_{\text{original}}}{\text{CPU time}_{\text{FPSR}}} = \frac{\text{CPI}_{\text{original}}}{\text{CPI}_{\text{FPSR}}} = \frac{2.0}{1.64} = 1.22$$

The speedup for the overall FP enhancement is

$$Speedup_{new FP} = \frac{CPU time_{original}}{CPU time_{new FP}} = \frac{IC \times Clock cycle \times CPI_{original}}{IC \times Clock cycle \times CPI_{new FP}} = \frac{CPI_{original}}{CPI_{new FP}} = \frac{2.0}{1.625} = 1.23$$

#### Conclusions

- It is often easier to use the processor performance equation than Amdahl's law
- In fact,
  - It is often possible to measure the constituent parts of the processor performance equation
  - It may be *difficult* to measure things such as the *fraction of* execution time for which a set of instructions is responsible
  - In practice, this would probably be computed by summing the product of the instruction count and the CPI for each of the instructions in the set
- Hence, the starting point is often individual instruction count and CPI measurements → performance equation